

Original operating instructions

AMS 304*i*

Optical laser measurement system – PROFIBUS / SSI



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Leuze electronic GmbH + Co. KG

In der Braike 1

D-73277 Owen / Germany

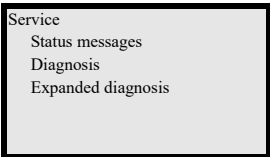
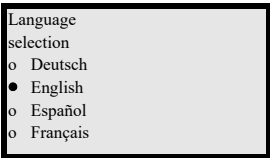
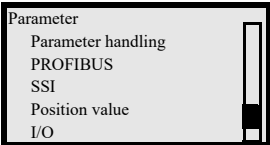
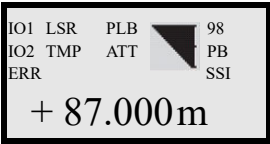
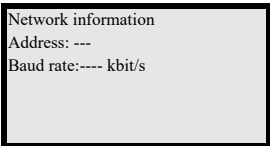
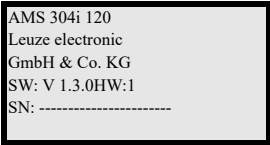
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The main menus



Device information - main menu
This menu item contains detailed information on

- Device type
- Manufacturer
- Software and hardware version
- Serial number

No entries can be made via the display.

Network information - main menu
Explanations of address and baud rate.
No entries can be made via the display.

Status and measurement data - main menu

- Display of status, warning and error messages.
- Status overview of the switching inputs/outputs
- Bar graph for the received signal level.
- Activated interface.
- Measurement value

No entries can be made via the display.
See "Indicators in the display" on page 41.

Parameter - main menu

- Configuration for PROFIBUS is carried out via the modules of the GSD file.

Language selection - main menu

- Selection of the display language.
See "Language selection menu" on page 51.

Service - main menu

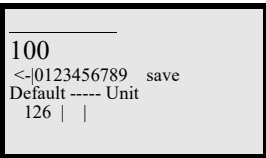
- Display of status messages.
- Display of diagnostic data.

No entries can be made via the display.
See "Service menu" on page 51.

Device buttons:

- Navigate upward/sideways
- Navigate downward/sideways
- ESCAPE** leave
- ENTER** confirm

Input of values



- + **Delete character**
- + **Enter digit**
- + **Save input**

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1 General information

1.1 Explanation of symbols

The symbols used in this technical description are explained below.



Attention!

This symbol precedes text messages which must strictly be observed. Failure to observe the provided instructions could lead to personal injury or damage to equipment.



Attention Laser!

This symbol warns of possible danger through hazardous laser radiation.



Note!

This symbol indicates text passages containing important information.

1.2 Declaration of Conformity

The AMS 304*i* absolute measuring optical laser measurement system was designed and manufactured in accordance with the applicable European directives and standards.

The AMS series is "UL LISTED" according to American and Canadian safety standards and fulfills the requirements of Underwriter Laboratories Inc. (UL).



Note!

The Declaration of Conformity for these devices can be requested from the manufacturer.

The manufacturer of the product, Leuze electronic GmbH & Co. KG in D-73277 Owen, possesses a certified quality assurance system in accordance with ISO 9001.

1.3 Description of functions AMS 304/

The AMS 304/ optical laser measurement system calculates distances to fixed as well as moving system parts. The distance to be measured is calculated according to the principle of the propagation time of radiated light. Here, the light emitted by the laser diode is reflected by a reflector onto the receiving element of the laser measurement system. The AMS 304/ uses the "propagation time" of the light to calculate the distance to the reflector. The high absolute measurement accuracy of the laser measurement system and the fast response time are designed for position control applications.

With its AMS 3xx/ product series, Leuze makes available a wide range of internationally relevant interfaces. Note that each interface version listed below corresponds to a different AMS 3xx/ model.



AMS 304/



AMS 348/



AMS 355/



AMS 358/



AMS 335/



AMS 338/



AMS 308/



AMS 384/



AMS 301/



AMS 300/

2 Safety

This sensor was developed, manufactured and tested in line with the applicable safety standards. It corresponds to the state of the art.

2.1 Intended use

The AMS is an absolute measuring optical laser measurement system which allows distance measurement of up to 300m against a reflector.

Areas of application

The AMS is designed for the following areas of application:

- Positioning of automated, moving plant components
- Travel and lifting axes of high-bay storage devices
- Repositioning units
- Gantry crane bridges and their trolleys
- Elevators
- Electroplating plants



CAUTION

Observe intended use!

☞ *Only operate the device in accordance with its intended use. The protection of personnel and the device cannot be guaranteed if the device is operated in a manner not complying with its intended use.*

Leuze electronic GmbH + Co. KG is not liable for damages caused by improper use.

☞ *Read the technical description before commissioning the device. Knowledge of this technical description is an element of proper use.*

NOTE

Comply with conditions and regulations!

☞ *Observe the locally applicable legal regulations and the rules of the employer's liability insurance association.*



Attention

For UL applications, use is only permitted in Class 2 circuits in accordance with the NEC (National Electric Code).

2.2 Foreseeable misuse

Any use other than that defined under "Intended use" or which goes beyond that use is considered improper use.

In particular, use of the device is not permitted in the following cases:

- in rooms with explosive atmospheres
- as stand-alone safety component in accordance with the machinery directive ¹⁾
- for medical purposes

NOTE**Do not modify or otherwise interfere with the device!**

⚠ *Do not carry out modifications or otherwise interfere with the device.*

The device must not be tampered with and must not be changed in any way.

The device must not be opened. There are no user-serviceable parts inside.

Repairs must only be performed by Leuze electronic GmbH + Co. KG.

2.3 Competent persons

Connection, mounting, commissioning and adjustment of the device must only be carried out by competent persons.

Prerequisites for competent persons:

- They have a suitable technical education.
- They are familiar with the rules and regulations for occupational safety and safety at work.
- They are familiar with the technical description of the device.
- They have been instructed by the responsible person on the mounting and operation of the device.

Certified electricians

Electrical work must be carried out by a certified electrician.

Due to their technical training, knowledge and experience as well as their familiarity with relevant standards and regulations, certified electricians are able to perform work on electrical systems and independently detect possible dangers.

In Germany, certified electricians must fulfill the requirements of accident-prevention regulations DGUV (German Social Accident Insurance) provision 3 (e.g. electrician foreman). In other countries, there are respective regulations that must be observed.

2.4 Exemption of liability

Leuze electronic GmbH + Co. KG is not liable in the following cases:

- The device is not being used properly.
- Reasonably foreseeable misuse is not taken into account.
- Mounting and electrical connection are not properly performed.
- Changes (e.g., constructional) are made to the device.

¹⁾ Use as safety-related component within the safety function is possible, if the component combination is designed correspondingly by the machine manufacturer.

2.5 Laser safety notices



ATTENTION! LASER RADIATION – CLASS 2 LASER PRODUCT

Do not stare into beam!

The device satisfies the requirements of IEC/EN 60825-1:2014 safety regulations for a product of **laser class 2** and complies with 21 CFR 1040.10 except for conformance with IEC 60825-1 Ed. 3., as described in Laser Notice No. 56, dated May, 2019.

- ⚠ *Never look directly into the laser beam or in the direction of reflected laser beams!*
If you look into the beam path over a longer time period, there is a risk of injury to the retina.
- ⚠ *Do not point the laser beam of the device at persons!*
- ⚠ *Interrupt the laser beam using a non-transparent, non-reflective object if the laser beam is accidentally directed towards a person.*
- ⚠ *When mounting and aligning the device, avoid reflections of the laser beam off reflective surfaces!*
- ⚠ *CAUTION! The use of operating and adjustment devices other than those specified here or the carrying out of differing procedures may lead to dangerous exposure to radiation.*
- ⚠ *Observe the applicable statutory and local laser protection regulations.*
- ⚠ *The device must not be tampered with and must not be changed in any way.*
There are no user-serviceable parts inside the device.
Repairs must only be performed by Leuze electronic GmbH + Co. KG.

NOTE

Affix laser information and warning signs!

Laser information and warning signs are attached to the device (see figure 2.1). Also included with the device are self-adhesive laser warning and laser information signs (stick-on labels) in multiple languages (see figure 2.2).

- ⚠ *Affix the laser information sheet to the device in the language appropriate for the place of use.*
When using the device in the U.S.A., use the stick-on label with the "Complies with 21 CFR 1040.10" notice.
- ⚠ *Affix the laser information and warning signs near the device if no signs are attached to the device (e.g. because the device is too small) or if the attached laser information and warning signs are concealed due to the installation position.*
Affix the laser information and warning signs so that they can be read without the reader being exposed to the laser radiation of the device or other optical radiation.

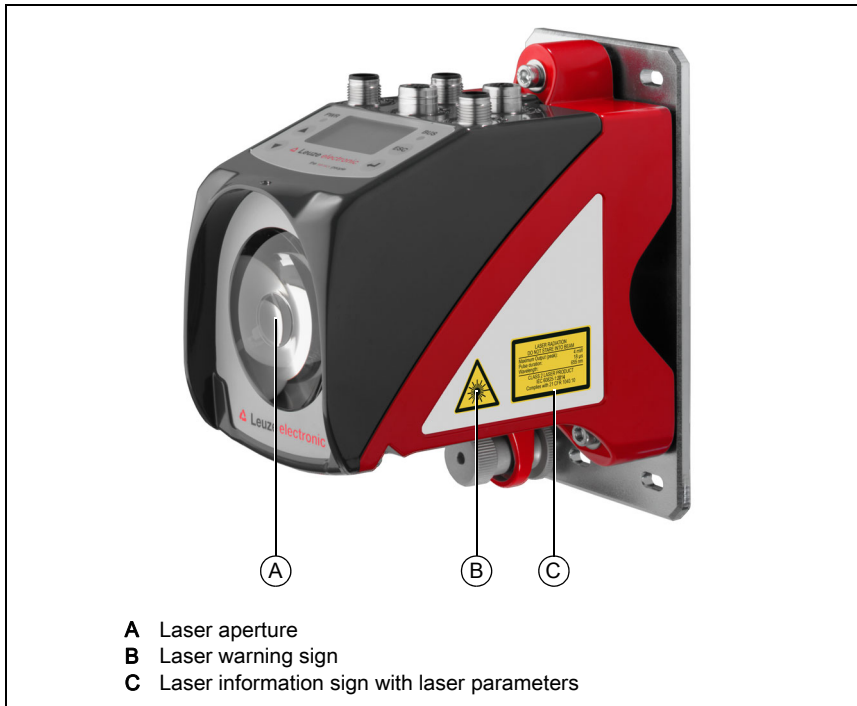


Figure 2.1: Laser apertures, laser warning signs

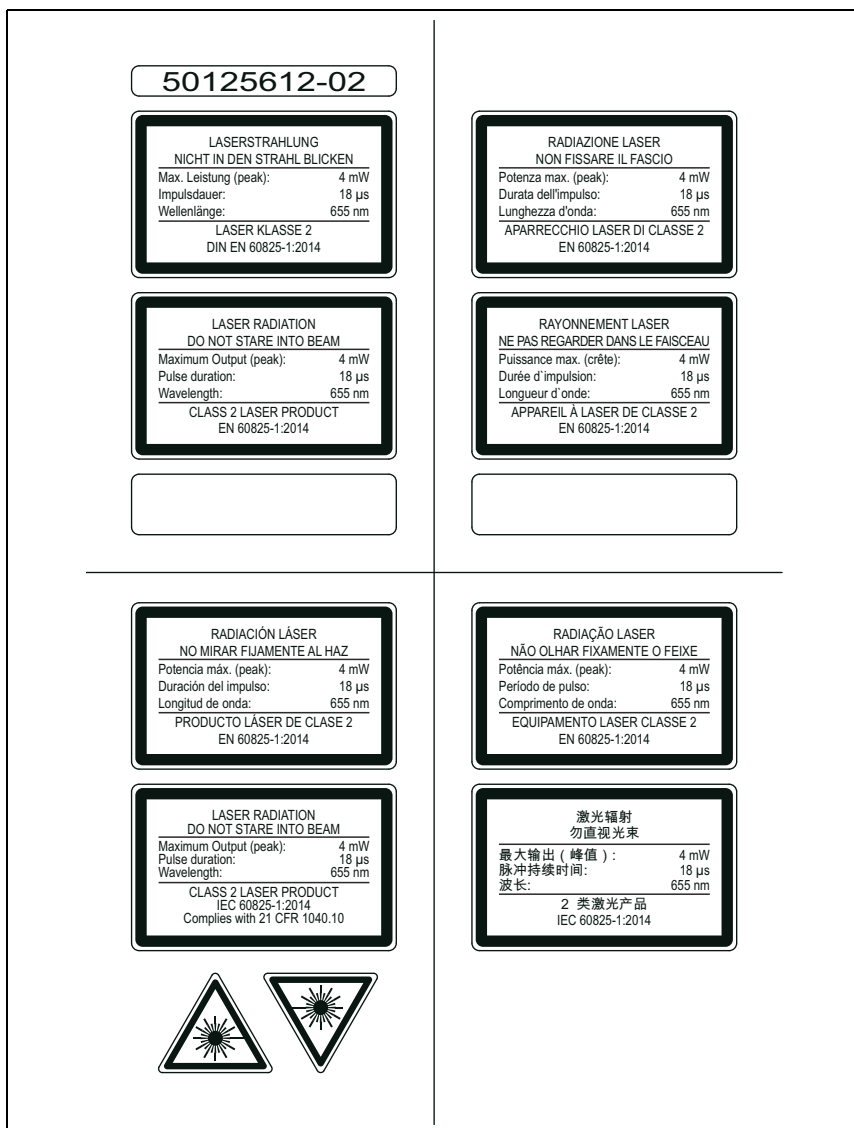


Figure 2.2: Laser warning and information signs – supplied stick-on labels

3 Fast commissioning / operating principle

**Note!**

Below you will find a **short description for the initial commissioning** of the AMS 304*i*. Detailed explanations for the listed points can be found throughout the handbook.

3.1 Mounting the AMS 304*i*

The AMS 304*i* and the corresponding reflector are mounted on two mutually opposing, plane-parallel, flat walls.



Figure 3.1: Schematic illustration of mounting

**Attention!**

For error-free position measurement, there must be an unobstructed line-of-sight between the AMS 304*i* and the reflector.

3.1.1 Mounting the device

The laser is mounted using 4 screws (M5).

Alignment is performed using 2 adjustment screws. Adjust so that the laser light spot is positioned at the center of the reflector. The alignment is secured with the knurled nut and locked with the M5 nut.

Detailed information can be found in Chapter 5.2 and Chapter 5.3.

3.1.2 Mounting the reflector

The reflector is mounted using 4 screws (M5). The reflector is angled using the spacer sleeves included. Incline the reflector by approx. 1°.

Detailed information can be found in Chapter 6.4.

3.2 Connecting the voltage supply

The laser measurement system is connected using M12 connectors. The voltage supply is connected via the PWR M12 connection.

Detailed information can be found in Chapter 7.

3.3 Display

Once the laser measurement system is supplied with voltage, the device status as well as the measured position values can be read on the display. The display automatically switches to the display of the measurement values.

Use the up/down buttons   to the left of the display to read and change a wide range of data and parameters.

Depending on the connected interface, the network address or IP addresses must be configured via the display.

Detailed information can be found in Chapter 8.

3.4 AMS 304/i on the PROFIBUS

Install the GSD file associated with the AMS 304/i in the PROFIBUS manager of your control. Activate the desired modules (at least one module).

Store the slave address for the AMS 304/i in the PROFIBUS manager. Ensure that the address is the same as the address configured in the device.

Detailed information can be found in Chapter 9.

4 Technical data

4.1 Technical data of laser measurement system

4.1.1 General specifications AMS 304/

Measurement data	AMS 304/40 (H)	AMS 304/120 (H)	AMS 304/200 (H)	AMS 304/300 (H)
Measurement range	0.2 ... 40m	0.2 ... 120m	0.2 ... 200m	0.2 ... 300m
Accuracy	± 2mm	± 2mm	± 3mm	± 5mm
Reproducibility ¹⁾	0.3mm	0.5mm	0.7mm	1.0mm
Light spot diameter	≤ 40mm	≤ 100mm	≤ 150mm	≤ 225mm
Output time	1.7 ms			
Response time	14ms			
Basis for contouring error calculation	7ms			
Resolution	Adjustable; see chapters on individual interfaces			
Temperature drift	≤ 0.1mm/K			
Ambient temperature sensitivity	1ppm/K			
Air pressure sensitivity	0.3ppm/hPa			
Traverse rate	≤ 10m/s			
Electrical data				
Supply voltage Vin ²⁾	18 ... 30VDC			
Current consumption	Without device heating: ≤ 250mA / 24VDC With device heating: ≤ 500mA / 24VDC			
Optical data				
Transmitter	Laser diode, red light			
Laser class	2 in acc. with IEC 60825-1:2014			
Wavelength	655nm			
Impulse duration	≤ 18µs			
Max. output power (peak)	≤ 4mW			
Interfaces				
PROFIBUS DP to V, V1	≤ 12Mbit/s			
SSI clock rate	50kHz ... 800kHz			
Controls and indicators				
Keyboard	4 keys			
Display	Monochromatic graphical display, 128 x 64 pixels			
LED	2 LEDs, two-colored			
Inputs/outputs				
Quantity	2, programmable			
Input	Protected against polarity reversal			
Output	Max. 60 mA, short-circuit-proof			

Mechanical data

Housing	Diecast zinc/aluminum
Optics	Glass
Weight	Approx. 2.45 kg
Degree of protection	IP 65 acc. to EN 60529 ³⁾

Environmental conditions

Operating temperature	
without device heating	-5 °C ... +50 °C
with device heating	-30 °C ... +50 °C ⁴⁾
Storage temperature	-30 °C ... +70 °C
Air humidity	Max. 90% rel. humidity, non-condensing
MTTF	31 years (at 25 °C) ⁵⁾

Mechanical/electrical loading capacity

Vibration	Acc. to EN 60068-2-6
Noise	Acc. to EN 60060-2-64
Shock	Acc. to EN 60068-2-27
EMC	Acc. to EN 61000-6-2 and EN 61000-6-4 ⁶⁾

- 1) Statistical error: 1 sigma; minimum switch-on time: 2min.
- 2) For UL applications: only for use in "Class 2" circuits according to NEC.
- 3) With screwed-on M12 plugs or mounted caps.
- 4) With devices with heating, the switch on/off area of the internal heating can be extended to prevent condensation from forming. Total prevention of condensation cannot be guaranteed due to the limited heating capacity of the AMS 304/.
- 5) We reserve the right to make changes. (Value is updated at regular intervals.)
- 6) This is a Class A product. In a domestic environment this product may cause radio interference, in which case the operator may be required to take adequate measures.



The AMS 304/ is designed in accordance with protection class III for supply with PELV (protective extra-low voltage).

