



### Technical data

#### Optical data

|                                      |  |
|--------------------------------------|--|
| Measurement range                    | ROD4 plus, ROD4-50 plus, ROD4-56 plus: 0 ... 65m<br>ROD4-08 plus, ROD4-58 plus: 0 ... 25 m |
| Detection field radius <sup>1)</sup> | Near: 0 ... 30m<br>Far: 0 ... 50m  |
| Scanning angle                       | max. 190°  |
| Angular resolution                   | 0.36°  |
| Scan rate                            | ROD4-5x plus: 50 scans/s or 20ms/scan<br>ROD4 plus, ROD4-08 plus: 25scans/s or 40ms/scan   |
| Transmitter                          | Infrared laser diode   |
| Wavelength                           | 905nm  |
| Laser class                          | 1 in accordance with IEC 60825-1:2014 / EN 60825-1:2014+A11:2021                           |
| Impulse duration                     | 3ns  |
| Max. output power (peak)             | 15W  |

#### Object measurement

|   |  |
|---|--|
| Reflectivity                            | from min. 1.8% (matt black)<br>ROD4-x8 plus from 6% (dark grey)  |
| Object size                             | > 20mm at 4m distance<br>> 100mm at 15m distance   |
| Response time                           | ROD4-5x plus: at least 20ms (equivalent to 1scan)<br>ROD4 plus, ROD4-08 plus: at least 40ms (equivalent to 1scan)  |
| Switching inputs                        | 4x +24VDC<br>(FPS1 ... 4 to Y1 for detection field switchover)<br>additional restart input on Y1 and interface box |
| Switching outputs                       | 4x PNP transistor outputs, 24V/250mA<br>(Alarm, Warning, NearField1, NearField2)                                   |
| Measurement value resolution per sector | 5mm  |
| Repeatability <sup>2)</sup>             | ROD4 plus, ROD4-50 plus, ROD4-56 plus: ± 15mm<br>ROD4-08 plus, ROD4-58 plus: ± 20mm                                |

#### Object detection (ROD4 plus, ROD4-08 plus)

|                                 |  |
|---------------------------------|--|
| Reflectivity                    | from min. 1.8% (matt black)<br>ROD4-08 plus from 6% (dark grey)  |
| Object size                     | > 20mm at 4m distance<br>> 100mm at 15m distance   |
| Response time                   | at least 40ms (equivalent to 1 scan)   |
| Number of detection field pairs | 7 (switchable via switching inputs)  |
| Switching inputs                | 4x +24VDC<br>(FPS1 ... 4 to Y1 for detection field switchover)<br>additional restart input on Y1 and interface box |
| Switching outputs               | 4x PNP transistor outputs, 24V/250mA<br>(Alarm, Warning, NearField1, NearField2)                                   |

#### Electrical data

|                              |   |
|------------------------------|---|
| Voltage supply <sup>3)</sup> | +24VDC +20% / -30%  |
| Overcurrent protection       | Via 2.5A (4A with heating) semi time-lag fuse in the switch cabinet |
| Current consumption          | approx. 1A (use NT with 2.5A), approx. 4A with heating              |
| Power consumption            | < 75W at 24V including outputs                                      |
| Overvoltage protection       | overvoltage protection with protected limit stop                    |

#### Mechanical data

|                 |   |
|-----------------|---|
| Housing         | Diecast aluminum, plastic                   |
| Weight          | 2.3kg                                       |
| Connection type | 4 connectors (can be plugged in from above) |

#### Environmental data

|                                   |  |
|-----------------------------------|--|
| Ambient temp. (operation/storage) | -0°C ... +50°C/-20°C ... +50°C<br>-20°C ... +50°C/-20°C ... +50°C (with heating) |
| VDE protection class              | III, protective extra-low voltage  |
| Protection class                  | IP 65  |
| Standards applied                 | IEC 60947-5-2  |
| Approvals                         | UL 508, C22.2 No.14-13 3)  |

1) only applies to ROD4 plus, ROD4-08 plus

2) 10 ... 90% diffuse reflection, at 4m operating range

3) Protective Extra Low Voltage (PELV).

