

SMART  
**SENSOR**  
BUSINESS

 **Leuze electronic**

the sensor people

**BCL 95**  
Bar code reader



EN 2019/11/18 - 50140970  
We reserve the right to make technical changes

© 2019

Leuze electronic GmbH & Co. KG

In der Braike 1

D-73277 Owen / Germany

Phone: +49 7021 573-0

Fax: +49 7021 573-199

<http://www.leuze.com>

[info@leuze.com](mailto:info@leuze.com)

|          |   |           |
|----------|---|-----------|
| <b>1</b> | <b>About this document .....</b>                                    | <b>5</b>  |
| 1.1      | Used symbols and signal words .....                                 | 5         |
| 1.2      | Terms and abbreviations .....                                       | 6         |
| <b>2</b> | <b>Safety .....</b>   | <b>7</b>  |
| 2.1      | Intended use .....  | 7         |
| 2.2      | Foreseeable misuse .....  | 8         |
| 2.3      | Competent persons .....   | 8         |
| 2.4      | Disclaimer .....  | 8         |
| 2.5      | Laser safety notices .....  | 9         |
| <b>3</b> | <b>Device description .....</b>                                     | <b>10</b> |
| 3.1      | Device overview .....   | 10        |
| 3.1.1    | The BCL 95 bar code reader .....                                    | 10        |
| 3.1.2    | Stand-alone operation .....   | 10        |
| 3.2      | Performance characteristics .....                                   | 10        |
| 3.3      | Device construction .....   | 11        |
| 3.4      | Connection technology .....   | 11        |
| 3.5      | Display elements .....  | 11        |
| <b>4</b> | <b>Mounting .....</b>   | <b>12</b> |
| 4.1      | Selecting a mounting location .....                                 | 12        |
| <b>5</b> | <b>Electrical connection .....</b>                                  | <b>14</b> |
| 5.1      | Operating voltage .....   | 14        |
| 5.2      | Housing ground .....  | 14        |
| 5.3      | Pin assignment .....  | 15        |
| 5.4      | Switching input .....   | 16        |
| 5.5      | Switching output .....  | 17        |
| 5.6      | Cable lengths and shielding .....                                   | 17        |
| 5.7      | PC or terminal connection .....                                     | 17        |
| <b>6</b> | <b>Configuration and diagnostics software - Sensor Studio .....</b> | <b>18</b> |
| 6.1      | System requirements .....   | 18        |
| 6.2      | Installing Sensor Studio .....                                      | 19        |
| 6.2.1    | Downloading configuration software .....                            | 19        |
| 6.2.2    | Installing the Sensor Studio FDT frame .....                        | 19        |
| 6.2.3    | Install the communication DTM and device DTM .....                  | 19        |
| 6.2.4    | Connecting device to PC .....                                       | 19        |
| 6.3      | Starting Sensor Studio .....  | 20        |
| 6.4      | Exiting Sensor Studio .....   | 21        |
| 6.5      | Configuration parameters .....                                      | 22        |
| 6.5.1    | Decode tab .....  | 23        |
| 6.5.2    | Output tab .....  | 26        |
| 6.5.3    | Control tab .....   | 28        |
| 6.5.4    | Host interface tab .....  | 29        |
| 6.5.5    | Reference code tab .....  | 30        |
| 6.5.6    | Switching input tab .....   | 32        |
| 6.5.7    | Switching output tab .....  | 33        |
| 6.6      | Diagnosis .....   | 34        |
| 6.7      | Firmware Reload .....   | 35        |

|           |   |           |
|-----------|---|-----------|
| <b>7</b>  | <b>Starting up the device - Configuration</b> .....               | <b>36</b> |
| 7.1       | Measures to be performed prior to the initial commissioning ..... | 36        |
| 7.2       | Starting the device .....   | 36        |
| 7.2.1     | Power-on test .....   | 36        |
| 7.2.2     | Interface .....   | 36        |
| 7.2.3     | Online commands .....   | 36        |
| 7.2.4     | Problems .....  | 36        |
| 7.3       | Starting up with factory settings .....                           | 37        |
| 7.4       | Setting the configuration parameters .....                        | 37        |
| 7.4.1     | Service mode .....  | 37        |
| 7.4.2     | Parameter sets .....  | 38        |
| <b>8</b>  | <b>Online commands</b> .....                                      | <b>39</b> |
| 8.1       | Overview of commands and parameters .....                         | 39        |
| 8.2       | General online commands .....                                     | 40        |
| 8.3       | Online commands for system control .....                          | 45        |
| 8.4       | Online commands for the parameter set operations .....            | 46        |
| <b>9</b>  | <b>Care, maintenance and disposal</b> .....                       | <b>50</b> |
| <b>10</b> | <b>Diagnostics and troubleshooting</b> .....                      | <b>51</b> |
| <b>11</b> | <b>Service and support</b> .....                                  | <b>52</b> |
| 11.1      | What to do should servicing be required? .....                    | 52        |
| <b>12</b> | <b>Technical data</b> .....                                       | <b>53</b> |
| 12.1      | General specifications .....                                      | 53        |
| 12.2      | Reading fields .....  | 55        |
| 12.3      | Dimensioned drawings .....  | 56        |
| <b>13</b> | <b>Order guide and accessories</b> .....                          | <b>58</b> |
| 13.1      | Type overview .....   | 58        |
| 13.2      | Accessories.....  | 58        |
| <b>14</b> | <b>EC Declaration of Conformity</b> .....                         | <b>59</b> |
| <b>15</b> | <b>Appendix</b> .....   | <b>60</b> |
| 15.1      | Bar code samples .....  | 60        |