4.1.2 AMS 304/i dimensioned drawing

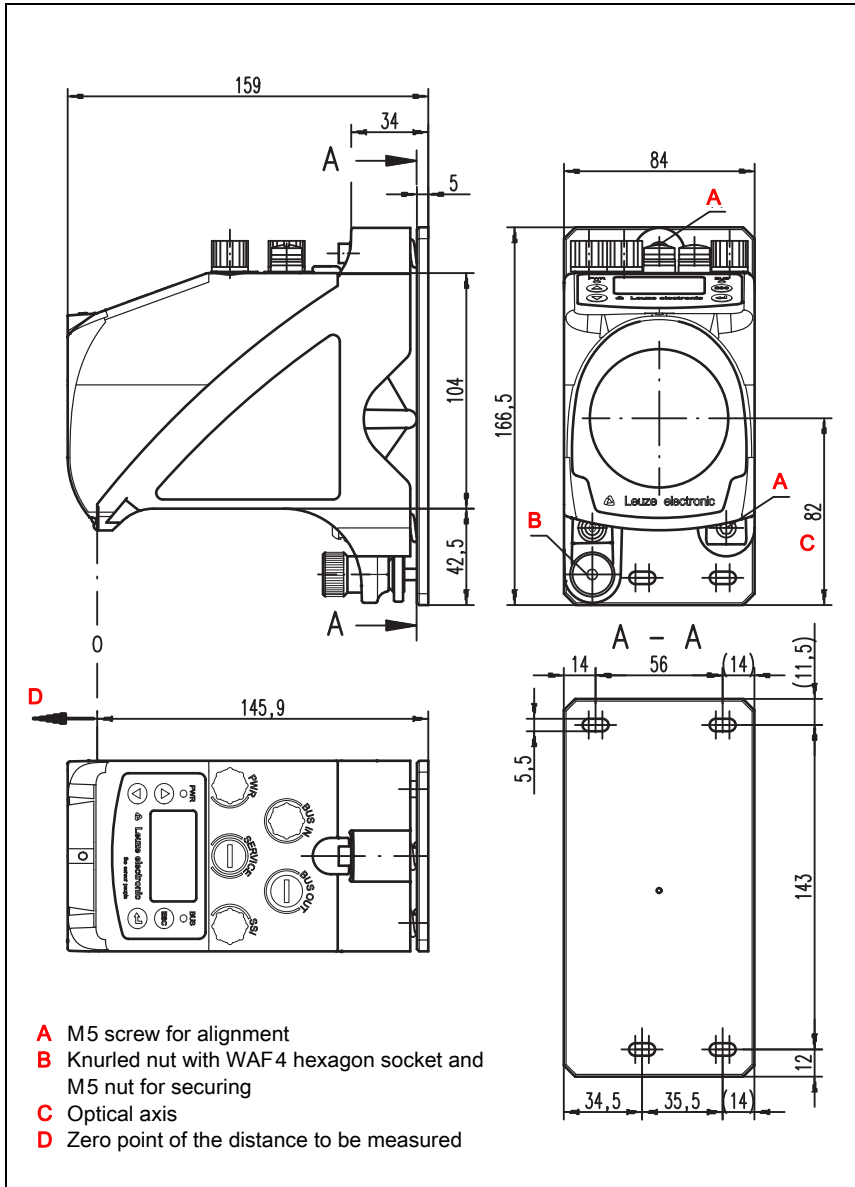


Figure 4.1: AMS 304/i dimensioned drawing

4.1.3 Overview of AMS 304/i types

AMS 304/i (PROFIBUS)

Type designation	Description	Part no.
AMS 304/i 40	40m operating range, PROFIBUS/SSI interface	50113677
AMS 304/i 120	120m operating range, PROFIBUS/SSI interface	50113678
AMS 304/i 200	200m operating range, PROFIBUS/SSI interface	50113679
AMS 304/i 300	300m operating range, PROFIBUS/SSI interface	50113680
AMS 304/i 40 H	40m operating range, PROFIBUS/SSI interface, integrated heating	50113681
AMS 304/i 120 H	120m operating range, PROFIBUS/SSI interface, integrated heating	50113682
AMS 304/i 200 H	200m operating range, PROFIBUS/SSI interface, integrated heating	50113683
AMS 304/i 300 H	300m operating range, PROFIBUS/SSI interface, integrated heating	50113684

Table 4.1: Overview of AMS 304/i types

5 Installation and mounting

5.1 Storage, transportation



Attention!

Package the device for transport and storage in such a way that is protected against shock and humidity. Optimum protection is achieved when using the original packaging. Ensure compliance with the approved environmental conditions listed in the specifications.

Unpacking

✦ *Check the packaging content for any damage. If damage is found, notify the post office or shipping agent as well as the supplier.*

✦ *Check the delivery contents using your order and the delivery papers:*

- Delivered quantity
- Device type and model as indicated on the name plate
- Brief manual

The name plate provides information as to what AMS 304/i type your device is. For specific information, please refer to Chapter 12.2.

Name plates

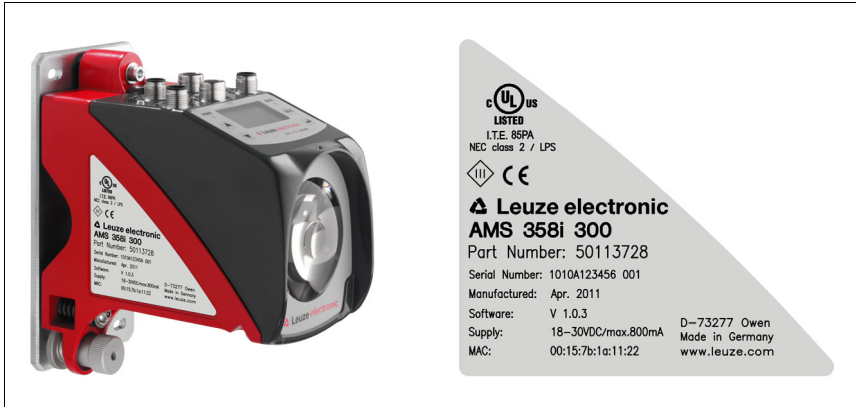


Figure 5.1: Device name plate using the AMS 358i as an example



Note!

Please note that the shown name plate is for illustration purposes only; the contents do not correspond to the original.

✦ *Save the original packaging for later storage or shipping.*

If you have any questions concerning your shipment, please contact your supplier or your local Leuze sales office.

↗ Observe the applicable local regulations when disposing of the packaging materials.

5.2 Mounting the AMS 304*i*

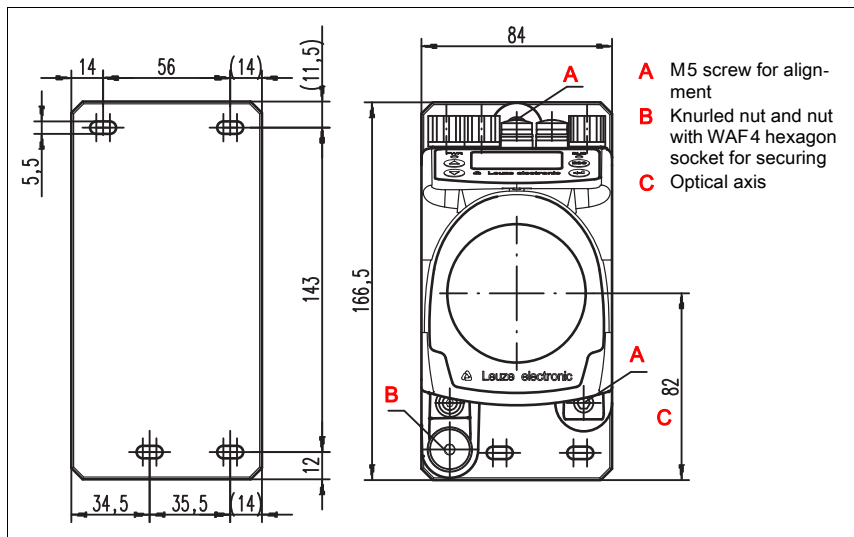


Figure 5.2: Mounting the device

The AMS 304*i* and the corresponding reflector are mounted on two mutually opposing, plane-parallel, flat walls or system parts. For error-free position measurement, there must be an unobstructed line-of-sight between the AMS 304*i* and the reflector.

Use M5 screws to fasten the laser measurement system. Secure the screws with a lock washer to protect against loosening caused by vibrations.

Aligning the laser light spot with the center of the reflector

The laser light spot has to be aligned so that it always hits the center of the opposing reflector, both at close range as well as at the maximum measurement distance. **To align, use the two M5 Allen screws ("A" in Figure 5.2).** When aligning, please ensure that the knurled nut and the lock nut ("B" in Figure 5.2) are opened wide.

**Attention!**

To prevent the laser measurement system from moving out of alignment during continuous operation, subsequently hand-tighten the knurled nut and counterlock with the nut with WAF4 hexagon socket ("B" in Figure 5.2). Knurled nut and nut must not be tightened until alignment has been completed.

**Attention!**

The device must not be opened. Failure to comply will render the guarantee void. Warranted features cannot be guaranteed after the device has been opened.

5.2.1 Optional mounting bracket

A mounting bracket for mounting the AMS 304/i on a flat, horizontal surface is available as an optional accessory.

Type designation:

MW OMS/AMS 01

Part no.:

50107255

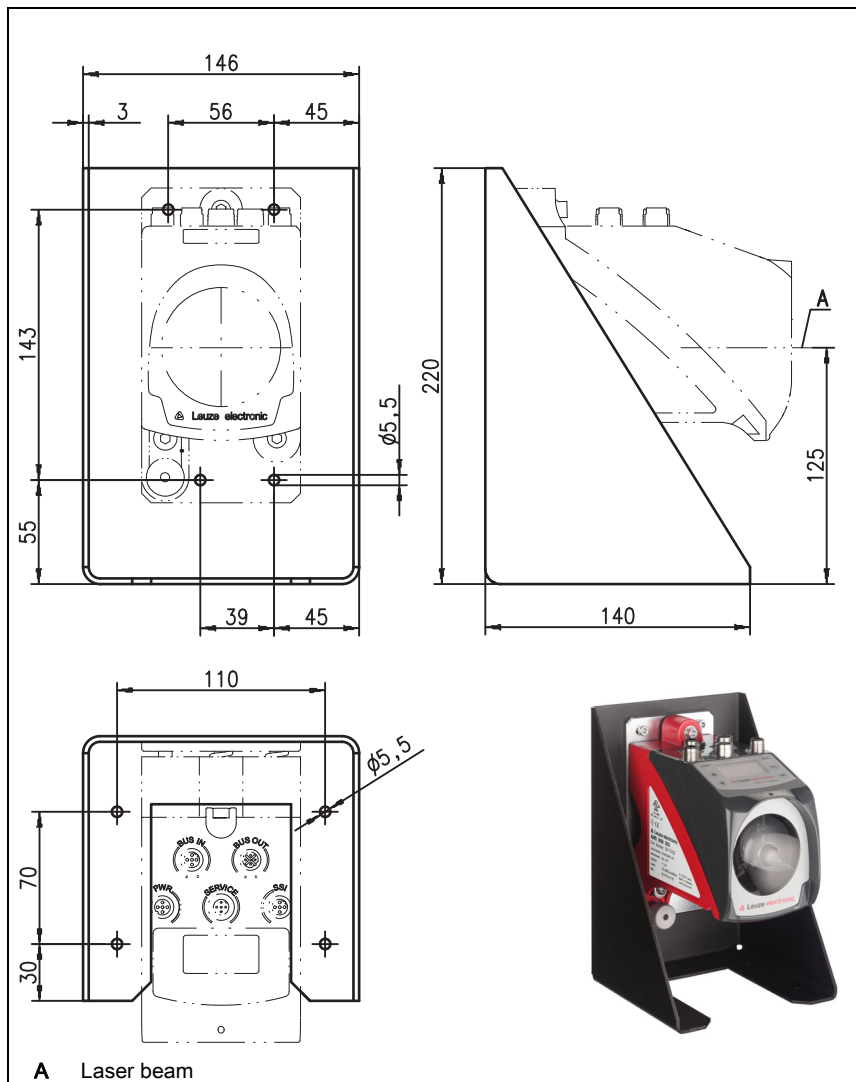


Figure 5.3: Optional mounting bracket

5.2.2 Parallel mounting of the AMS 304*/*

Definition of the term "parallel spacing"

As shown in Figure 5.4, dimension X describes the "parallel spacing" of the inner edges of the two laser light spots on the reflector.

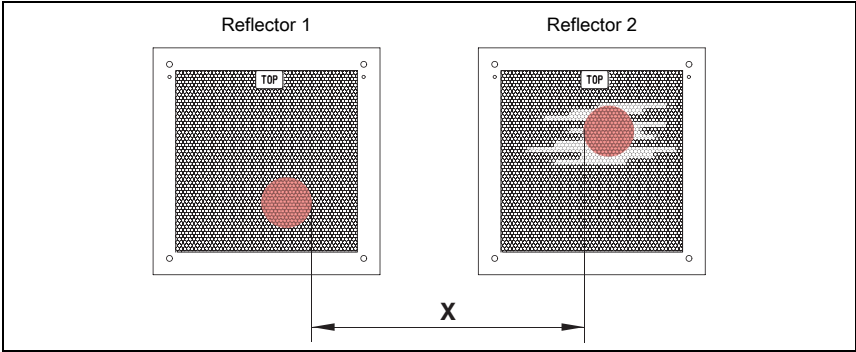


Figure 5.4: Minimum parallel spacing X between adjacent AMS 304*/*

The diameter of the light spot increases with distance.

	AMS 304 <i>/</i> 40 (H)	AMS 304 <i>/</i> 120 (H)	AMS 304 <i>/</i> 200 (H)	AMS 304 <i>/</i> 300 (H)
Max. measurement distance	40m	120m	200m	300m
Light spot diameter	≤ 40mm	≤ 100mm	≤ 150mm	≤ 225mm

Thus, the center-to-center spacing of the two AMS 304*/*devices with respect to one another can be calculated as a function of the maximum measurement distance.

To define the minimum parallel spacing between two AMS 304*/*, it is necessary to distinguish between three different arrangements of AMS 304*/* and reflectors.

**The AMS 304*/* are mounted stationary and in parallel on one plane.
Both reflectors move independently of one another at different distances to the AMS 304*/*.**

Minimum parallel spacing X of the two laser light spots:
 $X = 100\text{mm} + (\text{max. measurement distance in mm} \times 0.01)$

**The AMS 304*/* are mounted stationary and in parallel on one plane.
Both reflectors move in parallel at the same distance to the AMS 304*/*.**
Measurement distance **up to 120m**: minimum parallel spacing **X ≥ 600mm**
Measurement distance **up to 200m**: minimum parallel spacing **X ≥ 750mm**
Measurement distance **up to 300m**: minimum parallel spacing **X ≥ 750mm**

The reflectors are mounted stationary and in parallel on one plane.

Both AMS 304/i move independently of one another at different or the same distances to the reflectors.

Measurement distance up to 120m: minimum parallel spacing $X \geq 600\text{mm}$

Measurement distance up to 200m: minimum parallel spacing $X \geq 750\text{mm}$

Measurement distance up to 300m: minimum parallel spacing $X \geq 750\text{mm}$



Note!

Please note that when the AMS 304/i are mounted in a mobile manner, travel tolerances could cause the two laser light spots to move towards each other.

Take the travel tolerances of the vehicle into account when defining the parallel spacing of adjacent AMS 304/i.

5.2.3 Parallel mounting of AMS 304/i and DDLS optical data transmission

The optical data transceivers of the DDLS series and the AMS 304/i do not interfere with one another. Depending on the size of the used reflector, the DDLS can be mounted with a minimum parallel spacing of 100mm to the AMS 304/i. The parallel spacing is independent of the distance.

5.3 Mounting the AMS 304/i with laser beam deflector unit

General information

The two available deflector units are used for the 90° deflection of the laser beam, see "Accessories – Deflector unit" on page 107.



Attention!

The deflector units are designed for a maximum range of 40m. Longer distances on request.

5.3.1 Mounting the laser beam deflector unit with integrated mounting bracket

The AMS 304/i is screwed onto the mechanism of the US AMS 01 deflector unit. The mirror can be mounted for three deflection directions:

1. Upward beam deflection
2. Beam deflection to the left
3. Beam deflection to the right

The deflector unit is mounted on plane-parallel, flat walls or system parts. For error-free position measurement, there must be an unobstructed line-of-sight between the AMS 304/i... and the deflection mirror as well as between the mirror and the reflector.

Use the M5 screws to mount the deflector unit. Secure the screws with a lock washer to protect against loosening caused by vibrations.

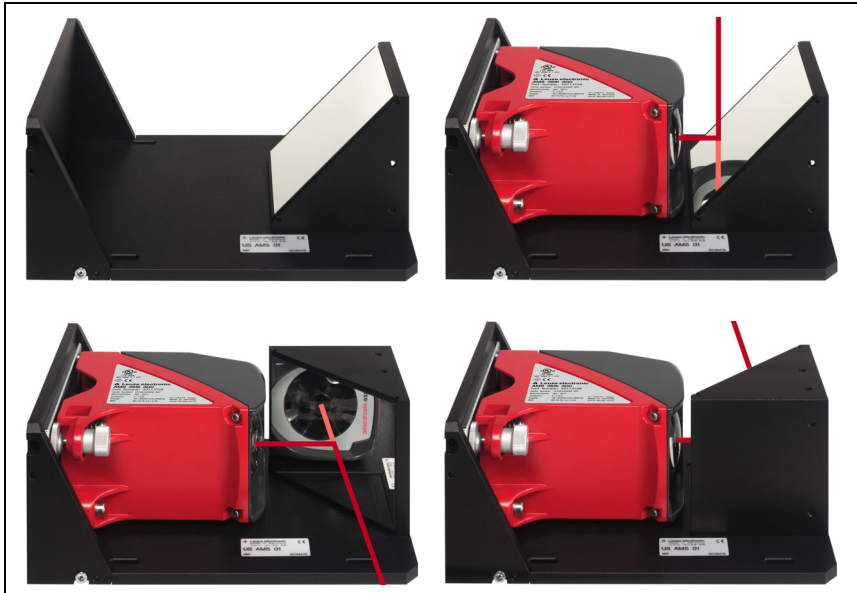


Figure 5.5: Mounting variants of the US AMS 01 laser beam deflector unit

5.3.2 Dimensioned drawing of US AMS 01 deflector unit

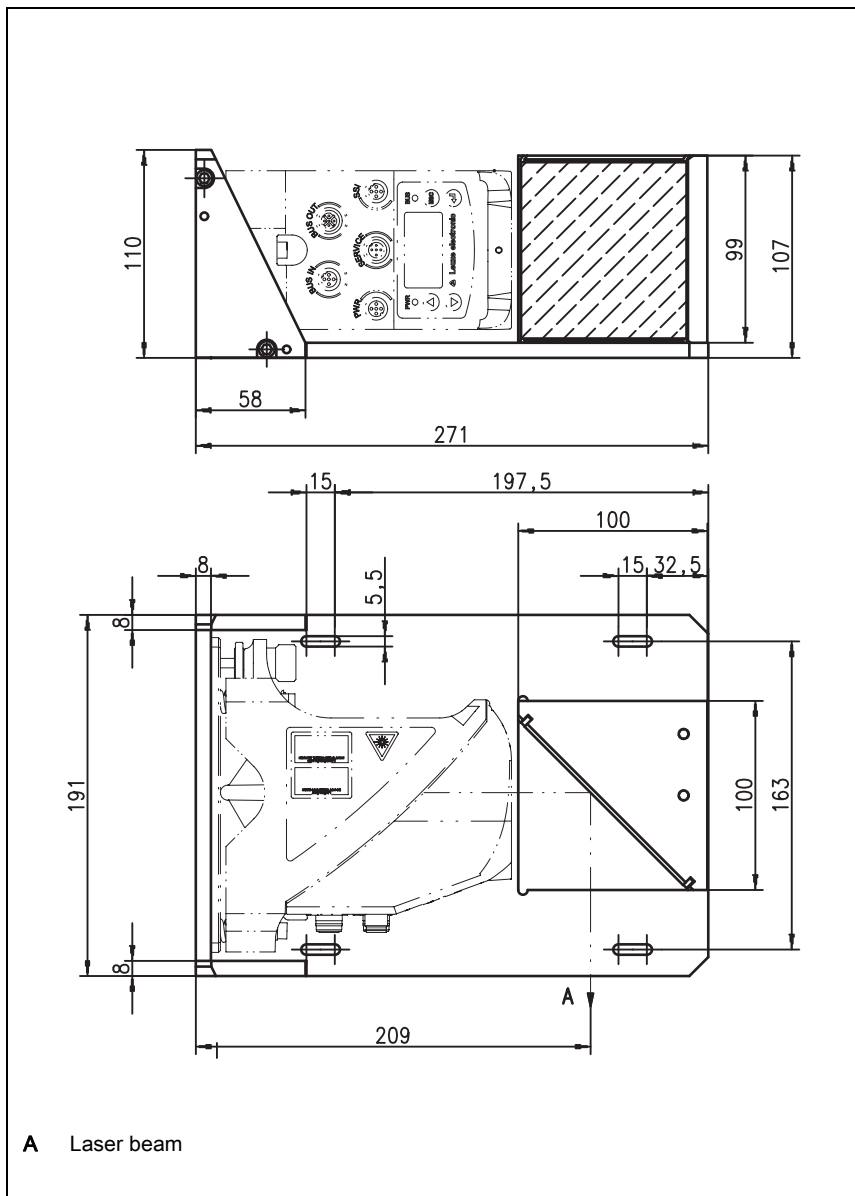


Figure 5.6: Dimensioned drawing of US AMS 01 deflector unit

5.3.3 Mounting the US 1 OMS deflector unit without mounting bracket

The US 1 OMS deflector unit and the AMS 304*i* are mounted separately.



Note!

When mounting, make certain that the laser light spot of the AMS 304*i* is aligned with the center of the deflection mirror.