For UL applications: Use is permitted exclusively in Class 2 circuits according to NEC.

### Order guide

|  | Designation  | Part no. |
|--|--------------|----------|
| <b>for object detection/measurement, scanning rate 25scans/s</b> |              |          |
|  | ROD4 plus    | 50106481 |
| with heating/dust-insensitive                                    | ROD4-08 plus | 50106480 |
| <b>for object measurement, scanning rate 50scans/s,</b>          |              |          |
| With heating   | ROD4-50 plus | 50113226 |
| with heating/dust-insensitive                                    | ROD4-56 plus | 50129795 |
|  | ROD4-58 plus | 50113225 |

### Notes

#### Intended use:

The laser scanners are opto-electronic sensors for optical, contactless detection of objects.

**NOTES**

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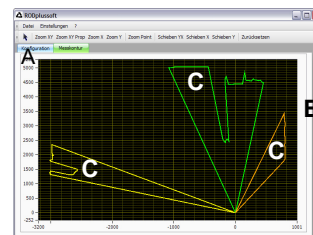
**Observe intended use!**

- ↪ This product is not a safety sensor and is not intended as personnel protection.
- ↪ The product may only be put into operation by competent persons.
- ↪ Only use the product in accordance with its intended use.

#### “RODplussoft” configuration software

The configuration software runs on Windows 2000/XP and offers the following options:

- Configuration of Ethernet and serial interface
- Configuration of up to 12 measurement segments
- Visualization of measured values



- A Configuration of data transmission in the “Configuration” tab
- B Definition of measurement segments in the “Toolbox”
- C Graphical representation of the measurement segments' measurement values in different colors
- Transmission of measured values in XY coordinates or polar coordinates.

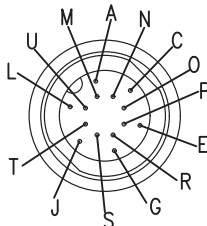
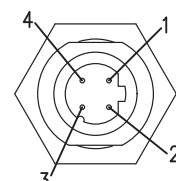
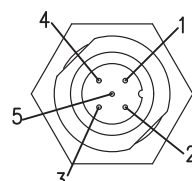
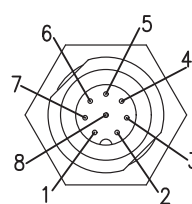
#### Configuration software

##### “RODsoft”

(only for ROD4(-08) plus

- Definition of detection fields
- Configuration of the scanner parameters
- Visualization of detection fields and measured values
- Presentation of status/diagnostic information
- Support for different languages

### Electrical connection – connector assignment

| Y1 logic  |                 |                    | Y2 Ethernet   |          |             | Y3 Service   |          |       | Y4 RS 232/422   |                  |       |
|---|-----------------|--------------------|---|----------|-------------|--|----------|-------|---|------------------|-------|
|  |                 |                    |  |          |             |  |          |       |  |                  |       |
| Pin   | Function        | Color              | Pin   | Function | Color       | Pin  | Function | Color | Pin   | Function         | Color |
| A   | +U <sub>B</sub> | rd (red)           | 1   | Tx+      | yw          | 1  | NC       | br    | 1   | TX+ / TxD        | wh    |
| C   | GND_IN          | bl (blue)          | 2   | Rx+      | wh          | 2  | TxD      | wh    | 2   | Tx-              | br    |
| E   | FPS1            | pk (pink)          | 3   | Tx-      | or (orange) | 3  | GND      | bl    | 3   | Rx-              | gn    |
| G   | FPS2            | gr (gray)          | 4   | Rx-      | bl          | 4  | RxD      | bk    | 4   | Rx+ / RxD        | yw    |
| J   | FPS3            | yw (yellow)        |   |          |             | 5  | NC       | gr    | 5   | GND/shield       | gr    |
| L   | FPS4            | gn (green)         |   |          |             |  |          |       | 6   | RS 422 detection | pk    |
| M   | Restart_IN      | br (brown)         |   |          |             |  |          |       | 7   | NC               | bl    |
| N   | Near field 1    | wh (white)         |   |          |             |  |          |       | 8   | NC               | RD    |
| O   | Near field 2    | vi (violet)        |   |          |             |  |          |       |   |                  |       |
| P   | Warning2        | bk (black)         |   |          |             |  |          |       |   |                  |       |
| R   | Warning1        | whgn (white-green) |   |          |             |  |          |       |   |                  |       |
| S   | NC              | rdbl (red-blue)    |   |          |             |  |          |       |   |                  |       |
| T   | NC              | brgn (brown-green) |   |          |             |  |          |       |   |                  |       |
| U   | NC              | grpk (grey-pink)   |   |          |             |  |          |       |   |                  |       |