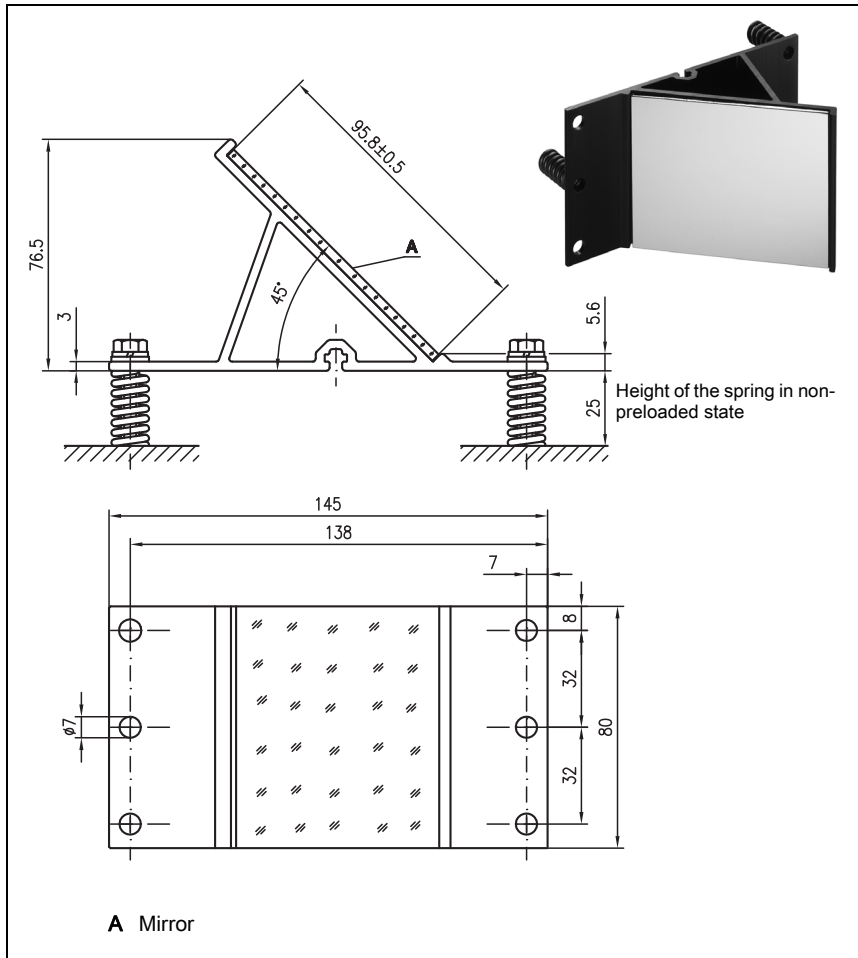


Figure 5.7: Photo and dimensioned drawing of the US 1 OMS deflector unit

The laser light spot is aligned with the reflector as described in Chapter 5.2.

6 Reflectors

6.1 General information

The AMS 304*/* measures distances against a reflective tape specified by Leuze. All technical data given for the AMS 304*/*, such as the operating range or accuracy, can only be achieved with the reflective tape specified by Leuze.

The reflective tapes are available as self-adhesive tapes or affixed to a carrier plate and with an integrated heater especially for use at low temperatures. Reflective tapes with heating have the designation "**Reflective tape ...x...-H**", where "**H**" is an abbreviation for the heating variant.

The reflective tapes/reflectors must be ordered separately. The choice of size is left to the user. In Chapter 6.3, recommendations on reflector size are given depending on the distance that is to be measured. In each case, the user must check whether the recommendation is suitable for the respective application.

6.2 Description of the reflective tape

The reflective tape consists of a white, microprism-based reflective material. The microprisms are protected by a hard, highly transparent protective layer.

Under certain circumstances, the protective layer can cause surface reflections. The surface reflections can be directed past the AMS 304*/* by positioning the reflective tape at a slight incline. The inclination of the reflective tape/reflectors is described in Chapter 6.4.2. The required pitch can be found in Table 6.1 "Reflector pitch resulting from spacer sleeves" on page 36.

The reflective tapes have a protective film that is easy to peel off. It must be removed from the reflector before the complete system is put into operation.

6.2.1 Technical data of self-adhesive tape

	Article				
Type designation	Reflective tape 200x200-S	Reflective tape 500x500-S	Reflective tape 914x914-S	REF 4-A- 150x150	REF 4-A- 300x300
Part no.	50104361	50104362	50108988	50141015	50141014
Film size	200 x 200 mm	500 x 500 mm	914x914 mm	150 x 150 mm	300 x 300 mm
Recommended application temperature for adhesive tape	+5°C ... +25°C				
Temperature resistance, affixed	-40°C ... +80°C				
Bonding surface	The bonding surface must be clean, dry and free of grease.				
Cutting tape	Cut with a sharp tool, always on the side with the prism structure.				
Cleaning	Do not use any abrasive agents. A conventional household detergent can be used as a cleaning agent. Rinse with clear water and dry the surface.				
Film storage	Store in a cool and dry place.				

6.2.2 Technical data of reflective tape on carrier plate

The reflective tape is affixed to a carrier plate. Included with the carrier plate are spacers for positioning at an incline in order to avoid surface reflections (see chapter 6.4.2 "Mounting the reflector").

	Article		
Type designation	Reflective tape 200x200-M	Reflective tape 500x500-M	Reflective tape 914x914-M
Part no.	50104364	50104365	50104366
Film size	200 x 200 mm	500 x 500 mm	914x914 mm
Outer dimensions of carrier plate	250 x 250 mm	550 x 550 mm	964 x 964 mm
Weight	0.4 kg	1.6 kg	6 kg
Cleaning	Do not use any abrasive agents. A conventional household detergent can be used as a cleaning agent. Rinse with clear water and dry the surface.		
Reflector storage	Store in a cool and dry place.		

6.2.3 Dimensioned drawing of reflective tape on carrier plate

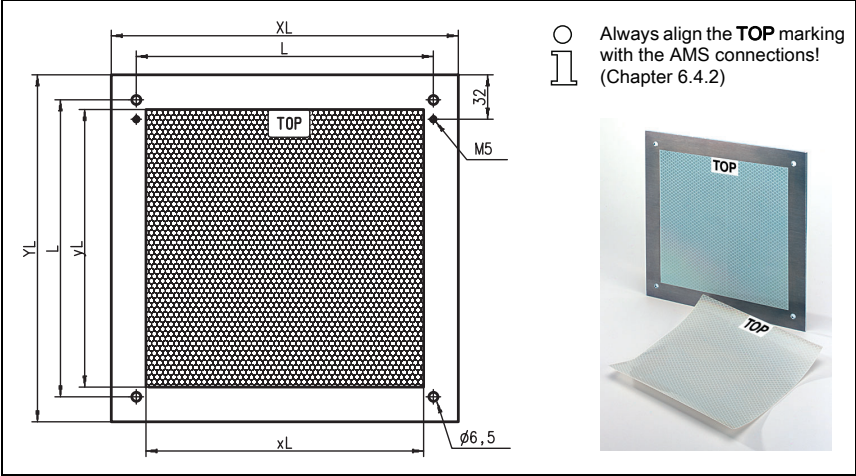


Figure 6.1: Dimensioned drawing of reflectors

Article	Reflective tape (mm)		Reflector plate (mm)		
	xL	yL	XL	YL	L
Reflective tape 200x200-M	200	200	250	250	214
Reflective tape 500x500-M	500	500	550	550	514
Reflective tape 914x914-M	914	914	964	964	928

6.2.4 Technical data of heated reflectors

The reflective tape is affixed to a heated, thermally insulated carrier. The insulation results in a very high energetic efficiency.

Only the reflective tape is kept at the specified temperature by the integrated heater. The insulation on the back prevents the generated heat from being dissipated via the steel construction. Energy costs are greatly reduced in the case of continuous heating.

	Article		
Type designation	Reflective tape 200x200-H	Reflective tape 500x500-H	Reflective tape 914x914-H
Part no.	50115020	50115021	50115022
Voltage supply	230VAC		
Power	100W	600W	1800W
Current consumption	~ 0.5A	~ 3A	~ 8A
Length of supply line	2 m		
Size of reflective tape	200 x 200mm	500 x 500mm	914 x 914mm
Outer dimensions of base material	250 x 250mm	550 x 550mm	964 x 964mm
Weight	0.5kg	2.5kg	12kg
Temperature control	Controlled heating with the following switch-on and switch-off temperatures, measured at the reflector surface.		
Switch-on temperature	~ 5°C		
Switch-off temperature	~ 20°C		
Operating temperature	-30°C ... +70°C		
Storage temperature	-40°C ... +80°C		
Air humidity	Max. 90 %, non-condensing		
Cleaning	Do not use any abrasive agents. A conventional household detergent can be used as a cleaning agent. Rinse with clear water and dry the surface.		
Reflector storage	Store in a cool and dry place.		

6.2.5 Dimensioned drawing of heated reflectors

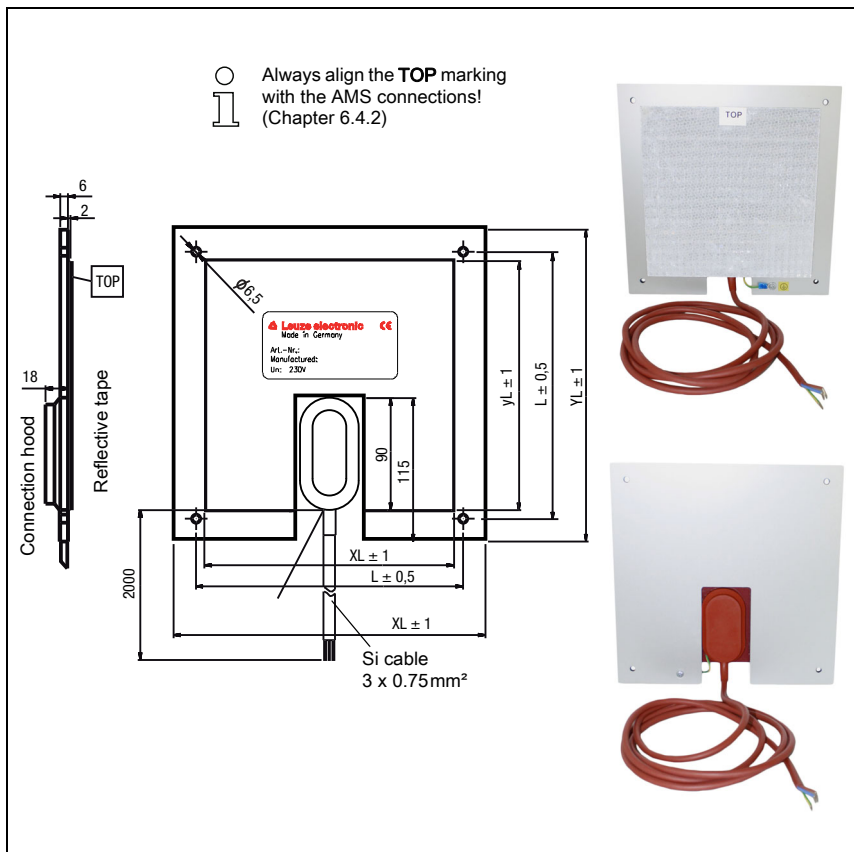


Figure 6.2: Dimensioned drawing of heated reflectors

Article	Reflective tape (mm)		Insulated carrier plate (mm)		
	xL	yL	XL	YL	L
Reflective tape 200x200-H	200	200	250	250	214
Reflective tape 500x500-H	500	500	550	550	514
Reflective tape 914x914-H	914	914	964	964	928

6.3 Selecting reflector size

Depending on the system design, the reflector can be mounted so that it moves with the vehicle or it can be mounted at a fixed location.



Attention!

*The reflector sizes shown below are a recommendation from Leuze for on-vehicle mounting of the AMS 304*i*. For stationary mounting of the AMS 304*i*, a smaller reflector is generally sufficient for all measurement distances. For this reason, two smaller reflector sizes are available in the self-adhesive variant "-S".*

*During system planning and design, always check whether mechanical travel tolerances require the use of a reflector larger than that which is recommended. This applies, in particular, when the laser measurement system is mounted on a vehicle. During travel, the laser beam must reach the reflector unobstructed. For on-vehicle mounting of the AMS 304*i*, the reflector size must accommodate any travel tolerances that may arise and the associated "wandering" of the light spot on the reflector.*

Overview of reflector types

Recommended reflector size			
Selected AMS 304 <i>i</i> (operating range in m)	Recommended reflector size (H x W)	Type designation ...-S = self-adhesive ...-M = Carrier plate ...-H = heating	Part no.
AMS 304 <i>i</i> 40 (max. 40m)	200 x 200 mm	REF 4-A-150x150 ¹⁾ Reflective tape 200x200-S Reflective tape 200x200-M Reflective tape 200x200-H REF 4-A-300x300 ¹⁾	50141015 50104361 50104364 50115020 50141014
AMS 304 <i>i</i> 120 (max. 120m)	500x500mm	Reflective tape 500x500-S Reflective tape 500x500-M Reflective tape 500x500-H	50104362 50104365 50115021
AMS 304 <i>i</i> 200 (max. 200m)	749x914mm 914x914mm	Reflective tape 749x914-S Reflective tape 914x914-M Reflective tape 914x914-S Reflective tape 914x914-H	50104363 50104366 50108988 50115022
AMS 304 <i>i</i> 300 (max. 300m)	749x914mm 914x914mm	Reflective tape 749x914-S Reflective tape 914x914-M Reflective tape 914x914-S Reflective tape 914x914-H	50104363 50104366 50108988 50115022

1) For landside mounting

6.4 Mounting the reflector

6.4.1 General information

Self-adhesive reflective tapes

The reflective tapes of the "Reflective tape ...x...-S" series (self-adhesive) must be affixed to a flat, clean and grease-free surface. We recommend using a separate carrier plate, which is to be provided on-site.

As described in Table 6.1, the reflective tape must be at an angle.

Reflective tapes on carrier plate

The reflective tapes of the "Reflective tape ...x...-M" series have corresponding mounting holes. Spacer sleeves are provided to enable mounting at the necessary pitch angle. For further information, see Table 6.1.

Heated reflectors

The reflective tapes of the "Reflective tape ...x...-H" series have corresponding mounting holes. Due to the voltage supply affixed on the rear, the reflector cannot be mounted flat. Four spacer sleeves in two different lengths are supplied. Use the spacer sleeves to ensure separation from the wall as well as to provide the necessary pitch for avoiding surface reflection. For further information, see Table 6.1.

The reflector has a 2m-long connection cable for supplying with 230VAC. Connect the cable to the nearest power distribution point. Observe the current consumptions listed in the technical data.



Attention!

Connection work must be carried out by a certified electrician.

6.4.2 Mounting the reflector

The combination of laser measurement system and reflective tape/reflector is mounted so that the laser light spot hits the film as centered as possible and without obstruction.

For this purpose, use the alignment elements provided on the AMS 304*i*... (see chapter 5.2 "Mounting the AMS 304i"). If necessary, remove the protective film from the reflector.



Attention!

The "TOP" label on the reflectors should be aligned the same as the connections of the AMS 304*i*.

Example:

*If the AMS 304*i* is mounted so that the M12 connections are on the top, the "TOP" label of the reflector is also on the top. If the AMS 304*i* is mounted so that the M12 connections are on the side, the "TOP" label of the reflector is also on the side.*

i

Note!
The reflector must be positioned at an angle. Use the spacer sleeves for this purpose. Angle the reflector so that the **surface reflections of the foil seal are deflected to the left, right or upwards**. Chapter 6.4.3 gives the correct pitch with respect to the reflector size and, thus, the length of the spacers.

Reflective tapes ...-S and ...-M

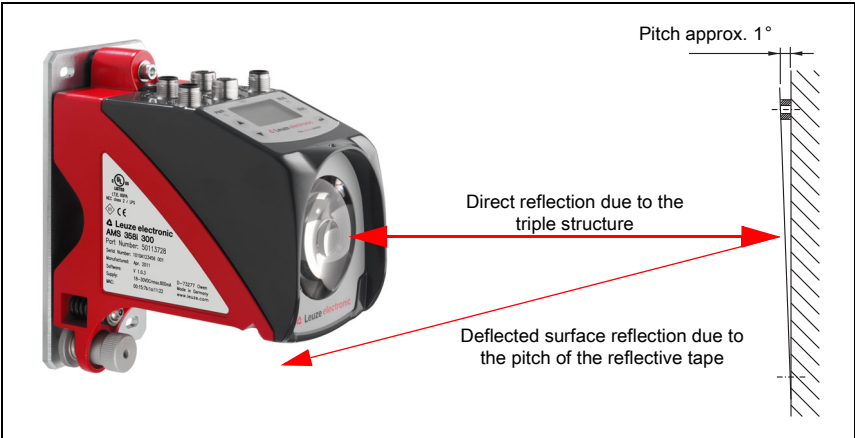


Figure 6.3: Mounting the reflector

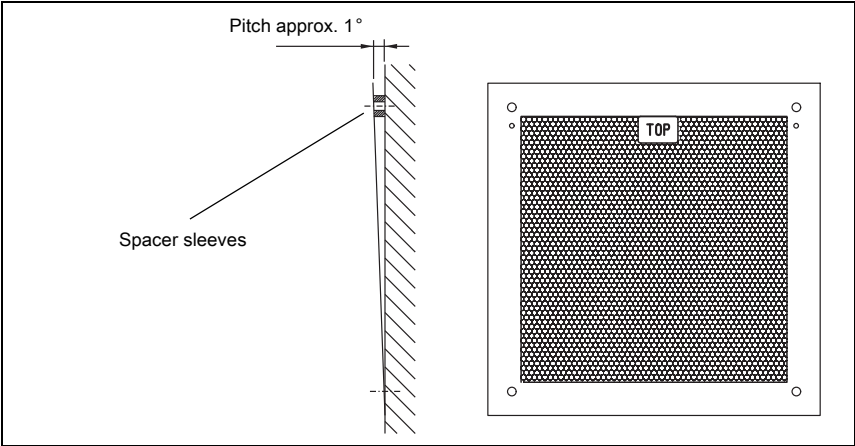


Figure 6.4: Pitch of the reflector

Reflective tapes ...-H

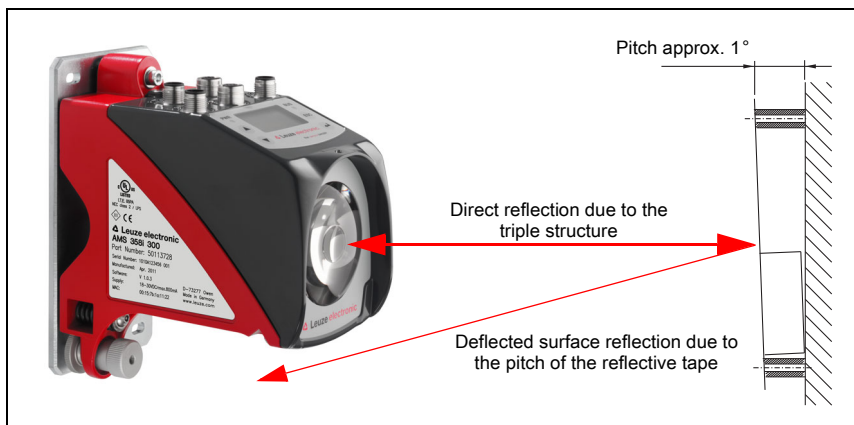


Figure 6.5: Mounting of heated reflectors

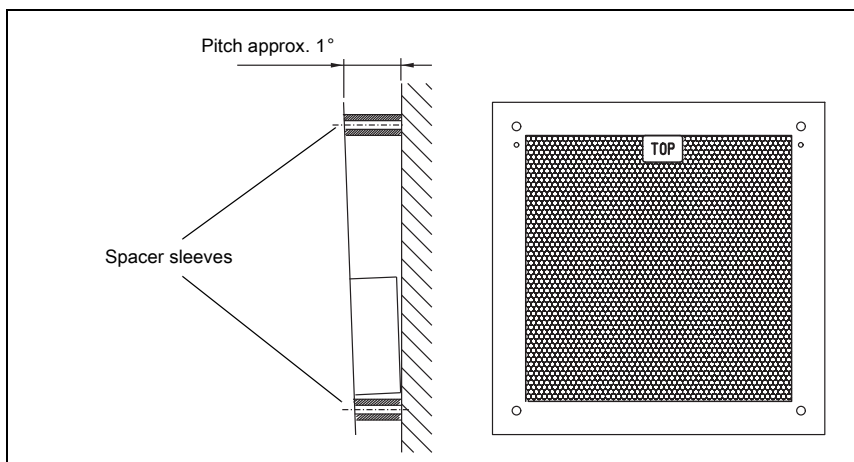


Figure 6.6: Pitch of the heated reflector

6.4.3 Table of reflector pitches

Reflector type	Pitch resulting from spacer sleeves ¹⁾	
Reflective tape 200x200-S Reflective tape 200x200-M	2 x 5mm	
Reflective tape 200x200-H	2 x 15mm	2 x 20mm
Reflective tape 500x500-S Reflective tape 500x500-M	2 x 10mm	
Reflective tape 500x500-H	2 x 15mm	2 x 25mm
Reflective tape 749x914-S	2 x 20mm	
Reflective tape 914x914-S Reflective tape 914x914-M	2 x 20mm	
Reflective tape 914x914-H	2 x 15mm	2 x 35mm

1) Spacer sleeves are included with reflective tape ...-M and ...-H

Table 6.1: Reflector pitch resulting from spacer sleeves



Note!

Reliable operation of the AMS 304*i* and, thus, max. operating range and accuracy can only be achieved with the reflective tape specified by Leuze. Correct operation cannot be guaranteed if other reflectors are used!

7 Electrical connection

The AMS 304*i* laser measurement systems are connected using variously coded M12 connectors. This ensures unique connection assignments.



Note!

The corresponding mating connectors and ready-made cables are available as accessories for all connections. For further information, see chapter 12 "Type overview and accessories".



Figure 7.1: Connections of the AMS 304*i*

7.1 Safety notices for the electrical connection



Attention!

Before connecting the device, be sure that the supply voltage agrees with the value printed on the name plate.

The device may only be connected by a qualified electrician.

Ensure that the functional earth (FE) is connected correctly. Unimpaired operation is only guaranteed when the functional earth is connected properly.

If faults cannot be cleared, the device should be switched off and protected against accidental use.



Attention!

For UL applications, use is only permitted in Class 2 circuits in accordance with the NEC (National Electric Code).



The laser measurement systems are designed in accordance with protection class III for supply by PELV (protective extra-low voltage with reliable disconnection).



Note!

Degree of protection IP65 is achieved only if the connectors and caps are screwed into place!

Described in detail in the following are the individual connections and pin assignments.

7.2 PWR – voltage supply / switching input/output

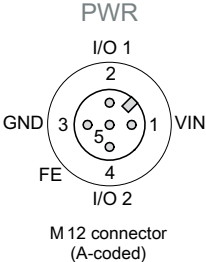
PWR (5-pin plug, A-coded)			
	Pin	Name	Comment
	1	VIN	Positive supply voltage +18 ... +30VDC
	2	I/O 1	Switching input/output 1
	3	GNDIN	Negative supply voltage 0VDC
	4	I/O 2	Switching input/output 2
	5	FE	Functional earth
	Thread	FE	Functional earth (housing)

Table 7.1: Pin assignments - PWR

Further information on configuring the input/output can be found in Chapter 8 and Chapter 9.

7.3 PROFIBUS BUS IN

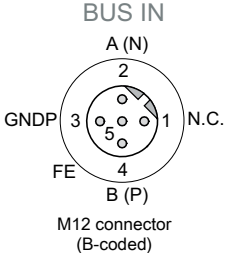
BUS IN (5-pin plug, B-coded)			
	Pin	Name	Comment
	1	NC	Not assigned
	2	A (N)	Receive/transmit data A-line (N)
	3	GNDP	Data reference potential
	4	B (P)	Receive/transmit data B-line (P)
	5	SHIELD	Shield or functional earth
	Thread	FE	Functional earth (housing)

Table 7.2: BUS IN pin assignment

7.4 PROFIBUS BUS OUT

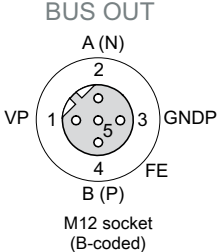
BUS OUT (5-pin socket, B-coded)			
	Pin	Name	Comment
	1	VP	Supply voltage +5V (termination)
	2	A (N)	Receive/transmit data A-line (N)
	3	GNDP	Data reference potential
	4	B (P)	Receive/transmit data B-line (P)
	5	SHIELD	Shield or functional earth
Thread		FE	Functional earth (housing)

Table 7.3: Pin assignment BUS OUT

7.5 SSI

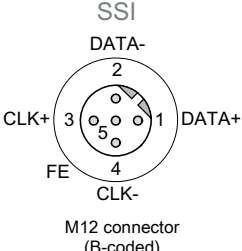
SSI (5-pin plug, B-coded)			
	Pin	Name	Comment
	1	DATA+	+ Data line SSI (output)
	2	DATA-	- Data line SSI (output)
	3	CLK+	+ Clock line SSI (input electrically insulated)
	4	CLK-	- Clock line SSI (input electrically insulated)
	5	FE	Functional earth
Thread		FE	Functional earth (housing)

Table 7.4: SSI pin assignment

7.6 Service

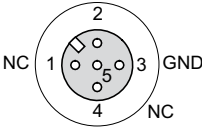
Service (5-pin socket, A-coded)			
SERVICE RS232-TX  NC 1 3 GND RS232-RX M12 socket (A-coded)	Pin	Name	Comment
	1	NC	Not assigned
	2	RS232-TX	Transmission line RS 232/service data
	3	GND	Voltage supply 0VDC
	4	RS232-RX	Receiving line RS 232/service data
	5	NC	Not used
	Thread	FE	Functional earth (housing)

Table 7.5: Pin assignment - Service



Note!
The service interface is designed only for use by Leuze!

8 Display and control panel AMS 304i

8.1 Structure of the control panel

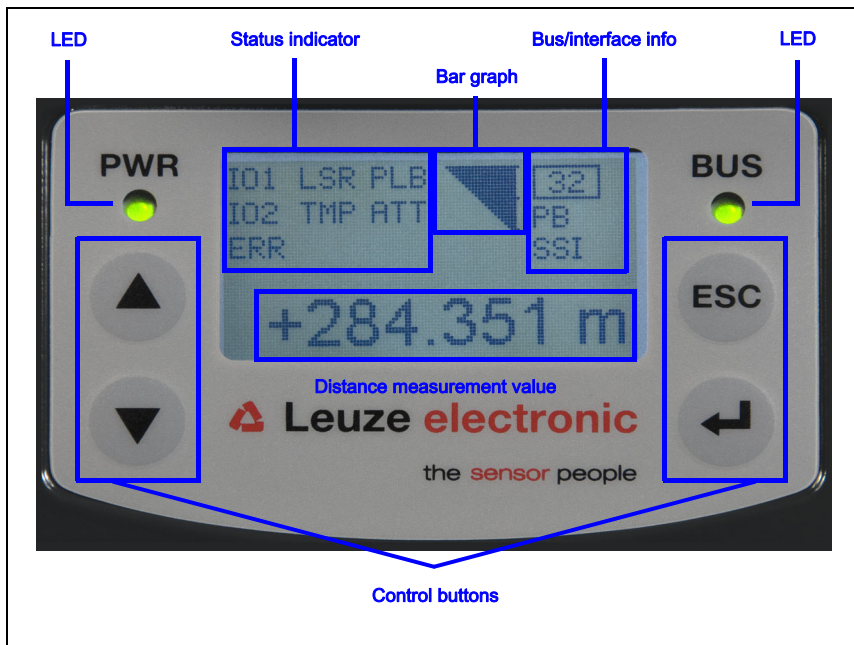


Figure 8.1: Structure of the control panel using the AMS 304i/PROFIBUS device variant as an example



Note!

The figure is for illustration purposes only and does not correspond to the AMS 304i with respect to specified bus/interface info.

8.2 Status indicators and operation

8.2.1 Indicators in the display

Status and warning messages in the display

- IO1 **Input 1 or output 1 active:**
Function depending on configuration. See also module 4/5.
- IO2 **Input 2 or output 2 active:**
Function depending on configuration. See also module 4/5

- LSR Warning - laser prefailure message:**
Laser diode old, device still functional, exchange or have repaired.
- TMP Warning - temperature monitoring:**
Internal device temperature above/below permissible range.
- PLB Plausibility error:**
Implausible measurement value. Possible causes: light beam interruption, outside of measurement range, permissible internal device temperature considerably exceeded or traverse rate >10m/s.
Depending on the configuration, either zero or the last valid measurement value is output at the interfaces.
- ATT Warning - received signal:**
Laser exit window or reflector soiled or fogged by rain, water vapor or fog. Clean or dry surfaces.
- ERR Internal hardware error:**
The device must be sent in for inspection.

Bar graph



Indicates the **strength of the received laser light**.

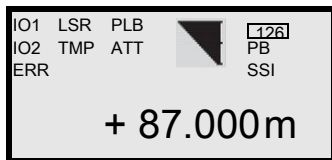
The center bar represents the **ATT** warning threshold. The distance value remains valid and is output at the interfaces.

If no bar graph is available, the **PLB** status information appears at the same time.

The measurement value is assessed as implausible. Depending on the configuration, either zero or the last valid measurement value is output at the interfaces.

Interface info

The set bus address ("126" in the figure) as well as the "PB" identifier indicate an activated PROFIBUS interface. The abbreviation "SSI" stands for an activated SSI interface.



← Bus address
Activated interfaces

← Position value

Position value

The measured position value is displayed in the configured unit of measurement.

- +87.000m** With the **metric** setting, the measurement value is always displayed in meters to **three decimal places**.
- +87.0in** With the **inch** setting, the measurement value is always displayed in inches to **one decimal place**.

8.2.2 LED status indicators

PWR LED

PWR



Off

Device OFF

- No supply voltage

PWR



Flashing green

Power LED flashes green

- No measurement value output
- Voltage connected
- Self test running
- Initialization running
- Parameter download running
- Boot process running

PWR



Green continuous light

Power LED green

- AMS 304/OK
- Measurement value output
- Self test successfully finished
- Device monitoring active

PWR



Red flashing

Power LED flashes red

- Device OK but warning message (ATT, TMP, LSR) set in display
- Light beam interruption
- Plausibility error (PLB)

PWR



Red continuous light

Power LED red

- No measurement value output; for details, see display

PWR



Orange continuous light

Power LED orange

- Parameter enable active
- No data on the host interface

BUS LED

BUS



Off

BUS LED off

- No supply voltage (Power)
- PROFIBUS deactivated? - SSI interface active!

BUS 	Green continuous light	BUS LED green - AMS 304<i>i</i> PROFIBUS communication active, bus OK
BUS 	Flashing green	BUS LED flashes green - AMS 304<i>i</i> not on the bus
BUS 	Flashing red	BUS LED flashes red - Configuration failed ("parameter failure") - DP error - No data exchange
BUS 	Red continuous light	BUS LED red - Bus failure, no DP protocol to the master established ("no data exchange")

8.2.3 Control buttons

	Up	Navigate upward/sideways.
	Down	Navigate downward/sideways.
	ESC	Exit menu item.
	ENTER	Confirm/enter value, change menu levels.

Navigating within the menus

The menus within a level are selected with the up/down buttons  .

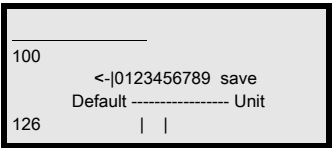
The selected menu item is activated with the enter button .

Press the ESC button  to move up one menu level.

When one of the buttons is actuated, the display illumination is activated for 10 min.

Setting values

If input of a value is possible, the display looks like this:



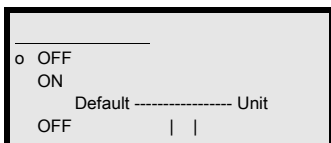
-  +  Delete character
-  ...  +  Enter digit
- save** +  Save

Use the   and  buttons to set the desired value. An accidental, incorrect entry can be corrected by selecting  and then pressing .

Then use the   buttons to select save and save the set value by pressing .

Selecting options

If options can be selected, the display looks like this:

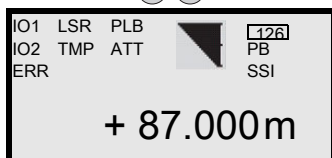
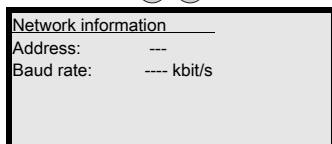
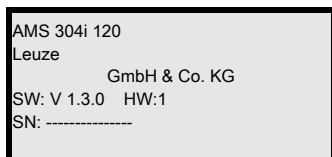


Select the desired option with the   buttons. Activate the option by pressing .

8.3 Menu description

8.3.1 The main menus

After voltage has been applied to the laser, device information is displayed for several seconds. The display then shows the measurement window with all status information.



Device information - main menu

This menu item contains detailed information on

- Device type
- Manufacturer
- Software and hardware version
- Serial number

No entries can be made via the display.

Network information - main menu

- Explanations of address and baud rate.

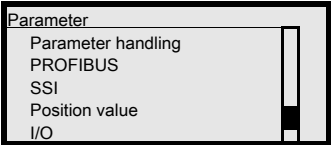
No entries can be made via the display.

Status and measurement data - main menu

- Display of status, warning and error messages.
- Status overview of the switching inputs/outputs
- Bar graph for the received signal level.
- Link
- Measurement value

No entries can be made via the display.

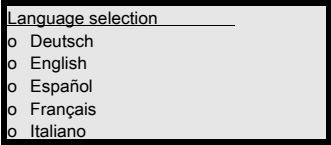
See "Indicators in the display" on page 41.



Parameter - main menu

- Configuration of the AMS.

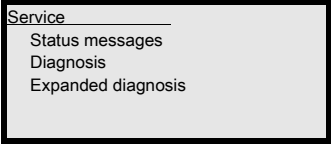
See "Parameter menu" on page 46.



Language selection - main menu

- Selection of the display language.

See "Language selection menu" on page 51.



Service - main menu

- Display of status messages.
- Display of diagnostic data.

No entries can be made via the display.
See "Service menu" on page 51.



Note!
*The rear cover of this manual includes a **fold-out page** with the complete **menu structure**. It describes the menu items in brief.*

8.3.2 Parameter menu

Parameter handling submenu

The following functions can be called up in the Parameter handling submenu:

- Lock and enable parameter entry
- Set up a password
- Reset the AMS 304*i* to the default settings

Table 8.1: Parameter handling submenu

Level 3	Level 4	Level 5	Selection/configuration option Description	Standard
Parameter enable			ON/OFF The standard setting (OFF) prevents unintended parameter changes. With parameter enable activated (ON), the display is inverted. In this state, it is possible to change parameters manually.	OFF
Password	Activate password		ON/OFF To enter a password, parameter enable must be activated. If a password is assigned, changes to the AMS 304 <i>i</i> can only be made after the password is entered. The master password 2301 overrides the individually set password.	OFF
	Password entry		For setting a four-digit numerical password.	

Table 8.1: Parameter handling submenu

Level 3	Level 4	Level 5	Selection/configuration option Description	Standard
Parameters to default			By pressing the enter button  after selecting Parameters to default, all parameters are reset to their standard settings without any further security prompts. In this case, English is selected as the display language.	

Additional important information on parameter handling can be found at the end of the chapter.

PROFIBUS submenu

Tabelle 8.2: PROFIBUS submenu

Level 3	Level 4	Level 5	Selection/configuration option Description	Standard
Activation			ON/OFF Activates or deactivates the AMS 304 <i>i</i> as a PROFIBUS participant.	ON
Address			Value from 0 to 126 The PROFIBUS permits an address range from 0 to 126. Address 126 must not be used for data communication. It may only be used temporarily for commissioning. The default address is 126. The address must be assigned individually for each AMS 304 <i>i</i> .	126

SSI submenu

Tabelle 8.3: SSI submenu

Level 3	Level 4	Level 5	Selection/configuration option Description	Standard
Activation			ON/OFF Activates or deactivates the AMS 304 <i>i</i> as an SSI participant.	ON
Encoding			Binary/gray Specifies the output format of the measurement value.	Gray
Number of data bits			24-bit/25-bit/26-bit The measurement value can be represented on the SSI interface in this data width.	24 bit
SSI resolution			0.001 mm / 0.01 mm / 0.1 mm / 1 mm / 10 mm / free resolution The measurement value can be displayed in these resolutions. The value of the free resolution is determined in the "Position value" submenu in the "Free resolution value" parameter.	0.1 mm
Error bit			ON/OFF This parameter determines whether an error bit is also attached to the "number of data bits". The error bit is the LSB and is not converted in the case of gray representation of the measurement value.	ON

Tabelle 8.3: SSI submenu

Level 3	Level 4	Level 5	Selection/configuration option Description	Standard
Error bit function			The error bit can be assigned the following status messages: Overflow / Intensity (ATT) / Temperature (TMP) / Laser (LSR) / Plausibility (PLB) / Hardware (ERR). In the case of multiple entries, the individual states in the error bit are processed in an OR function.	Plausibility (PLB) Hardware (ERR)
Update rate			1.7 / 0.2ms	1.7
Clock frequency			50 - 79kHz / 80 - 800kHz Selection of the clock frequency.	80 - 800kHz

Position value submenu

Table 8.4: Position value submenu

Level 3	Level 4	Level 5	Selection/configuration option Description	Standard
Unit			Metric/Inch Specifies the units of the measured distances	Metric
Counting direction			Positive/Negative Positive: The measurement value begins at 0 and increases with increasing distance. Negative: The measurement value begins at 0 and decreases with increasing distance. Negative distance values may need to be compensated with an offset or preset.	Positive
Offset			Output value = measurement value + offset The resolution of the offset value is independent of the selected "Position resolution" and is entered in mm or inch/100. The offset value is effective immediately after entry. If the preset value is activated, this has priority over the offset. Preset and offset are not offset against each other.	0 mm
Preset			The preset value is accepted by means of teach pulse. The teach pulse can be applied to a hardware input of the M12 PWR connector. The hardware input must be appropriately configured. See also configuration of the I/Os.	0 mm
Free resolution value			The measurement value can be resolved in increments of 1/1000 within the 5 ... 50000 value range. If e.g. a resolution of 0.875mm per digit is required, the parameter is set to 875. In the activated interface, the measurement value display must also be set to "Free resolution" ("SSI resolution" parameter).	1000
Error delay			ON/OFF Specifies whether, in the event of an error, the position value immediately outputs the value of the "Position value in the case of failure" parameter or the last valid position value for the configured error delay time.	ON/100 ms
Position value in the case of failure			Last valid value / zero Specifies which position value is output after the error delay time elapses.	Zero

I/O submenu

Table 8.5: I/O submenu

Level 3	Level 4	Level 5	Selection/configuration option Description	Standard
I/O 1	Port configuration		Input/Output Defines whether I/O 1 functions as an output or input.	Output
	Switching input	Function	No function/teach preset/laser ON/OFF	No function
		Activation	Low active/High active	Low active
	Switching output	Function	Pos. limit value 1 / Pos. limit value 2 / Velocity / Intensity (ATT) / Temp. (TMP) / Laser (LSR) / Plausibility (PLB) / Hardware (ERR) The individual functions are "ORed" on the selected switching output.	Plausibility (PLB), hardware (ERR)
		Activation	Low active/High active	Low active
I/O 2	Port configuration		Input/Output Defines whether I/O 2 functions as an output or input.	Output
	Switching input	Function	No function/teach preset/laser ON/OFF	No function
		Activation	Low active/High active	Low active
	Switching output	Function	Pos. limit value 1 / Pos. limit value 2 / Velocity / Intensity (ATT) / Temp. (TMP) / Laser (LSR) / Plausibility (PLB) / Hardware (ERR) The individual functions are "ORed" on the selected switching output.	Intensity (ATT), Temp. (TMP), Laser (LSR)
		Activation	Low active/High active	Low active
Limit values	Upper pos. limit 1	Activation	ON/OFF	OFF
		Limit value input	Value input in mm or inch/100	0
	Lower pos. limit 1	Activation	ON/OFF	OFF
		Limit value input	Value input in mm or inch/100	0
	Upper pos. limit 2	Activation	ON/OFF	OFF
		Limit value input	Value input in mm or inch/100	0
	Lower pos. limit 2	Activation	ON/OFF	OFF

Table 8.5: I/O submenu

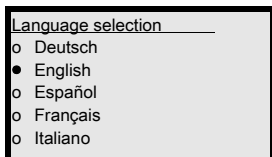
Level 3	Level 4	Level 5	Selection/configuration option Description	Standard
		Limit value input	Value input in mm or inch/100	0
	Max. velocity	Activa- tion	ON/OFF	OFF
		Max. velocity	Value input in mm/s or inch/100s	0

Other submenu

Table 8.6: Other submenu

Level 3	Level 4	Level 5	Selection/configuration option Description	Standard
Heating control			Standard (10°C ... 15°C)/Extended (30°C ... 35°) Defines a switch-on/switch-off range for the heating control. The extended switch-on/switch-off range for heating may provide a remedy in the event of condensation problems. Due to the limited heating capacity, it cannot be guaranteed that no condensation will form on the optics in the extended switch-on/switch-off range. This parameter is available as standard, but functions only for devices with integrated heating (AMS 304 <i>i</i> ... H).	Standard
Display illumination			10 minutes/ON Display illumination is switched off after 10 minutes or, if the parameter is set to "ON", illumination is always on.	10min
Display contrast			Weak/Medium/Strong The display contrast may change at extreme temperature values. The contrast can subsequently be adapted using the three levels.	Medium
Service RS232	Baud rate		57.6kbit/s / 115.2kbit/s The service interface is only available to Leuze personnel.	115.2kbit/s
	Format		8,e,1 / 8,n,1 The service interface is only available to Leuze personnel.	8,n,1

8.3.3 Language selection menu



5 display languages are available:

- German
- English
- Spanish
- French
- Italian

The AMS 304*i* is delivered from the factory with the display preset to English.