### Installing the RODplussoft software

The **RODplussoft** configuration software is used to configure the interfaces and metrological functions of all ROD4... plus.

The **RODplussoft** configuration software can be found on the included CD. To install, follow the instructions in the relevant readme files, which can also be found on the included CD.

You can also download the latest version of **RODplussoft** at [www.leuze.com](http://www.leuze.com).

Unpack the ZIP file provided in a suitable folder on your hard disk.

☞ Start the installation by double-clicking on the **setup.exe** file.

☞ Follow the installation routine instructions.

#### NOTE



Before installing **RODplussoft**, you should ensure that the Microsoft® .NET Framework 2.0 SP1 or higher is installed on your computer.

### Installing RODsoft software (only for ROD4 plus and ROD4-08 plus)

You only need to install the **RODsoft** software if you want to define detection fields for ROD4 plus or ROD4-08 plus laser scanners.

#### NOTE



With **ROD4-5... plus** laser scanners, status and diagnostic information can be called up with **RODsoft**.

The **RODsoft** configuration software can be found on the included CD. To install, follow the instructions in the relevant readme files, which can also be found on the included CD.

You can also download the latest version of **RODsoft** at [www.leuze.com](http://www.leuze.com).

Unpack the ZIP file provided in a suitable folder on your hard disk.

☞ Start the installation by double-clicking on the **setup.exe** file.

☞ Follow the installation routine instructions.

## Establish connection to PC

The ROD4... plus is configured via a PC using the **RODplussoft** program before it is integrated into the process control.

In order to be able to establish TCP communication with the PC, the IP address of your PC and the IP address of the ROD4... plus must lie in the same address range. The ROD4... plus has no built-in DHCP client, so that you need to set the address manually. This is done the easiest way via the PC.

The ROD4...plus is set as follows at the factory:

IP address: 192.168.060.003  
Subnet mask: 255.255.255.0

### NOTE



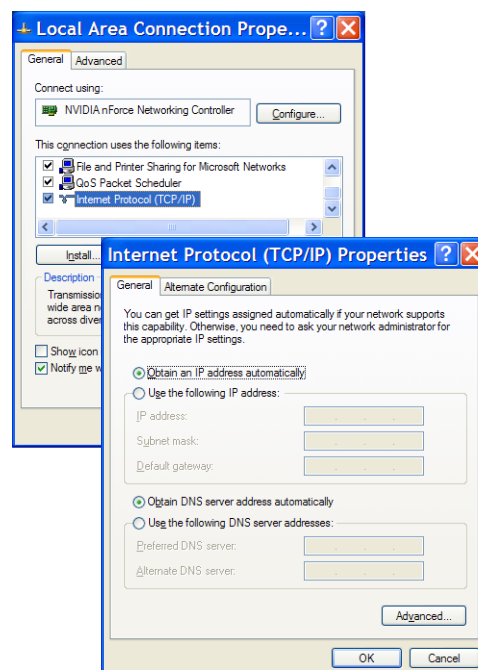
If you use a desktop firewall, please make certain that the PC can communicate with the ROD4... plus via the Ethernet interface by means of TCP on ports 9008. Furthermore, the firewall must allow ICMP echo messages to pass through for the connection test (ping).

If the PC is usually connected to a network using DHCP address allocation, the easiest way to access the ROD4... plus is by applying an alternative configuration in the TCP/IP settings of the PC and connecting the ROD4... plus to the PC.