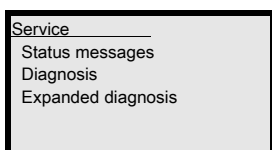


Note!

*When operating the AMS 304*i* on the PROFIBUS, the language configured in the GSD file is used in the display.*

To change the language, no password needs to be entered nor must parameter enable be active. The display language is a passive operational control and is therefore not a function parameter per se.

8.3.4 Service menu



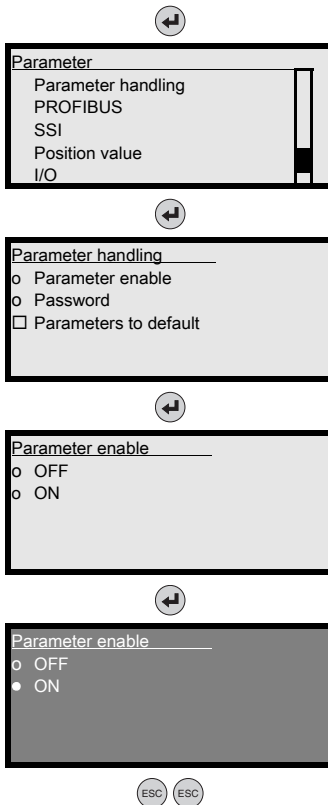
A detailed description of the individual functions can be found in Chapter 11.

8.4 Operation

An operating process is described here using parameter enable as an example.

Parameter enable

During normal operation parameters can be viewed only. If parameters are to be changed, the ON menu item in the Parameter -> Parameter handling -> Parameter enable menu must be activated. To do this, proceed as follows.



In the main menu, press the enter button to enter the Parameter menu.

Use the ▲▼ buttons to select the Parameter handling menu item.

Press the enter button to enter the Parameter handling menu.

In the Parameter handling menu, use the ▲▼ buttons to select the Parameter enable menu item.

Press the enter button to enter the Parameter enable menu.

In the Parameter enable menu, use the ▲▼ buttons to select the ON menu item.

Press the enter button to activate parameter enable.

The PWR LED lights up orange; the display is inverted. You can now set the individual parameters on the display.

Press the ESC button twice to return to the Parameter menu.



Viewing and editing parameters

As long as parameter enable is active, the entire AMS 304/i display is inverted.

As long as parameter enable is active, communication between control and AMS 304/i is interrupted. The extended networking via BUS OUT is retained.

**Note!**

If a password was stored, parameter enable is not possible until this password is entered; see "Password for parameter enable" below.

**Note!**

Parameters which are defined in a GSD file have priority. After deactivation of parameter enable on the AMS 304i, the parameters defined in the control are reactivated. The address setting is not overwritten.

For the SSI interface, communication between the control and the AMS 304i is also active when parameter enable is active.

**Note!**

Changes to the SSI parameters via display entry have immediate effect.

Password for parameter enable

Parameter entry on the AMS 304i can be protected with a password. On the AMS 304i, the password is determined using the PROFIBUS GSD file. Therefore, the password cannot be changed by means of display entry.

To activate parameter enable via the display (e.g. for changing an address), the password defined in the GSD file must be entered. If parameter enable has been activated after successfully entering the password, parameters can be temporarily changed via the display. After parameter enable is deactivated, all changes made on the display are overwritten by the GSD file. This also applies to any new passwords that may have been assigned. Only a changed address remains unchanged after entry via the display.

**Note!**

The master password 2301 can enable the AMS 304i at any time.

9 PROFIBUS interface

9.1 General information on PROFIBUS

The AMS 304*i* is designed as a PROFIBUS DP device for cyclical (V0) as well as acyclic (V1) data exchange.

For this purpose, the functionality of the laser is defined via GSD parameter sets. The max. baud rate of the data to be transferred is 12Mbit/s.

The PROFIBUS interface can be used parallel to the SSI interface. The PROFIBUS and SSI interface are active by default.



Note!

The PROFIBUS interface can be activated/deactivated via the display. To activate / deactivate the interface, parameter enable must be activated (see Chapter 8.3.2). The active interface is shown in the display; if PROFIBUS is active, the set address is visible in the display.

9.2 PROFIBUS electrical connection

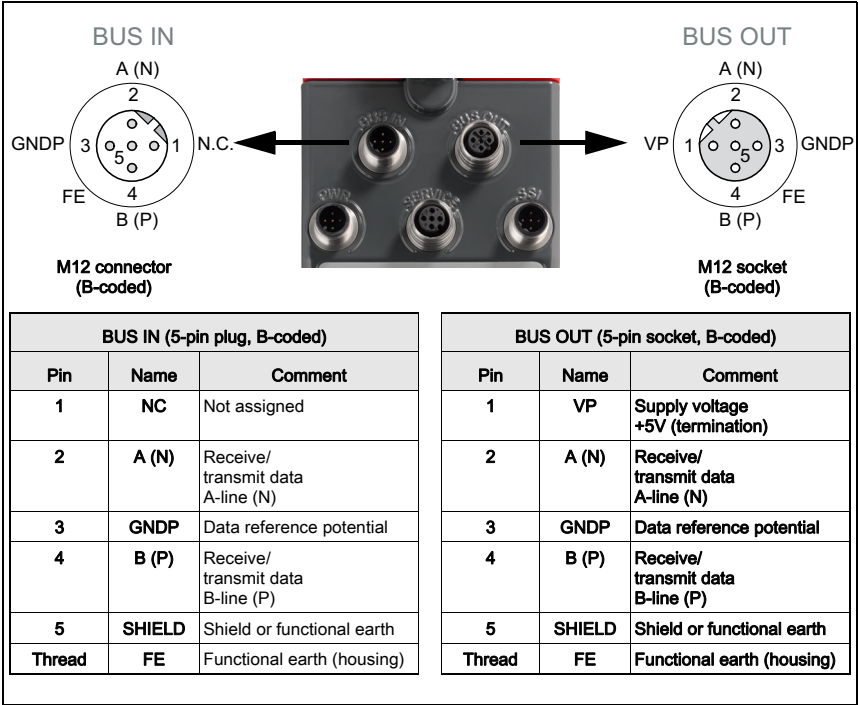


Figure 9.1: PROFIBUS electrical connection



Note!

For connecting **BUS IN** and **BUS OUT**, we recommend our ready-made PROFIBUS cables (see chapter 12.4.6 "Accessories - Ready-made cables for PROFIBUS").



Attention!

The laser measurement system can be used to branch out the PROFIBUS network. The **extended network** is connected via **BUS OUT**.

If the laser measurement system is the last subscriber in the network, the **BUS OUT** connection must be connected to a terminator plug; see "Accessories – Terminating resistor" on page 108.

9.3 PROFIBUS address entry



Note!

Basic operation of the control panel/display is described in Chapter 8.2. To set the address, parameter enable must be activated. The display is inverted.



Attention!

The laser measurement system is deactivated on the PROFIBUS when parameter enable is activated via the display. The device is reactivated on the PROFIBUS after parameter enable is canceled.

9.3.1 Entering the PROFIBUS addresses via the display

To do this proceed as follows:

- ✎ *Activate Parameter enable.*
- ✎ *Select the PROFIBUS submenu.*
- ✎ *Select the Address menu item [].*
- ✎ *Enter the PROFIBUS address of the laser measurement system; set to a value between 1 and 126 (default: 126).*
- ✎ *Deactivate parameter enable.*

9.4 PROFIBUS GSD file

9.4.1 General information about the GSD file

If the AMS 304*i* is operated in a PROFIBUS network, configuration must be performed exclusively via the PROFIBUS. The functionality of the laser measurement system is defined using modules. The parameters and their functions are structured in the GSD file using modules. Using a user-specific configuration tool, the respective required modules are integrated and configured according to the measurement application during PLC programming.

During operation of the laser measurement system on the PROFIBUS, all parameters are set to default values. If these values are not changed by the user, the device operates with the default settings set by Leuze electronic on delivery. Please refer to the following module descriptions for the default settings of the device.



Note!

*At least one module in the GSD file must be activated in the configuration tool for the control, usually the **Position value** module.*

**Note!**

Some controls make available a so-called "universal module". This module must not be activated for the AMS 304*i*.

**Attention!**

The AMS 304*i* provides a PROFIBUS interface and an SSI interface. Both interfaces can be operated in parallel. If the AMS 304*i* is operated via PROFIBUS, the SSI parameters must also be changed in the PROFIBUS SSI module if these parameters differ from the default settings.

The PROFIBUS manager overwrites SSI parameters, that are changed via the display only, with the SSI (default) values stored in the GSD file.

**Note!**

On a laser measurement system operated on the PROFIBUS, parameters can for test purposes be changed via the display. As soon as parameter enable is activated on the display, the device is deactivated on the PROFIBUS. All parameters set via PROFIBUS modules remain effective. Parameter changes can now be made via the display for test purposes. If parameter enable is deactivated again via the display, only the parameters set in the PROFIBUS modules and the PROFIBUS default settings are in effect.

Parameter changes made via the display are no longer in effect on the PROFIBUS!

**Attention!**

The laser measurement system does not permanently store parameters changed via the PROFIBUS. Following Power off/on, the currently configured parameters are downloaded from the PROFIBUS manager. If no PROFIBUS manager is available following Power OFF/ON, the parameters set on the display apply.

**Note!**

All input and output modules described in this documentation are described **from the viewpoint of the control**:

Inputs (I) described are inputs of the control.

Outputs (O) described are outputs of the control.

Parameters (P) described are parameters of the GSD file in the control.

**Note!**

You can find the current GSD file for the AMS 304*i* on our homepage at: www.leuze.com.

9.4.2 Overview of the GSD modules

Module	Module name	Module contents (P) = Parameter, (O) = Output, (I) = Input
M1 Page 61	Position value	(I) Position value (P) Sign (P) Unit (P) Resolution (P) Count direction (P) Offset
M2 Page 63	Static preset	(P) Preset value (O) Preset teach (O) Reset preset
M3 Page 64	Dynamic preset	(O) Preset value (O) Preset teach (O) Reset preset
M4 Page 65	I/O 1	(P) Definition whether output or input (P) Level/edge input/output (P) Function for output wiring (P) Function for input wiring (I) Signal level input/output (O) Output activated
M5 Page 68	I/O 2	(P) Definition whether output or input (P) Level/edge input/output (P) Function for output wiring (P) Function for input wiring (I) Signal level input/output (O) Output activated
M6 Page 71	Status and control	(I) Diagnosis and status of AMS 304 / (O) Laser control ON/OFF
M7 Page 73	Position limit value 1	(P) Upper and lower position limit value
M8 Page 74	Position limit value 2	(P) Upper and lower position limit value
M9 Page 75	Error handling procedures	(P) Position value in case of error (P) Position error message delay ON/OFF (P) Position error message delay (P) Velocity value in case of error (P) Velocity error message delay ON/OFF (P) Velocity error message delay
M10 Page 77	Velocity	(I) Velocity value (P) Velocity value resolution (P) Velocity response time

M11 Page 79	Velocity Limit value 1	(P) Monitoring for over/under values
		(P) Monitoring direction-dependent yes/no
		(P) Velocity limit value 1
		(P) Hysteresis of velocity limit value
		(P) Start of velocity monitoring range
		(P) End of velocity monitoring range
M12 Page 81	Velocity Limit value 2	(P) Monitoring for over/under values
		(P) Monitoring direction-dependent yes/no
		(P) Velocity limit value 2
		(P) Hysteresis of velocity limit value
		(P) Start of velocity monitoring range
		(P) End of velocity monitoring range
M13 Page 83	Velocity Limit value 3	(P) Monitoring for over/under values
		(P) Monitoring direction-dependent yes/no
		(P) Velocity limit value 3
		(P) Hysteresis of velocity limit value
		(P) Start of velocity monitoring range
		(P) End of velocity monitoring range
M14 Page 85	Velocity Limit value 4	(P) Monitoring for over/under values
		(P) Monitoring direction-dependent yes/no
		(P) Velocity limit value 4
		(P) Hysteresis of velocity limit value
		(P) Start of velocity monitoring range
		(P) End of velocity monitoring range
M15 Page 87	Velocity Limit value Dynamic	(O) Release/lock limit value control
		(P) Monitoring for over/under values
		(P) Monitoring direction-dependent yes/no
		(O) Dynamic velocity limit value
		(O) Hysteresis of velocity limit value
		(O) Start of velocity monitoring range
M16 Page 88	Velocity status	(O) End of velocity monitoring range
		(I) Status of velocity monitoring
M17 Page 90	SSI interface	(P) Gray/binary coding
		(P) Number of data bits
		(P) Resolution
		(P) Update rate
		(P) Function of error bit
M18 Page 93	Other	(P) Display language selection
		(P) Display illumination
		(P) Display contrast
		(P) Activate/inhibit password
		(P) Password
		(P) Heating control
M19	–	–
M20 Page 95	Free resolution	(P) Position resolution
		(P) Velocity resolution

Table 9.1: Overview of the GSD modules

9.4.3 Detailed description of the modules



Note!

*In the following detailed descriptions of the modules, you will find in the last column of the tables **cross references (CR) to parameters and input/output data of other modules** which are directly related to the described parameter. **It is essential to observe these cross-references during configuration.***

*The individual **modules** are numbered from **1 ... 20**.*

*The **parameters and input/output data** within a module are labeled from **a ... z**.*

Example:

The **a Preset** parameter in module 2 becomes active only when the preset teach occurs via module 2b, 4d or 5d.

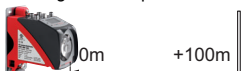
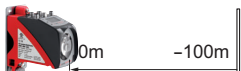
9.4.3.2 Module 1: Position value

Description

Outputs the current position value.

The parameters for sign, unit, resolution, counting direction and offset remain adjustable.

Parameter

Parameter	Description	Rel. addr.	Data type	Value range	Default	Unit		CR to module
						Metr.	Inch	
a Sign	Output mode of the sign. Sign affects position and velocity output	0.0	Bit	0: Two's complement 1: Sign + magnitude	0	–		–
b Unit	Selection of the unit ¹⁾ . The parameter applies to all values with units. The parameter applies to all interfaces	0.1	Bit	0: metric 1: Inch (in)	0	–		–
c Resolution	Resolution of the position value applies only to the PROFIBUS output. The resolution has no effect on: • Static preset • Dynamic preset • Offset The SSI interface has a separate parameter for resolution.	0.2 ... 0.4	Bit	001=1: 0.001 010=2: 0.01 011=3: 0.1 100=4: 1 101=5: 10 110= free resolution	4	mm	in/100	20a
d Counting direction	Counting direction positive:  Counting direction negative:  The parameter applies to all interfaces. The counting direction changes the sign during velocity measurement. No negative position values can be transmitted on the SSI interface. In this case, the value 0 is output on the SSI interface. An appropriate offset must be selected such that only positive values are transmitted.	0.5	Bit	0: Positive 1: Negative	0	–		–

e	Output value=measurement value+offset The parameter applies to all inter- faces. Attention: If the preset is activated, it has priority over the offset. Preset and offset are not offset against each other. The resolution of the offset value is independent of the resolution selected in module 1. The entered offset applies imme- diately without any further release.	1 - 4	sign 32 bits	-999999 ... +999999	0	mm	in/100	-
Offset								
Parameter length: 6 bytes								

1) See following notice!



Note!
If the **unit is changed from metric to inch** (or vice versa), **previously entered numerical values** (e.g. for offset, preset, limit values, etc.) **are not automatically converted**. This must be done manually!

Example:
Preset = 10000mm -> Change from metric to inch -> Preset = 10000 inch/100

Hex coding of the "Position value" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Sign Unit Resolution Counting direction	Offset
01	10	00 00 00 00

Input data

Input data	Description	Rel. addr	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
f Position value	Output of the current position.	0	sign 32 bits	-999999 ... +999999	–	Scaled		9a
Input data length: 4 bytes consistently								

Output data

None

9.4.3.3 Module 2: Static preset

Description

With this module, a preset value can be specified. The specified preset value becomes active in the position in which preset teaching is performed.



Note!

In the event of a device change, the preset value is retained in the PROFIBUS manager. The preset value (preset teach) must, however, be activated again at the intended position.

Parameter

[illegible]

Hex coding of the "Preset value" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Preset value
02	00 00 00 00

Input data

None

Output data

Output data	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
b Preset teach	Read in the preset value.	0.0	Bit	0→1 Preset teach	–	–		4d 5d
c Preset reset	Preset value is deactivated.	0.1	Bit	0→1 Preset reset	–	–		4d 5d

Output data length: 1 byte

9.4.3.4 Module 3: Dynamic preset

Description

With this module, a preset value can be specified. The specified preset value becomes active in the position in which preset teaching is performed. The preset value can be adjusted within the control to meet plant requirements without intervening in the static parameter structure.

Parameter

None

Input data

None

Output data

Output data	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Preset teach	Read in the preset value.	0.0	Bit	0→1 Preset teach	–	–		4d 5d
b Preset reset	Preset value is deactivated. Output value = measurement value+offset.	0.1	Bit	0→1 Preset reset	–	–		4d 5d
c Preset	The value is accepted during a corresponding teach event. The output data affects all interfaces. The resolution of the preset value is independent of the resolution selected in module 1.	1	sign 32 bits	-999999 ... +999999	–	mm	in/100	3a 4d 5d
Output data length: 5 byte								

9.4.3.5 Module 4: I/O 1 Input/Output

Description

The module defines the mode of operation of the digital input/output I/O 1.

Parameter

Parameter	Description	Rel. addr	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Function	The parameter defines whether I/O 1 functions as an input or as an output.	0.0	Bit	0: Input 1: Output	1	–		4cd
b Activation	The parameter defines the level of the output at which the "Output" event occurs. If I/O 1 is configured as an input, the response is edge-triggered.	0.1	Bit	0: Low 1-0 transition 1: High 0-1 transition	0	–		–
c Output	The parameter defines which event triggers activation of the output. The individual functions are OR-linked to one another					–		4a
	Position limit value 1 If the position value is outside of configured limit range 1, the output is set.	1.0	Bit	0 = OFF 1 = ON	0	–		
	Position limit value 2 If the position value is outside of configured limit range 2, the output is set.	1.1	Bit	0 = OFF 1 = ON	0	–		
	Velocity limit value If the velocity value is outside of the configured values, the output is set. Monitoring from modules 11 to 15 is OR-linked.	1.2	Bit	0 = OFF 1 = ON	0	–		
	Intensity (ATT) If the intensity of the received signal is less than the warning threshold, the output is set.	1.3	Bit	0 = OFF 1 = ON	0	–		
	Temperature (TMP) If the internal device temperature exceeds the set limit value, the output is set.	1.4	Bit	0 = OFF 1 = ON	0	–		
	Laser (LSR) Laser prefailure message.	1.5	Bit	0 = OFF 1 = ON	0	–		
	Plausibility (PLB) If implausible measurement values are diagnosed, the output is set.	1.6	Bit	0 = OFF 1 = ON	1	–		

c	Hardware (ERR) If a hardware error is diagnosed, the output is set.	1.7	Bit	0 = OFF 1 = ON	1	–	4a
	Pseudodynamic output If bit 0.0 is set in the output data, the output is set.	2.0	Bit	0 = OFF 1 = ON	0	–	
d	Preset The HW input is used as the pre-set teach input (valid for static or dynamic preset). Laser The HW input is used as laser OFF.	3.0 ... 3.2	unsign 8Bit	000 =HW input no function 001 =HW input as preset teach function 010 =HW input as laser OFF function	000	–	4a

Parameter length: 4 bytes

Hex coding of the "I/O 1 input/output" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Function Activation	Position limit value 1 Position limit value 2 Velocity limit value Intensity (ATT) Temperature (TMP) Laser (LSR) Plausibility (PLB) Hardware (ERR) Pseudodynamic output	Preset / laser input
04	01	00 C0	00



Note!

Behaviour of the AMS 304*i* with laser ON/OFF:

If the laser light spot is positioned on the reflector when the laser diode is switched on, the AMS 304*i* returns valid measurement values after approx. 330ms.

If the laser light spot is not positioned on the reflector when the laser diode is switched on, the AMS 304*i* cannot calculate any distance values. If the laser beam hits the reflector at a later point in time while switched on, the AMS 304*i* 200 returns valid measurement values after the following time span:

t = (measurement distance / 20m) sec.

Example: Aisle change of a high-bay storage device during which the laser diode is not switched off while traveling around curves.

Measurement distance 100m → t = 5sec., measurement distance 200m → t = 10sec.

Input data

Input data	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
e State	Signal state of the input or output.	0.0	Bit	0: Input/output inactive at signal level 1: Input/output active at signal level	–	–		–
Input data length: 1 byte								

Output data

Output data	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
f State	The output can be activated/de-activated with this bit. The corresponding release is performed in module 4, output parameter bit 2.0.	0.0	Bit	0: Output not active at signal level 1: Output active at signal level	–	–		4c
Output data length: 1 byte								

9.4.3.6 Module 5: I/O 2 Input/Output

Description

The module defines the mode of operation of the digital input/output I/O 2.

Parameter

Parameter	Description	Rel. addr	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Function	The parameter defines whether I/O 2 functions as an input or as an output.	0.0	Bit	0: Input 1: Output	1	–		5cd
b Activation	The parameter defines the level of the output at which the "Output" event occurs. If I/O 2 is configured as an input, the response is edge-triggered.	0.1	Bit	0: Low 1-0 transition 1: High 0-1 transition	0	–		–
c Output	The parameter defines which event triggers activation of the output. The individual functions are OR-linked to one another					–		5a
	Position limit value 1 If the position value is outside of configured limit range 1, the output is set.	1.0	Bit	0 = OFF 1 = ON	0	–		
	Position limit value 2 If the position value is outside of configured limit range 2, the output is set.	1.1	Bit	0 = OFF 1 = ON	0	–		
	Velocity limit value If the velocity value is outside of the configured values, the output is set. Monitoring from modules 11 to 15 is OR-linked.	1.2	Bit	0 = OFF 1 = ON	0	–		
	Intensity (ATT) If the intensity of the received signal is less than the warning threshold, the output is set.	1.3	Bit	0 = OFF 1 = ON	1	–		
	Temperature (TMP) If the internal device temperature exceeds the set limit value, the output is set.	1.4	Bit	0 = OFF 1 = ON	1	–		
	Laser (LSR) Laser prefailure message.	1.5	Bit	0 = OFF 1 = ON	1	–		
	Plausibility (PLB) If implausible measurement values are diagnosed, the output is set.	1.6	Bit	0 = OFF 1 = ON	0	–		

c Output	Hardware (ERR) If a hardware error is diagnosed, the output is set.	1.7	Bit	0 = OFF 1 = ON	0	–	5a
	Pseudodynamic output If bit 0.0 is set in the output data, the output is set.	2.1	Bit	0 = OFF 1 = ON	0	–	
d Input	Preset The HW input is used as the pre-set teach input (valid for static or dynamic preset). Laser The HW input is used as laser OFF.	3.0 ... 3.2	unsign 8Bit	000 =HW input no function 001 =HW input as preset teach function 010 =HW input as laser OFF function	000	–	5a
Parameter length: 4 bytes							

Hex coding of the "I/O 2 input/output" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Function Activation	Position limit value 1 Position limit value 2 Velocity limit value Intensity (ATT) Temperature (TMP) Laser (LSR) Plausibility (PLB) Hardware (ERR) Pseudodynamic output	Preset / laser input
05	01	00 38	00



Note!

Behaviour of the AMS 304*i* with laser ON/OFF:

If the laser light spot is positioned on the reflector when the laser diode is switched on, the AMS 304*i* returns valid measurement values after approx. 330ms.

If the laser light spot is not positioned on the reflector when the laser diode is switched on, the AMS 304*i* cannot calculate any distance values. If the laser beam hits the reflector at a later point in time while switched on, the AMS 304*i* returns valid measurement values after the following time span:

$t = (\text{measurement distance} / 20\text{m}) \text{ sec.}$

Example: Aisle change of a high-bay storage device during which the laser diode is not switched off while traveling around curves.
Measurement distance 100m → t = 5sec., measurement distance 200m → t = 10sec.

Input data

Input data	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
e State	Signal state of the input or output.	0.0	Bit	0: Input/output inactive at signal level 1: Input/output active at signal level	–	–		–
Input data length: 1 byte								

Output data

Output data	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
f State	The output can be activated/de-activated with this bit. The corresponding release is performed in module 5, output parameter bit 2.1.	0.0	Bit	0: Output not active at signal level 1: Output active at signal level	–	–		5c
Output data length: 1 byte								

9.4.3.7 Module 6: Status and control

Description

This module supplies the PROFIBUS master with various AMS 304 status information. The laser can be controlled via the master's output data.

Parameter

None

Input data

Input data	Description	Rel. addr	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Laser status	Signals the laser status.	1.0	Bit	0: Laser ON 1: Laser OFF	–	–		–
b Preset status	State of the preset value.	1.1	Bit	0: Preset not active 1: Preset active	–	–		–
c Preset teach	This bit toggles at each teach event of a preset value.	1.2	Bit	0 or 1	–	–		–
d Overflow	The output value exceeds the value that can be represented on the SSI interface. If an overflow occurs, the data of the SSI interface is set to 0xFF.	1.3	Bit	0: OK 1: Overflow	–	–		–
e Intensity (ATT)	If the intensity of the received signal is less than the warning threshold, the status bit is set.	1.4	Bit	0: OK 1: Warning	–	–		–
f Temperature (TMP)	If the internal device temperature exceeds or drops below the set limit value, the status bit is set.	1.5	Bit	0: OK 1: Temperature above/below limit	–	–		–
g Laser (LSR)	Laser prefailure message.	1.6	Bit	0: OK 1: Laser warning	–	–		–
h Plausibility (PLB)	If implausible measurement values are diagnosed, the status bit is set.	1.7	Bit	0: OK 1: Implausible measurement values	–	–		–
i Hardware (ERR)	If a hardware error is diagnosed, the status bit is set.	0.0	Bit	0: OK 1: Hardware error	–	–		–
j Lower position limit value 1	Signals that the value is less than lower limit value 1.	0.4	Bit	0: OK 1: Value less than limit	–	–		–
k Upper position limit value 1	Signals that the value is greater than upper limit value 1.	0.5	Bit	0: OK 1: Value greater than limit	–	–		–

l Lower position limit value 2	Signals that the value is less than lower limit value 2.	0.6	Bit	0: OK 1: Value less than limit	-	-	-
m Upper position limit value 2	Signals that the value is greater than upper limit value 2.	0.7	Bit	0: OK 1: Value greater than limit	-	-	-
Input data length: 2 byte							

Output data

Output data	Description	Rel. addr	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
n Laser	Actuation of the laser.	0.0	Bit	0: Laser ON 1: Laser OFF	-	-		-
Output data length: 2 bytes								

9.4.3.8 Module 7: Position limit value range 1

Description

The Position limit value range 1 parameter defines a distance range with lower and upper limit. If the measured value is outside the configured range, the corresponding bit is set in module 6 or, if configured, an output is set.

Parameter

Parameter	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
^a Lower pos. limit 1	Specifies the lower position limit.	0...3	sign 32 bits	-999999 ... +999999	0	mm	in/ 100	–
^b Upper pos. limit 1	Specifies the upper position limit.	4...7	sign 32 bits	-999999 ... +999999	0	mm	in/ 100	–
Parameter length: 8 bytes								

Hex code of the "Position limit value range 1" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Lower pos. limit 1	Upper pos. limit 1
07	00 00 00 00	00 00 00 00

Input data

None

Output data

None

9.4.3.9 Module 8: Position limit value range 2

Description

The Position limit value range 2 parameter defines a distance range with lower and upper limit. If the measured value is outside the configured range, the corresponding bit is set in module 6 or, if configured, an output is set.

Parameter

Parameter	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
^a Lower pos. limit 2	Specifies the lower position limit.	0...3	sign 32 bits	-999999 ... +999999	0	mm	in/100	–
^b Upper pos. limit 2	Specifies the upper position limit.	4...7	sign 32 bits	-999999 ... +999999	0	mm	in/100	–
Parameter length: 8 bytes								

Hex code of the "Position limit value range 2" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Lower pos. limit 2	Upper pos. limit 2
08	00 00 00 00	00 00 00 00

Input data

None

Output data

None

9.4.3.10 Module 9: Error handling procedures

Description

The module makes parameters available to handle any errors should they occur.

In the event of a temporary error in the value/velocity calculation (e.g. plausibility error caused by light beam interruption), the laser measurement system transmits the last valid measurement value for a configured length of time xx.

If the configured time is exceeded, the error display or the error measurement value output is activated.

Parameter

Parameter	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Position value in the case of failure	Specifies which position value is to be output in the event of an error after the position suppression time has elapsed.	0.0	Bit	0: Last valid value 1: Zero	1	mm	In/100	–
	No function.	0.1	Bit	always 0	0	–	–	–
b Suppress position status	Specifies whether the PLB status bit is set immediately in the event of an error or if it is suppressed for the configured position suppression time.	0.2	Bit	0: OFF 1: ON	1	–	–	–
c Error delay (position)	Specifies in the event of an error whether the position value immediately outputs the value of the "Position value in the case of failure" parameter or outputs the last valid position value for the duration of the configured "error delay time".	0.3	Bit	0: OFF 1: ON	1	–	–	–
d Error delay time (position)	Errors which occur are suppressed for the configured time. If no valid position value can be ascertained during the configured time, the last valid position value is output. If the error persists after the time elapses, the value stored in the "Position value in the case of failure" parameter is output.	1...2	unsigned 16 bit	100 ... 1000	100	ms	–	–
e Velocity in the case of failure	Specifies which velocity is to be output in the event of an error after the velocity suppression time has elapsed.	3.0	Bit	0: Last valid value 1: Zero	1	–	–	–
	No function.	3.1	Bit	always 0	0	–	–	–
f Suppress velocity status	Specifies whether the PLB status bit is set immediately in the event of an error or if it is suppressed for the configured velocity suppression time.	3.2	Bit	0: OFF 1: ON	1	–	–	–

q Error delay (velocity)	Specifies in the event of an error whether the velocity immediately outputs the value of the "Velocity in the case of failure" parameter or outputs the last valid velocity for the duration of the configured "error delay time".	3.3	Bit	0: OFF 1: ON	1	-	-
h Error delay time (velocity)	Errors which occur are suppressed for the configured time. If no valid velocity value can be ascertained during the configured time, the last valid velocity value is output. If the error persists after the time elapses, the value stored in the "Velocity in the case of failure" parameter is output.	4...5	unsigned 16Bit	200 ... 1000	200	ms	-
Parameter length: 6 bytes							

Hex coding of the "Error handling procedures" parameter (position and velocity)

The value listed in the table shows the hex coding of the default settings:

Module address	Position value in the case of failure Suppress position status Error delay (position)	Position suppression time	Velocity output in the case of failure Suppress velocity status Error delay (velocity)	Velocity suppression time
09	C0	00 64	C0	00 C8

Input data

None

Output data

None

9.4.3.11 Module 10: Velocity

Description

Outputs the current velocity with the configured resolution. The unit (metric or inch) is set in module 1 (position value) and also applies to the velocity. If module 1 is not configured, the AMS 304*i* operates with the default unit (metric).

The sign of the velocity is dependent on the counting direction in module 1d.

In the default setting, a positive velocity is output when the reflector moves away from the AMS 304*i*. When the reflector moves toward the AMS 304*i*, negative velocities are output. If the "negative" counting direction is configured in module 1, the velocity sign is reversed.

Measurement value preparation averages all velocity values calculated during the selected period to yield a velocity value.

Parameter

Parameter	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Velocity resolution	The parameter specifies the resolution for the velocity value.	0.0 ... 0.2	Bit	001=1: 1 010=2: 10 011=3: 100 100=4: 1000 101 = 5: free resolution	1	mm/s	(in/100)/s	20
b Averaging	The parameter specifies the response time (averaging time) of the calculated velocity values.	0.3 ... 0.5	Bit	000=0: 2 001=1: 4 010=2: 8 011=3: 16 100=4: 32 101=5: 64 110=6: 128	3	ms		—
Parameter length: 2 bytes								

Hex coding of the "Velocity" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Velocity resolution Averaging
0A	00 19

Input data

Input data	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
C Velocity	Current velocity.	0	sign 32 bits	-999999 ... +999999	0	Scaled		-

Input data length: 4 bytes consistently

Output data

None

9.4.3.12 Module 11: Static velocity limit value 1

Description

The **static velocity limit value 1** function compares the current velocity with a velocity stored in the configuration. This occurs in the configured range, which is defined by **range start** and **range end**.



Note!

*If **range start** and **range end** are identical, velocity monitoring is active over the entire traversing range.*

If a direction-dependent limit value check is activated via the **Direction selection** parameter, the values of **range start** and **range end** also define the direction. The check is always performed from **range start** to **range end**. For example, if the range start is "5500" and the range end is "5000", the direction-dependent check is only performed in the direction from "5500" to "5000". The limit value is not active in the opposite direction.

If the check is independent of direction, the order of **range start** and **range end** is irrelevant. Depending on the selected **switching type**, if the value is above or below the defined limits, the limit value status in module 16 is set and, if configured, the output is appropriately set via module 4 or 5.

Parameter

Parameter	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Switching type	Condition for the "Velocity limit value 1" signal, which applies to the output (module 4/5) and the status bit (module 16).	0.0	Bit	0: Value greater than limit 1: Value less than limit	0	–		–
b Direction selection	Selection of the direction-dependent or direction-independent limit value check.	0.1	Bit	0: Direction independent 1: Direction dependent	0	–		–
c Velocity limit value 1	Limit value is compared to the current velocity.	1...2	unsign 16 bit	0 ... 20000	0	mm/s	(in/ 100) /s	16d
d Velocity hysteresis 1	Relative shift to prevent signal bouncing.	3...4	unsign 16 bit	0 ... 20000	100	mm/s	(in/ 100) /s	–
e Limit value 1 range start	The velocity limit value is monitored beginning at this position.	5...8	sign 32 bits	-999999 ... +999999	0	mm	in/ 100	–
f Limit value 1 range end	The velocity limit value is monitored up to this position.	9 ... 12	sign 32 bits	-999999 ... +999999	0	mm	in/ 100	–
Parameter length: 13 bytes								

Hex coding of the "Static velocity limit value 1" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Switching type Direction selection	Velocity limit value 1	Velocity hysteresis 1	Limit value 1 range start	Limit value 1 range end
0B	00	00 00	00 64	00 00 00 00	00 00 00 00

Input data

None

Output data

None

9.4.3.13 Module 12: Static velocity limit value 2

Description

The **static velocity limit value 2** function compares the current velocity with a velocity stored in the configuration. This occurs in the configured range, which is defined by **range start** and **range end**.



Note!

If **range start** and **range end** are identical, velocity monitoring is active over the entire traversing range.

If a direction-dependent limit value check is activated via the **Direction selection** parameter, the values of **range start** and **range end** also define the direction. The check is always performed from **range start** to **range end**. For example, if the range start is "5500" and the range end is "5000", the direction-dependent check is only performed in the direction from "5500" to "5000". The limit value is not active in the opposite direction.

If the check is independent of direction, the order of **range start** and **range end** is irrelevant. Depending on the selected **switching type**, if the value is above or below the defined limits, the limit value status in module 16 is set and, if configured, the output is appropriately set via module 4 or 5.

Parameter

Parameter	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Switching type	Condition for the "Velocity limit value 2" signal, which applies to the output (module 4/5) and the status bit (module 16).	0.0	Bit	0: Value greater than limit 1: Value less than limit	0	–		–
b Direction selection	Selection of the direction-dependent or direction-independent limit value check.	0.1	Bit	0: Direction independent 1: Direction dependent	0	–		–
c Velocity limit value 2	Limit value is compared to the current velocity.	1...2	unsign 16 bit	0 ... 20000	0	mm/s	(in/100)/s	16e
d Velocity hysteresis 2	Relative shift to prevent signal bouncing.	3...4	unsign 16 bit	0 ... 20000	100	mm/s	(in/100)/s	–
e Limit value 2 range start	The velocity limit value is monitored beginning at this position.	5...8	sign 32 bits	-999999 ... +999999	0	mm	in/100	–
f Limit value 2 range end	The velocity limit value is monitored up to this position.	9 ... 12	sign 32 bits	-999999 ... +999999	0	mm	in/100	–
Parameter length: 13 bytes								

Hex coding of the "Static velocity limit value 2" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Switching type Direction selection	Velocity limit value 2	Velocity hysteresis 2	Limit value 2 range start	Limit value 2 range end
0C	00	00 00	00 64	00 00 00 00	00 00 00 00

Input data

None

Output data

None

9.4.3.14 Module 13: Static velocity limit value 3

Description

The **static velocity limit value 3** function compares the current velocity with a velocity stored in the configuration. This occurs in the configured range, which is defined by **range start** and **range end**.



Note!

If **range start** and **range end** are identical, velocity monitoring is active over the entire traversing range.

If a direction-dependent limit value check is activated via the **Direction selection** parameter, the values of **range start** and **range end** also define the direction. The check is always performed from **range start** to **range end**. For example, if the range start is "5500" and the range end is "5000", the direction-dependent check is only performed in the direction from "5500" to "5000". The limit value is not active in the opposite direction.

If the check is independent of direction, the order of **range start** and **range end** is irrelevant. Depending on the selected **switching type**, if the value is above or below the defined limits, the limit value status in module 16 is set and, if configured, the output is appropriately set via module 4 or 5.

Parameter

Parameter	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Switching type	Condition for the "Velocity limit value 3" signal, which applies to the output (module 4/5) and the status bit (module 16).	0.0	Bit	0: Value greater than limit 1: Value less than limit	0	–		–
b Direction selection	Selection of the direction-dependent or direction-independent limit value check.	0.1	Bit	0: Direction independent 1: Direction dependent	0	–		–
c Velocity limit value 3	Limit value is compared to the current velocity.	1...2	unsign 16 bit	0 ... 20000	0	mm/s	(in/ 100) /s	16f
d Velocity hysteresis 3	Relative shift to prevent signal bouncing.	3...4	unsign 16 bit	0 ... 20000	100	mm/s	(in/ 100) /s	–
e Limit value 3 range start	The velocity limit value is monitored beginning at this position.	5...8	sign 32 bits	-999999 ... +999999	0	mm	in/ 100	–
f Limit value 3 range end	The velocity limit value is monitored up to this position.	9 ... 12	sign 32 bits	-999999 ... +999999	0	mm	in/ 100	–
Parameter length: 13 bytes								

Hex coding of the "Static velocity limit value 3" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Switching type Direction selection	Velocity limit value 3	Velocity hysteresis 3	Limit value 3 range start	Limit value 3 range end
0D	00	00 00	00 64	00 00 00 00	00 00 00 00

Input data

None

Output data

None

9.4.3.15 Module 14: Static velocity limit value 4

Description

The **static velocity limit value 4** function compares the current velocity with a velocity stored in the configuration. This occurs in the configured range, which is defined by **range start** and **range end**.



Note!

*If **range start** and **range end** are identical, velocity monitoring is active over the entire traversing range.*

If a direction-dependent limit value check is activated via the **Direction selection** parameter, the values of **range start** and **range end** also define the direction. The check is always performed from **range start** to **range end**. For example, if the range start is "5500" and the range end is "5000", the direction-dependent check is only performed in the direction from "5500" to "5000". The limit value is not active in the opposite direction.