According to the default setting 255.255.255.0 for the subnet mask, the IP address of the PC must therefore be in the range of 192.168.060.0 to 192.168.060.255 (e.g. 192.168.060.110, but not 192.168.060.003!) so that the ROD4... plus and PC can communicate with each other. If the ROD4... plus and PC have the same IP address, they cannot communicate with each other.


### Setting the IP address on the PC

- ☞ Log in to your PC as administrator.
- ☞ Go via **Start -> Control Panel** to the **Network Connections** menu (Windows XP) or the **Network and Sharing Center** (Windows 7).
- ☞ Select the **LAN connection** there and call up the corresponding properties page by right-clicking it.
- ☞ Select the **Internet protocol (TCP/IP)** (by scrolling down, if necessary) and click on **Properties**.
- ☞ In the **Internet protocol (TCP/IP) Properties** window select the **Alternate configuration** tab.
- ☞ Set the **IP address** of the PC in the ROD4... plus address range.  
**Attention:** Not the same as the ROD4... plus!
- ☞ Set the PC **subnet mask** to the same value as on the ROD4... plus.
- ☞ Close the configuration dialog by confirming all windows using **OK**.
- ☞ Connect the interface Y2 of the ROD4... plus directly to the LAN port of your PC.  
Use a **KB ET-...-SA-RJ45** cable for the connection.



### Laser safety notices – laser class 1

⚠
**ATTENTION**



**LASER RADIATION – CLASS 1 LASER PRODUCT**

The device satisfies the requirements of IEC 60825-1:2014 / EN 60825-1:2014+A11:2021 safety regulations for a product of **laser class 1** and complies with 21 CFR 1040.10 except for conformance with IEC 60825-1 Ed. 3., as described in Laser Notice No. 56, dated May 8, 2019.

- ↳ Observe the applicable statutory and local laser protection regulations.
- ↳ The device must not be tampered with and must not be changed in any way. There are no user-serviceable parts inside the device.

**CAUTION!** Opening the device may result in hazardous radiation exposure!  
Repairs must only be performed by Leuze electronic GmbH + Co. KG.

### Commissioning

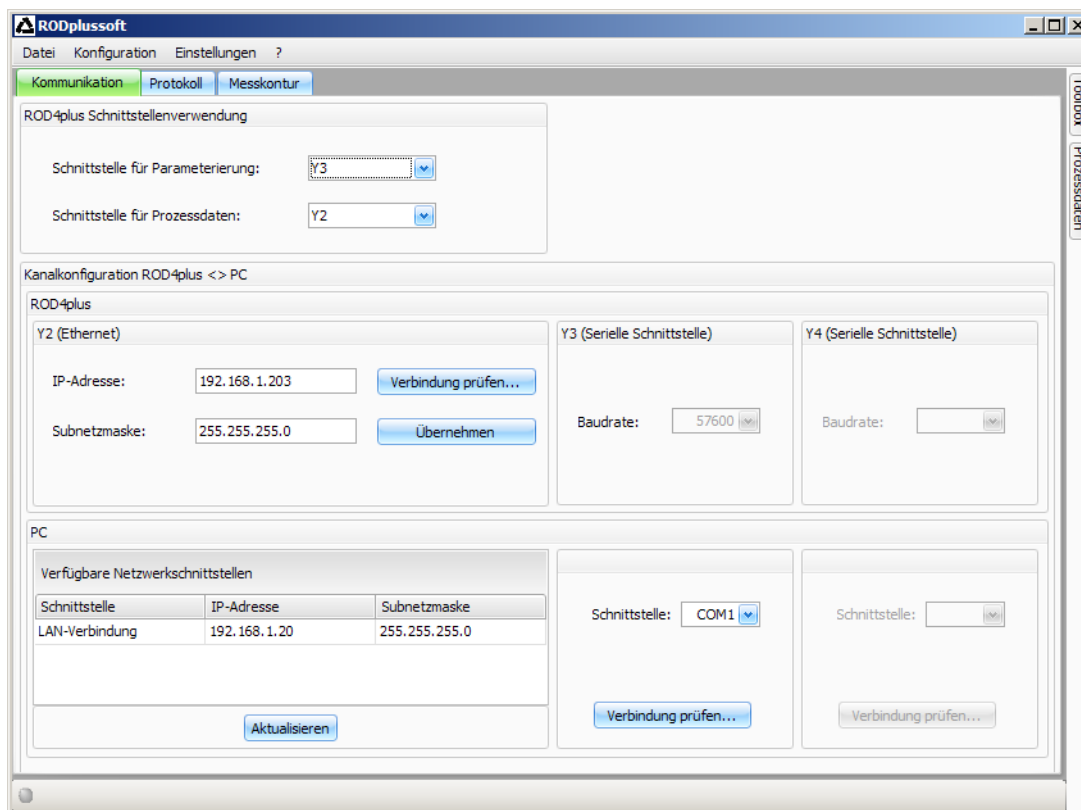
- ↳ Switch on the ROD4... plus supply voltage.
- ↳ Start the **RODplussoft** software.