If the check is independent of direction, the order of **range start** and **range end** is irrelevant. Depending on the selected **switching type**, if the value is above or below the defined limits, the limit value status in module 16 is set and, if configured, the output is appropriately set via module 4 or 5.

Parameter

Parameter	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Switching type	Condition for the "Velocity limit value 4" signal, which applies to the output (module 4/5) and the status bit (module 16).	0.0	Bit	0: Value greater than limit 1: Value less than limit	0	–		–
b Direction selection	Selection of the direction-dependent or direction-independent limit value check.	0.1	Bit	0: Direction independent 1: Direction dependent	0	–		–
c Velocity limit value 4	Limit value is compared to the current velocity.	1...2	unsign 16 bit	0 ... 20000	0	mm/s	(in/ 100) /s	16g
d Velocity hysteresis 4	Relative shift to prevent signal bouncing.	3...4	unsign 16 bit	0 ... 20000	100	mm/s	(in/ 100) /s	–
e Limit value 4 range start	The velocity limit value is monitored beginning at this position.	5...8	sign 32 bits	-999999 ... +999999	0	mm	in/ 100	–
f Limit value 4 range end	The velocity limit value is monitored up to this position.	9 ... 12	sign 32 bits	-999999 ... +999999	0	mm	in/ 100	–
Parameter length: 13 bytes								

Hex coding of the "Static velocity limit value 4" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Switching type Direction selection	Velocity limit value 4	Velocity hysteresis 4	Limit value 4 range start	Limit value 4 range end
0E	00	00 00	00 64	00 00 00 00	00 00 00 00

Input data

None

Output data

None

9.4.3.16 Module 15: Dynamic velocity limit value

Description

The **dynamic velocity limit value** function compares the current velocity with a stored velocity within the defined range. If the value is above or below the limit value, the dynamic limit value status in module 16 is set and, if configured, the output is appropriately set. **Limit value**, **hysteresis**, **range start** and **range end** are transferred with the output data of this module by the PROFIBUS master. The transferred values are activated by **Bit 0.0**, i.e. if this bit is set, the AMS 304*i* compares the current velocity with the new limit value conditions.



Note!

If **range start** and **range end** are identical, velocity monitoring is active over the entire traversing range.

Parameter

None

Input data

None

Output data

Output data	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Limit value control	Controls internal processing of the transferred dynamic limit value parameters.	0.0	Bit	0: Do not process 1: Process parameter	–	–	–	–
b Switching type	Condition for the signal change of the output/status bit.	0.1	Bit	0: Value greater than limit 1: Value less than limit	–	–	–	–
c Direction selection	Selection of the direction-dependent or direction-independent limit value check.	0.2	Bit	0: Direction independent 1: Direction dependent	–	–	–	–
d Velocity limit value	Limit value is compared to the current velocity.	1...2	unsign 16 bit	0 ... +20000	–	mm/s	(in/100)/s	16h
e Velocity hysteresis	Relative shift to prevent signal bouncing.	3...4	unsign 16 bit	0 ... +20000	–	mm/s	(in/100)/s	–
f Limit value range start	The velocity limit value is monitored beginning at this position.	5...8	sign 32 bits	-999999 ... +999999	0	mm	in/100	–
g Limit value range end	The velocity limit value is monitored up to this position.	9...12	sign 32 bits	-999999 ... +999999	0	mm	in/100	–
Output data length: 13 bytes consistently								

9.4.3.17 Module 16: Velocity status

Description

This module supplies the PROFIBUS master with various status information for velocity measurement.

Parameter

None

Input data

Input data	Description	Rel. addr	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Velocity measurement error	Signals that no valid velocity could be ascertained.	1.0	Bit	0: OK 1: Error	–	–		–
b Movement status	Signals whether a movement > 0.1 m/s is currently being detected.	1.1	Bit	0: No movement 1: Movement	–	–		–
c Direction of movement	When the movement status is activated, this bit indicates the direction.	1.2	Bit	0: Positive direction 1: Negative direction	–	–		–
d Velocity limit value status 1	Signals that limit value 1 has been exceeded.	1.3	Bit	0: Limit value maintained 1: Limit value violated	–	–		11c
e Velocity limit value status 2	Signals that limit value 2 has been exceeded.	1.4	Bit	0: Limit value maintained 1: Limit value violated	–	–		12c
f Velocity limit value status 3	Signals that limit value 3 has been exceeded.	1.5	Bit	0: Limit value maintained 1: Limit value violated	–	–		13c
g Velocity limit value status 4	Signals that limit value 4 has been exceeded.	1.6	Bit	0: Limit value maintained 1: Limit value violated	–	–		14c
h Dynamic velocity limit value status	Signals that the dynamic limit value has been exceeded.	1.7	Bit	0: Limit value maintained 1: Limit value violated	–	–		15bd
i Velocity comparison Limit value 1	Signals whether the current velocity is compared with this limit value.	0.3	Bit	0: Comparison not active 1: Comparison active	–	–		–
j Velocity comparison Limit value 2	Signals whether the current velocity is compared with this limit value.	0.4	Bit	0: Comparison not active 1: Comparison active	–	–		–
k Velocity comparison Limit value 3	Signals whether the current velocity is compared with this limit value.	0.5	Bit	0: Comparison not active 1: Comparison active	–	–		–

l Velocity comparison Limit value 4	Signals whether the current velocity is compared with this limit value.	0.6	Bit	0: Comparison not active 1: Comparison active	–	–	–
m Dynamic velocity comparison	Signals whether the current velocity is compared with this limit value.	0.7	Bit	0: Comparison not active 1: Comparison active	–	–	–
Input data length: 2 byte							

Output data
None

9.4.3.18 Module 17: SSI interface

Description

The module defines the parameters for the SSI interface.



Attention!

The SSI interface can only represent positive distance values. If negative output values are ascertained due to the offset or counting direction, a zero value is output at the SSI interface! In the event of a number overflow, all data bits are set to "1".

The **Unit**, **Offset** and **Counting direction** parameters of module 1 also apply to the SSI interface.



Note!

If the SSI interface is not configured via module 17 (SSI interface) in PROFIBUS operation, the SSI interface is operated with the default parameters.

If the SSI interface is operated without PROFIBUS (PROFIBUS OFF/SSI ON), configuration is performed via the display.

Parameter

Parameter	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Encoding	The parameter defines the coding of the SSI data.	0.0	Bit	0: Binary 1: Gray	1	–		–
b Mode	The parameter defines the number of data bits.	0.1 ... 0.2	Bit	00=0: 24Bit 01=1: 25 bits 10=2: 26bits	0	–		–
c Resolution	The parameter defines the resolution of the SSI position value.	0.3 ... 0.5	Bit	001=1: 0.001 010=2: 0.01 011=3: 0.1 100=4: 1 101=5: 10 110=6: free resolution	3	mm	in/ 100	1b 6d 19a
d Update rate	The parameter defines the update rate of the measurement values on the SSI interface. The measurement value is updated independent of the clock frequency.	0.6	Bit	0: 1.7 ms 1: 0.2 ms	0	ms		–
e Clock frequency		0.7	Bit	0: 80kHz - 800kHz monoflop time 20us 1: 50kHz - 79 kHz monoflop time 30us	0			
f Error bit Attention! The attached error bit always has the following significance: 0: No error 1: Error	Error bit off/on The parameter defines the meaning of the error bit. If the error bit is OFF, no bit is attached to the data. The remaining bits 1 to 6 activate the various events which affect the error bit. The bits are OR-linked to each other.	1.0	Bit	0: OFF 1: ON	1	–		–
	Overflow Output value exceeds the maximum value which can be represented. In the event of an overflow, all data bits are set to 1.	1.1	Bit	0: OFF 1: ON	0	–		–
	Intensity (ATT) If the intensity of the received signal is less than the warning threshold, the bit is set.	1.2	Bit	0: OFF 1: ON	0	–		–
	Temperature (TMP) Maximum internal device temperature exceeded.	1.3	Bit	0: OFF 1: ON	0	–		–
	Laser (LSR) Laser prefailure message.	1.4	Bit	0: OFF 1: ON	0	–		–
	Plausibility (PLB) Plausibility error.	1.5	Bit	0: OFF 1: ON	1	–		–
	Hardware (ERR) Hardware error.	1.6	Bit	0: OFF 1: ON	1	–		–
Parameter length: 2 bytes								

Hex coding of the "SSI interface" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Encoding Mode Resolution Update rate	Error bits
11	19	61

Input data

None

Output data

None



Note!

Resolution and maximum position value which can be represented:

SSI setting	Max. distance which can be represented Metric	Max. distance which can be represented Inch (in)	
24 bits; resolution 0.1	1,677 m	16,777 in	≈ 426m
24 bits; resolution 0.01	167 m	1,677 in	≈ 42m
24 bits; resolution 0.001	16 m	167 in	≈ 4m
25 bits; resolution 0.1	3,355 m	33,554 in	≈ 852m
25 bits; resolution 0.01	335 m	3,355 in	≈ 85m
25 bits; resolution 0.001	33 m	335 in	≈ 8m
26 bits; resolution 0.1	6,710 m	67,108 in	≈ 1,704m
26 bits; resolution 0.01	671 m	6,710 in	≈ 170m
26 bits; resolution 0.001	67 m	671 in	≈ 17m

Figure 9.19:SSI interface - resolution and maximum position value which can be represented

9.4.3.20 Module 18: module for display language, display illumination, display contrast, password, heating control

Description

Parameters for general operation are set in this module.

Parameter

Parameter	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Language selection	Language selection for the display. A language preselected via the display is overwritten by this parameter.	0.0 ... 0.2	Bit	000=0: English 001=1: German 010=2: Italian 011=3: Spanish 100=4: French	0	–		–
b Display illumination	Off after 10 min. or always on.	0.3	Bit	0: Off after 10 min. 1: Always on	0	–		–
c Display contrast	Contrast setting of the display. The contrast changes under extreme ambient temperatures and can be adjusted with this parameter.	0.4 ... 0.5	Bit	000=0: Weak 001=1: Medium 010=2: Strong	1	–		–
d Password protection	Password protection on/off.	0.7	Bit	0: OFF 1: ON	0	–		–
e Password	Specifies the password. Password protection must be on.	1...2	unsign 16 bit	0000 ... 9999	0000	–		–
f Heating control	Defines a switch-on/switch-off range for the heating control. The extended switch-on/switch-off range for heating may provide a remedy in the event of condensation problems. Due to the limited heating capacity, it cannot be guaranteed that no condensation will form on the optics in the extended switch-on/switch-off range. This parameter is available as standard, but functions only for devices with integrated heating (AMS 304/... H).	3.0	Bit	0 = Standard T _{amb.} < 10°C: heating on T _{amb.} > 15°C: heating off 1 = Extended T _{amb.} < 30°C: heating on T _{amb.} > 35°C: heating off	0	–		–
Parameter length: 4 bytes								

Hex coding of the "Other" parameter

The value listed in the table shows the hex coding of the default settings:

Module address	Language Display illumination Display contrast Password protection	Password
12	10	00

Input data

None

Output data

None

9.4.3.21 Module 20: Free resolution

Description

Free resolution is used when the resolutions set in the standard are not suitable. If a free resolution is used, this must be activated in module 10a.

Module 10a and module 1c must be set to enable the free resolution to be configured.

Parameter

Parameter	Description	Rel. addr.	Data type	Value	Default	Unit		CR to module
						Metr.	Inch	
a Position free resolution	This module allows the output measurement values for position and velocity to be freely scaled.	0 ... 1	unsign 16 bit	5 ... 50000	1000	mm/10 ³	in/10 ⁵	1c
b Velocity free resolution	The parameters apply to all interfaces for which the "free resolution" resolution has been selected. The internal measurement value is multiplied by the set value based on (mm/1000). Example: Value "3000" means that in the event of a change in the measurement value by 3 mm, the position value in the binary code changes by binary 1. Due to the free resolution in the example, an internal measurement value of 3333mm gives an output value of "1111". The resolution of the "Offset", "Preset" and "Limit values" parameters is not affected by the free resolution.	2 ... 3	unsign 16 bit	5 ... 50000	1000	(mm/10 ³)/s	(in/10 ⁵)/s	10a
Parameter length: 4 bytes								

10 SSI

10.1 Principal functionality of the SSI interface

Data communication of the SSI interface is based on differential transmission as is used for RS 422 interfaces. The position value is transmitted in sync with a clock cycle (CLOCK) specified by the control, starting with the most significant bit (MSB).

In the idle state, both the clock line as well as the data line are at HIGH level. At the first HIGH-LOW edge (point ① in Figure 10.1), the data in the internal register is stored. This ensures that the data are not changed during serial transfer of the value.

When the next clock signal change from LOW to HIGH level (point ② in Figure 10.1) occurs, transmission of the position value begins with the most significant bit (MSB). With each subsequent change of the clock signal from LOW to HIGH level, the next least-significant bit is transmitted on the data line. After the least significant bit (LSB) has been output, the clock signal switches from LOW to HIGH for one last time and the data line switches to LOW level (end of transmission).

A monoflop retriggered by the clock signal determines the time span before the SSI interface can be called for the next transmission. This results in the minimum pause time between two successive clock cycles. If time $t_m = 20\mu s$ has elapsed, the data line is returned to the quiescent level (HIGH) (point ③ in Figure 10.1). This signals completed data communication and that the device is again ready for transmission.



Note!

If the off-cycle of data transmission is interrupted for longer than $t_m = 20\mu s$, the next cycle will begin with a completely new transmission cycle with a newly calculated value.

If a new transmission cycle is started before time t_m elapses, the previous value is output again.



Attention!

The SSI interface can only represent positive distance values. If negative output values are ascertained due to the offset or counting direction, a zero value is output at the SSI interface! In the event of a number overflow, all data bits are set to "1".

10.1.1 SSI sequence diagram

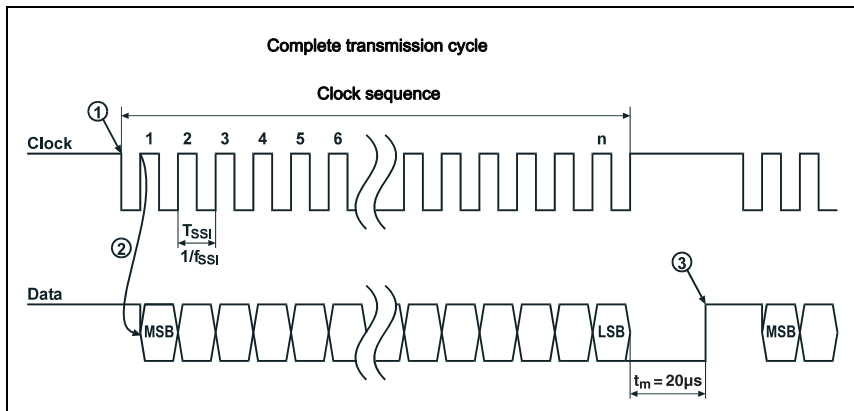


Figure 10.1: SSI data transmission sequence diagram



Note!

In the default setting, the **LSB** bit is the error bit.



Attention!

Significance of the error bit:

By default, a 25th error bit (LSB) is appended to the 24-bit measurement value. The error bit is not included in the Gray encoding of the measurement value. The error bit is 1 = active, 0 = not active.



Note!

The data can be read out at a clock rate between 80kHz and 800kHz.



Attention!

Updating the measurement values on the SSI interface of the AMS 304i:

The measurement value on the SSI interface of the AMS 304i is updated approx. every 1.7ms (default) irrespective of the clock frequency. The update rate on the interface can be reduced to 0.2ms via the display under the SSI menu item or in PROFIBUS module 17. The shorter update rate is only valid for the SSI interface and has no influence on the PROFIBUS DP interface.

10.1.2 Cable length depending on the data rate

Only shielded and twisted pair cables (pin 1 with 2 and pin 3 with 4) are permitted as data lines for the SSI interface (see chapter 10.2 "SSI - electrical connection").

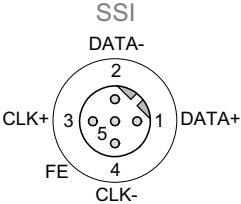
- ↗ *The shielding must be connected at both ends.*
- ↗ *Do not lay the cable parallel to power cables.*

The maximum possible cable length is dependent on the cable used and the clock rate:

Data rate	80 kBit/s	100 kBit/s	200 kBit/s	300 kBit/s	400 kBit/s	500 kBit/s	1.000 kBit/s
Max. cable length (typical)	500m	400m	200m	100m	50m	25 m	10 m

Table 10.1: Max. cable length as a function of the clock rate

10.2 SSI - electrical connection



SSI connector (5-pin plug, B-coded)		
Pin	Name	Comment
1	DATA+	+ Data line SSI (output)
2	DATA-	- Data line SSI (output)
3	CLK+	+ Clock line SSI (input electrically insulated)
4	CLK-	- Clock line SSI (input electrically insulated)
5	FE	Functional earth
Thread	FE	Functional earth (housing)

Figure 10.2:SSI - electrical connection



Note!
To connect the SSI interface, we recommend our ready-made SSI cables; see "Accessories - Ready-made cables for PROFIBUS" on page 109.

10.3 General Information on the AMS 304/i parameters



Attention!

Using the PROFIBUS and SSI interface simultaneously:

The SSI interface settings are performed by the PROFIBUS. If settings which differ from the default settings for the parameters are to be used, they must be configured via module 17 (SSI interface).

Using the SSI interface without PROFIBUS:

For this operating mode, deactivate the PROFIBUS via the display (PROFIBUS = OFF).

Default parameters are stored in the laser measurement system to enable sole use of the SSI interface. The preset default parameters can be changed at any time via the display.

This also applies when using parameters which do not relate directly to the SSI interface (for example: I/O 1 or I/O 2, Position value or Other).

The SSI interface remains active even during parameter enable. Changes to parameters have an immediate effect.

10.4 Default settings of the SSI interface

Default parameters which apply only to the SSI interface.	
SSI activation	ON
Measurement value coding	Gray
Transmission mode	24-bit measurement value + 1-bit error (error: 1 = active), error bit = LSB
Resolution	0.1 mm
Default error bit	Plausibility error or hardware error
Update rate	1.7 ms
Default parameters which apply to both PROFIBUS and SSI.	
Unit	metric
Counting direction	Positive (the SSI interface cannot represent negative values)
I/O 1	Output – plausibility error or hardware error
I/O 2	Output – temperature error, intensity error or laser prefailure message
Static preset	+000,000
Dynamic preset	+000,000
Position limit value range 1	Lower limit and upper limit: both 0
Position limit value range 2	Lower limit and upper limit: both 0
Error handling procedures	Position output: 0
	Suppress position status: active
	Position suppression time: 100 ms
Display language	English
Display illumination	OFF after 10 min.
Display contrast	Medium
Password protection	Off
Password	0000

Table 10.2: Default settings of the SSI interface

10.4.1 Changing the SSI settings via the display

**Note!**

For basic operation of the display, please refer to Chapter 8.2.3.

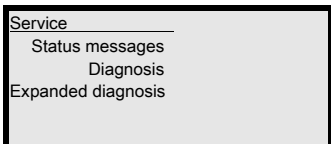
In order to change the parameters, please activate parameter enable.

The SSI interface remains active even during parameter enable. Changes to parameters have an immediate effect.

11 Diagnostics and troubleshooting

11.1 Service and diagnosis in the display of the AMS 304/

In the main menu of the AMS 304/, expanded "Diagnostics" can be called up under the Service heading.



From the Service main menu, press the enter button (↵) to access the underlying menu level.

Use the up/down buttons (▲ ▼) to select the corresponding menu item in the selected level; use the enter button (↵) to activate the selection.

Return from any sub-level to the next-higher menu item by pressing the ESC button (⏮).

11.1.1 Status messages

The status messages are written in a ring memory with 25 positions. The ring memory is organized according to the FIFO principle. No separate activation is necessary for storing the status messages. Power OFF clears the ring memory.



Basic representation of the status messages

n: Type / No. / 1

Meaning:

n: memory position in the ring memory

Type: type of message:

I = info, **W** = warning, **E** = error, **F** = severe system error.

No: internal error detection

1: frequency of the event (always "1" because no summation occurs)

The status messages within the ring memory are selected with the up/down buttons (▲ ▼). Use the enter button (↵) to call up **detailed information** about the respective status message:

Detailed information about a status message

Type: type of message + internal counter
UID: Leuze-internal coding of the message
ID: description of the message
Info: not currently used

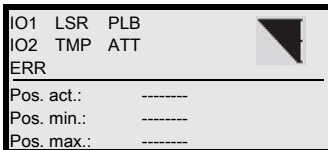
Within the detailed information, press the enter button  again to activate an **action menu** with the following functions:

- Acknowledge message
- Delete message
- Acknowledge all
- Delete all

11.1.2 Diagnosis

The diagnostics function is activated by selecting the Diagnostics menu item. The ESC button  deactivates the diagnostics function and clears the contents of the recordings.

The recorded diagnostic data is displayed in 2 fields. In the upper half of the display, status messages of the AMS and the bar graph are displayed. The lower half contains information used for Leuze-internal evaluation.



IO1	LSR	PLB
IO2	TMP	ATT
ERR		
Pos. act.:	-----	
Pos. min.:	-----	
Pos. max.:	-----	

Use the up/down buttons   to scroll in the bottom half between various displays. The contents of the scrollable pages are intended solely for Leuze for internal evaluation.

The diagnostics have no influence on communication with the host interface and can be activated during operation of the AMS 304*/*.

11.1.3 Expanded diagnosis

The Expanded diagnosis menu item is used for Leuze-internal evaluation.

11.2 General causes of errors

11.2.1 Power LED

See also Chapter 8.2.2.

Error	Possible error cause	Measure
PWR LED "OFF"	No supply voltage connected	Check supply voltage.
	Hardware error	Send in device.
PWR LED "flashes red"	Light beam interruption	Check alignment.
	Plausibility error	Traverse rate >10m/s.
PWR LED "static red"	Hardware error	For error description, see display, It may be necessary to send in the device.

Table 11.1: General causes of errors

11.3 Interface errors

11.3.1 BUS LED

Error	Possible error cause	Measure
BUS LED "OFF" (No communication via PROFIBUS)	No supply voltage connected	Check supply voltage.
	Incorrect wiring	Check wiring.
	Wrong termination	Check termination.
	Incorrect PROFIBUS address	Check PROFIBUS address.
	PROFIBUS deactivated	Activate PROFIBUS in the AMS 304 <i>i</i> .
	Configuration error	Check configuration.
BUS LED "flashes red"	Communication error: Configuration failed ("parameter failure") DP Error: no data exchange	• Check configuration. • Carry out a reset on the control.
BUS LED "red" (sporadic error at the PROFIBUS)	Incorrect wiring	Check wiring.
	Wrong termination	Check termination.
	Effects due to EMC	• Check shielding. • Check grounding concept and connection to FE. • Avoid EMC coupling caused by power cables laid parallel to device lines.
	Overall network expansion exceeded	Check max. network expansion as a function of the set baud rate.

Table 11.2: Bus error

11.4 Status indicators in the display of the AMS 304*i*

Display	Possible error cause	Measure
PLB (implausible measurement values)	Laser beam interruption	Laser spot must always be incident on the reflector.
	Laser spot outside of reflector	Traverse rate < 10m/s?
	Measurement range for maximum distance exceeded	Restrict traversing path or select AMS with larger measurement range.
	Velocity greater than 10m/s	Reduce velocity.
	Ambient temperature far outside permissible range (TMP display; PLB)	Select AMS with heating or ensure cooling.
ATT (insufficient received signal level)	Reflector soiled	Clean reflector or glass lens.
	Glass lens of the AMS soiled	
	Performance reduction due to snow, rain, fog, condensing vapor or heavily polluted air (oil mist, dust)	Optimize usage conditions.
	Laser spot only partially on reflector	Check alignment.
TMP (operating temperature outside of specification)	Protective film on reflector	Remove protective film from reflector.
	Ambient temperatures outside specified range	In case of low temperatures, remedy may be an AMS with heating. If temperatures are too high, provide cooling or change mounting location.
LSR Laser diode warning	Laser diode prefailure message	Send in device at next possible opportunity to have laser diode replaced. Have replacement device ready.
ERR Hardware error	Indicates an uncorrectable error in the hardware	Send in device for repair.

Service hotline:

You can find the contact information for the hotline in your country on our website www.leuze.com under "Contact & Support".

Repair service and returns:

Defective devices are repaired at our service centers competently and quickly. We offer you an extensive service packet to keep any system downtimes to a minimum. Our service center requires the following information:

- Your customer number
- Product description or part description
- Serial number and batch number
- Reason for requesting support together with a description

For this purpose, please register the merchandise concerned. Simply register return of the merchandise on our website www.leuze.com under Contact & Support -> Repair Service & Returns:

To ensure quick and easy processing of your request, we will send you a returns order with the returns address in digital form.

**Note!**

Please use Chapter 11 as a master copy should servicing be required.

Cross the items in the "Measures" column which you have already examined, fill out the following address field and fax the pages together with your service contract to the fax number listed below.

Customer data (please complete)

Device type:	
Company:	
Contact person/department:	
Phone (direct dial):	
Fax:	
Street / no.:	
ZIP code / City:	
Country:	

Leuze Service fax number:

+49 7021 573 - 199

12 Type overview and accessories

12.1 Part number code

AMS 3xx /	yyy	H
	Heating option	H = With heating
	Operating range	40 Max. operating range in m
		120 Max. operating range in m
		200 Max. operating range in m
		300 Max. operating range in m
		i = Integrated fieldbus technology
	Interface	00 RS 422/RS 232
		01 RS 485
		04 PROFIBUS DP / SSI
		08 TCP/IP
		35 CANopen
		38 EtherCAT
		48 PROFINET RT
		55 DeviceNet
		58 EtherNet/IP
		84 Interbus

AMS Absolute Measurement System

12.2 Overview of AMS 304/ types (PROFIBUS)

Type designation	Description	Part no.
AMS 304/40	40m operating range, PROFIBUS/SSI interface	50113677
AMS 304/120	120m operating range, PROFIBUS/SSI interface	50113678
AMS 304/200	200m operating range, PROFIBUS/SSI interface	50113679
AMS 304/300	300m operating range, PROFIBUS/SSI interface	50113680
AMS 304/40 H	40m operating range, PROFIBUS/SSI interface, integrated heating	50113681
AMS 304/120 H	120m operating range, PROFIBUS/SSI interface, integrated heating	50113682
AMS 304/200 H	200m operating range, PROFIBUS/SSI interface, integrated heating	50113683
AMS 304/300 H	300m operating range, PROFIBUS/SSI interface, integrated heating	50113684

Table 12.1: Overview of AMS 304/ types

12.3 Overview of reflector types

Type designation	Description	Part no.
REF 4-A-150x150	Reflective tape, 150x150mm, self-adhesive	50141015
Reflective tape 200x200-S	Reflective tape, 200x200mm, self-adhesive	50104361
REF 4-A-300x300	Reflective tape, 300x300mm, self-adhesive	50141014
Reflective tape 500x500-S	Reflective tape, 500x500mm, self-adhesive	50104362
Reflective tape 914x914-S	Reflective tape, 914x914mm, self-adhesive	50108988
Reflective tape 200x200-M	Reflective tape, 200x200mm, affixed to carrier plate	50104364
Reflective tape 500x500-M	Reflective tape, 500x500mm, affixed to carrier plate	50104365
Reflective tape 914x914-M	Reflective tape, 914x914mm, affixed to carrier plate	50104366
Reflective tape 200x200-H	Reflective tape, 200 x 200mm, heated	50115020
Reflective tape 500x500-H	Reflective tape, 500 x 500mm, heated	50115021
Reflective tape 914x914-H	Reflective tape, 914 x 914mm, heated	50115022

Table 12.2: Overview of reflector types

12.4 Accessories

12.4.1 Accessories – Mounting bracket

Type designation	Description	Part no.
MW OMS/AMS 01	Mounting bracket for mounting AMS 304/i to horizontal surfaces	50107255

Table 12.3: Accessories – Mounting bracket

12.4.2 Accessories – Deflector unit

Type designation	Description	Part no.
US AMS 01	Deflector unit with integrated mounting bracket for AMS 304/i. Variable 90° deflection of laser beam in different directions	50104479
US 1 OMS	Deflector unit without mounting bracket for simple 90° deflection of laser beam	50035630

Table 12.4: Accessories – Deflector unit

12.4.3 Accessories – M12 connector

Type designation	Description	Part no.
KD 02-5-BA	M12 connector, B-coded socket, BUS IN; SSI	50038538
KD 02-5-SA	M12 connector, B-coded plug, BUS OUT	50038537
KD 095-5A	M12 connector, A-coded socket, Power (PWR)	50020501

Table 12.5: Accessories – M12 connector

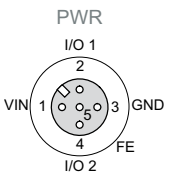
12.4.4 Accessories – Terminating resistor

Type designation	Description	Part no.
TS 02-4-SA	M12 terminating resistor for PROFIBUS BUS OUT	50038539

Table 12.6: Accessories – Terminating resistor

12.4.5 Accessories – Ready-made cables for voltage supply

Contact assignment/core color of PWR connection cable

PWR connection cable (5-pin socket, A-coded)			
 M12 socket (A-coded)	Pin	Name	Core color
	1	VIN	Brown
	2	I/O 1	White
	3	GND	Blue
	4	I/O 2	Black
	5	FE	Gray
	Thread	FE	Bare

Technical data of the cables for voltage supply

Operating temperature range In idle state: -30°C ... +70°C
In motion: -5°C ... +70°C

Material Sheathing: PVC

Bending radius > 50 mm

Order codes of the cables for voltage supply

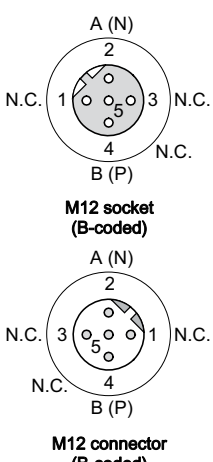
Type designation	Description	Part no.
K-D M12A-5P-5m-PVC	M12 socket, A-coded, axial plug outlet, open cable end, cable length 5m	50104557
K-D M12A-5P-10m-PVC	M12 socket, A-coded, axial plug outlet, open cable end, cable length 10m	50104559

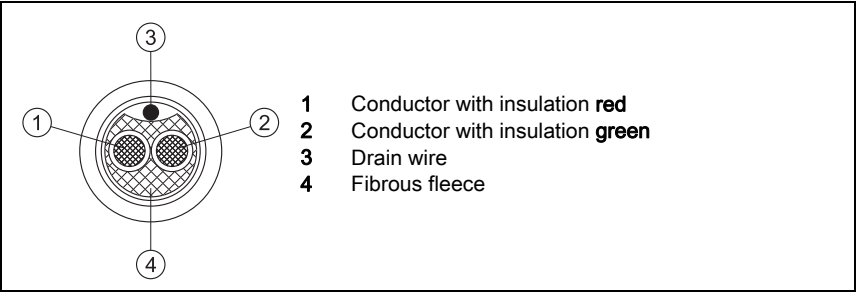
12.4.6 Accessories - Ready-made cables for PROFIBUS

General

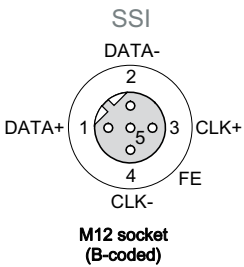
- **KB PB ...** cable for connection to the BUS IN/BUS OUT M12 connector
- **KB SSI ...** cable for connection to the SSI M12 connector
- Standard cables available in lengths from 2 ... 30m
- Special cables on request.

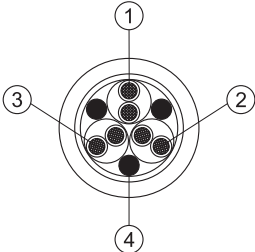
Contact assignment of PROFIBUS connection cable

PROFIBUS connection cable (5-pin socket/plug, B-coded, 2-pin cable)			
 M12 socket (B-coded) M12 connector (B-coded)	Pin	Name	Core color
	1	NC	-
	2	A (N)	Green
	3	NC	-
	4	B (P)	Red
	5	NC	-
	Thread	FE	Functional earth (housing)



Contact assignment of SSI connection cable

SSI/IBS connection cable (5-pin socket, B-coded)			
	Pin	Name	Core color
	1	DATA+	Yellow
	2	DATA-	Green
	3	CLK+	Gray
	4	CLK-	Pink
	5	FE	Brown
Thread		FE	Bare



1 Conductor pair with **white/brown** insulation

2 Conductor pair with **green/yellow** insulation

3 Conductor pair with **gray/pink** insulation

4 Filler (polyester threads)

All conductor pairs stranded,
colors acc. to DIN 47100

Technical data of PROFIBUS and SSI connection cable

Operating temperature range	In idle state: -40°C ... +80°C
	In motion: -5°C ... +80°C
Material	The cables fulfill the PROFIBUS requirements, Free of halogens, silicone and PVC
Bending radius	> 80mm, suitable for drag chains

Order codes for PROFIBUS and SSI connection cable

Type designation	Comment	Part no.
KB PB-2000-BA	M 12 socket for BUS IN, axial connector, open cable end, cable length 2m	50104181
KB PB-5000-BA	M 12 socket for BUS IN, axial connector, open cable end, cable length 5m	50104180
KB PB-10000-BA	M 12 socket for BUS IN, axial connector, open cable end, cable length 10m	50104179
KB PB-15000-BA	M 12 socket for BUS IN, axial connector, open cable end, cable length 15m	50104178

Type designation	Comment	Part no.
KB PB-20000-BA	M12 socket for BUS IN, axial connector, open cable end, cable length 20m	50104177
KB PB-25000-BA	M12 socket for BUS IN, axial connector, open cable end, cable length 25m	50104176
KB PB-30000-BA	M12 socket for BUS IN, axial connector, open cable end, cable length 30m	50104175
KB PB-2000-SA	M12 connector for BUS OUT, axial connector, open cable end, cable length 2m	50104188
KB PB-5000-SA	M12 connector for BUS OUT, axial connector, open cable end, cable length 5m	50104187
KB PB-10000-SA	M12 connector for BUS OUT, axial connector, open cable end, cable length 10m	50104186
KB PB-15000-SA	M12 connector for BUS OUT, axial connector, open cable end, cable length 15m	50104185
KB PB-20000-SA	M12 connector for BUS OUT, axial connector, open cable end, cable length 20m	50104184
KB PB-25000-SA	M12 connector for BUS OUT, axial connector, open cable end, cable length 25m	50104183
KB PB-30000-SA	M12 connector for BUS OUT, axial connector, open cable end, cable length 30m	50104182
KB PB-1000-SBA	M12 plug + M12 socket for PROFIBUS, axial connectors, cable length 1m	50104096
KB PB-2000-SBA	M12 connector + M12 socket for PROFIBUS, axial connectors, cable length 2m	50104097
KB PB-5000-SBA	M12 connector + M12 socket for PROFIBUS, axial connectors, cable length 5m	50104098
KB PB-10000-SBA	M12 connector + M12 socket for PROFIBUS, axial connectors, cable length 10m	50104099
KB PB-15000-SBA	M12 connector + M12 socket for PROFIBUS, axial connectors, cable length 15m	50104100
KB PB-20000-SBA	M12 connector + M12 socket for PROFIBUS, axial connectors, cable length 20m	50104101
KB PB-25000-SBA	M12 connector + M12 socket for PROFIBUS, axial connectors, cable length 25m	50104174
KB PB-30000-SBA	M12 connector + M12 socket for PROFIBUS, axial connectors, cable length 30m	50104173
KB SSI/IBS-2000-BA	M12 socket, B-coded, for SSI/Interbus, axial connector, open cable end, cable length 2m	50104172
KB SSI/IBS-5000-BA	M12 socket, B-coded, for SSI/Interbus, axial connector, open cable end, cable length 5m	50104171
KB SSI/IBS-10000-BA	M12 socket, B-coded, for SSI/Interbus, axial connector, open cable end, cable length 10m	50104170
KB SSI/IBS-15000-BA	M12 socket, B-coded, for SSI/Interbus, axial connector, open cable end, cable length 15m	50104169
KB SSI/IBS-20000-BA	M12 socket, B-coded, for SSI/Interbus, axial connector, open cable end, cable length 20m	50104168
KB SSI/IBS-25000-BA	M12 socket, B-coded, for SSI/Interbus, axial connector, open cable end, cable length 25m	50108447
KB SSI/IBS-30000-BA	M12 socket, B-coded, for SSI/Interbus, axial connector, open cable end, cable length 30m	50108446

13 Maintenance

13.1 General maintenance information

With normal use, the laser measurement system does not require any maintenance by the operator.

Cleaning

In the event of dust build-up or if the warning message (ATT) is displayed, clean the device with a soft cloth; use a cleaning agent (commercially available glass cleaner) if necessary. Also check the reflector for possible soiling.



Attention!

Do not use solvents and cleaning agents containing acetone. The use of such solvents can dull the reflector, the housing window and the display.

13.2 Repairs, servicing



Attention!

Access to or changes on the device, except where expressly described in this operating manual, is not authorized.

The device must not be opened. Failure to comply will render the guarantee void. Warranted features cannot be guaranteed after the device has been opened.

Repairs to the device must only be carried out by the manufacturer.

✎ *Contact your Leuze distributor or service organization should repairs be required. The addresses can be found on the inside of the cover and on the back.*



Note!

When sending laser measurement systems to Leuze for repair, please provide an accurate description of the fault.

13.3 Disassembling, packing, disposing

Repacking

For later reuse, the device is to be packed so that it is protected.

Note!

Electrical scrap is a special waste product! Observe the locally applicable regulations regarding disposal of the product.

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			↩ Password entry		For setting a four-digit numerical password	
		↩ Parameters to default			All parameters are reset to their factory settings	
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		↩ Address			Address of the AMS 304/ 0 ... 126	
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		↩ Encoding			Binary/gray	
		↩ Number of data bits			24-bit/25-bit/26-bit	
		↩ SSI resolution			0.001 mm / 0.01 mm / 0.1 mm / 1 mm / 10 mm / free resolution	
		↩ Error bit			ON/OFF	
		↩ Error bit function			Overflow / Intensity (ATT) / Temp. (TMP) / Laser (LSR) / Plausibility (PLB) / Hardware (ERR)	
		↩ Update rate			1.7 ms / 0.2 ms	
		↩ Clock frequency			80kHz - 800kHz, monoflop time 20us / 50kHz - 79kHz, monoflop time 30us	
	Position value ↩	↩ Unit			Metric/Inch	Page 48
		↩ Counting direction			Positive/Negative	
		↩ Offset			Value input:	
		↩ Preset			Value input	
		↩ Error delay			ON/OFF	
		↩ Position value in the case of failure			Last valid value / zero	
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				↩ Activation	Low active/High active	
		↩ Switching output		↩ Function	Pos. limit value 1 / Pos. limit value 2 / Velocity / Intensity (ATT) / Temp. (TMP) / Laser (LSR) / Plausibility (PLB) / Hardware (ERR)	
				↩ Activation	Low active/High active	
		↩ I/O 2	↩ Port configuration		Input/Output	
			↩ Switching input	↩ Function	No function/teach preset/laser ON/OFF	
				↩ Activation	Low active/High active	
		↩ Switching output		↩ Function	Pos. limit value 1 / Pos. limit value 2 / Velocity / Intensity (ATT) / Temp. (TMP) / Laser (LSR) / Plausibility (PLB) / Hardware (ERR)	
				↩ Activation	Low active/High active	

		Limit values	Upper pos. limit 1	Activation	ON/OFF	
				Limit value input	Value input in mm or inch/100	
			Lower pos. limit 1	Activation	ON/OFF	
				Limit value input	Value input in mm or inch/100	
			Upper pos. limit 2	Activation	ON/OFF	
				Limit value input	Value input in mm or inch/100	
			Lower pos. limit 2	Pos. limit value act.	ON/OFF	
				Position value	Value input in mm or inch/100	
			Max. velocity	Activation	ON/OFF	
				Max. velocity	Value input in mm/s or inch/100s	
Other		Heating control			Standard (heating: on < 10°C, off > 15°C) / Extended (heating: on < 30°C, off > 35°C)	Page 50
		Display background			10 minutes/ON	
		Display contrast			Weak/Medium/Strong	
		Service RS232	Baud rate		57.6kbit/s / 115.2kbit/s	
			Format		8,e,1 / 8,n,1	
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	Diagnosis				Only for use by Leuze personnel for service purposes	
	Expanded diagnosis				Only for use by Leuze personnel for service purposes	