The PC first attempts to establish a network connection via Ethernet using the automatic configuration. This takes a few seconds, after which the alternate configuration, which you just set, is activated. The PC can then communicate with the ROD4... plus via Ethernet.

Further information on using the **RODplussoft** software to configure the ROD4... plus can be found in the technical description and the software and protocol description.

The following steps are necessary for commissioning and integrating the laser scanner into the process control:

1. Configuring the ROD4... plus – see chapter 6 of the technical description.
2. If necessary, configure detection fields with the **RODsoft** configuration software (menu **Configuration -> Start RODsoft...**)  
(**only for ROD4 plus and ROD4-08 plus!**)  
See section “Configuring detection fields (for ROD4 plus and ROD4-08 plus only)” on page 6.
3. Program the process control.  
or
4. Connect switching inputs and outputs accordingly – see chapter 5 of the technical description.
5. Adjust the IP configuration of the ROD4... plus so that it can communicate with the process control. This is done in **RODplussoft** in the **Communication** tab. Here you can change the network address and associated netmask via which the ROD4... plus communicates with the process control.



6. You can save the changed settings in ROD4... plus with the menu item **Configuration -> Transfer to ROD4plus**.
7. Connect the ROD4... plus to the process control via the Y2 Ethernet interface.

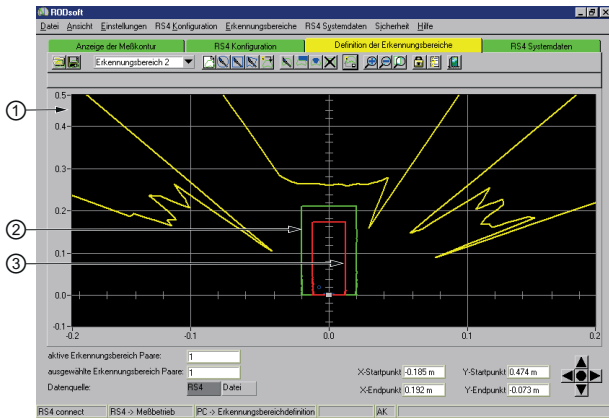
### Configuring detection fields (for ROD4 plus and ROD4-08 plus only)

#### Commissioning procedure:

- ☞ Connect the PC to the ROD4(-08) plus via the **KB-ROD4plus...** cable at the **Y3 – Service** connection.
- ☞ Call up the **RODsoft** configuration software from **RODplussoft** via the **Start RODsoft...** menu item.
- ☞ Enter the password "**ROD4LE**" in the "Authorized customer" level

The detection field can be displayed under "Display of the measurement contour". The response times, detection field switchovers etc. are defined under "ROD4 configuration". To configure detection fields, select the "Definition of detection areas" field. Error codes can be called up in "ROD4 system data".

A detailed description can be found in the **RODsoft** configuration software user manual.



- 1 Current measured values (yellow line)
- 2 Far detection field (green line)
- 3 Near detection field (red line)