## 1 About this document

### 1.1 Used symbols and signal words

Tab. 1.1: Warning symbols and signal words

|   |  |
|---|--|
|  | Symbol indicating dangers to persons   |
|  | Symbol indicating dangers from harmful laser radiation   |
|  | Symbol indicating possible property damage   |
| <b>NOTE</b>   | Signal word for property damage<br>Indicates dangers that may result in property damage if the measures for danger avoidance are not followed.       |
| <b>CAUTION</b>  | Signal word for minor injuries<br>Indicates dangers that may result in minor injury if the measures for danger avoidance are not followed.           |
| <b>WARNING</b>  | Signal word for serious injury<br>Indicates dangers that may result in severe or fatal injury if the measures for danger avoidance are not followed. |

Tab. 1.2: Other symbols

|   |  |
|---|--|
|  | Symbol for tips<br>Text passages with this symbol provide you with further information.                  |
|  | Symbol for action steps<br>Text passages with this symbol instruct you to perform actions.               |
|  | Symbol for action results<br>Text passages with this symbol describe the result of the preceding action. |

## 1.2 Terms and abbreviations

Tab. 1.3: Terms and abbreviations

|        |   |
|--------|---|
| BCL    | Bar code reader   |
| DNC    | This PIN must not be connected<br>(Do Not Connect)  |
| DTM    | Software device manager<br>(Device Type Manager)  |
| EMC    | Electromagnetic compatibility   |
| EN     | European standard   |
| FDT    | Software frame for management of device managers (DTM)<br>(Field Device Tool)                 |
| FE     | Functional earth  |
| GUI    | Graphical user interface  |
| HID    | Device class for input devices with which users directly interact<br>(Human Interface Device) |
| NC     | This pin is not contacted at the device<br>(Not Connected)                                    |
| SELV   | Safe Extra Low Voltage  |
| PLC    | Programmable Logic Control<br>(corresponds to Programmable Logic Controller (PLC))            |
| SW_IN  | Switching input   |
| SW_OUT | Switching output  |

**2 Safety**

This bar code reader was developed, manufactured and tested in accordance with the applicable safety standards. It corresponds to the state of the art.

**2.1 Intended use**

Bar code readers of the BCL 95 series are conceived as stationary scanners with integrated decoder for all current bar codes used for automatic object detection.

**Areas of application**

Bar code readers of the BCL 95 series are designed for the following areas of application:

- Automatic analyzers
- Robotics and automation technology
- Material flow
- Labeling and packaging machines
- For space-critical bar code reading tasks
- Applications with large reading field with small modules

**⚠ CAUTION**



**Observe intended use!**

The protection of personnel and the device cannot be guaranteed if the device is operated in a manner not complying with its intended use.

- ↳ Only operate the device in accordance with its intended use.
- ↳ Leuze electronic GmbH + Co. KG is not liable for damages caused by improper use.
- ↳ Read these operating instructions before commissioning the device. Knowledge of the operating instructions is an element of proper use.

**NOTICE**



**Comply with conditions and regulations!**

- ↳ Observe the locally applicable legal regulations and the rules of the employer's liability insurance association.

**⚠ CAUTION**



**UL applications!**

For UL applications, use is only permitted in LPS/Class 2 circuits in accordance with the NEC (National Electric Code).

## 2.2 Foreseeable misuse

Any use other than that defined under "Intended use" or which goes beyond that use is considered improper use.

In particular, use of the device is not permitted in the following cases:

- in rooms with explosive atmospheres
- in circuits which are relevant to safety
- for medical purposes

| <b>NOTICE</b>   |  |
|---|--|
|  | <p><b>Do not modify or otherwise interfere with the device!</b></p> <ul style="list-style-type: none"> <li>↳ Do not carry out modifications or otherwise interfere with the device. The device must not be tampered with and must not be changed in any way.</li> <li>↳ The device must not be opened. There are no user-serviceable parts inside.</li> <li>↳ Repairs must only be performed by Leuze electronic GmbH + Co. KG.</li> </ul> |

| <b>NOTICE</b>   |  |
|---|--|
|  | <ul style="list-style-type: none"> <li>↳ To increase the decoding reliability, it is recommended that only the actually needed code types be enabled.</li> <li>↳ If there are very high requirements on reading reliability, the use of additional processes is recommended, e.g.:                             <ul style="list-style-type: none"> <li>⇒ Device side: check digits, multiple evaluation by setting Equal Scans to min. <math>\geq 2</math></li> <li>⇒ Application side: reading moving codes</li> <li>⇒ System side: plausibility checks of the bar code information</li> </ul> </li> </ul> |

## 2.3 Competent persons

Connection, mounting, commissioning and adjustment of the device must only be carried out by competent persons.

Prerequisites for competent persons:

- They have a suitable technical education.
- They are familiar with the rules and regulations for occupational safety and safety at work.
- They are familiar with the operating instructions for the device.
- They have been instructed by the responsible person on the mounting and operation of the device.

### Certified electricians

Electrical work must be carried out by a certified electrician.

Due to their technical training, knowledge and experience as well as their familiarity with relevant standards and regulations, certified electricians are able to perform work on electrical systems and independently detect possible dangers.

In Germany, certified electricians must fulfill the requirements of accident-prevention regulations DGUV (German Social Accident Insurance) provision 3 (e.g. electrician foreman). In other countries, there are respective regulations that must be observed.

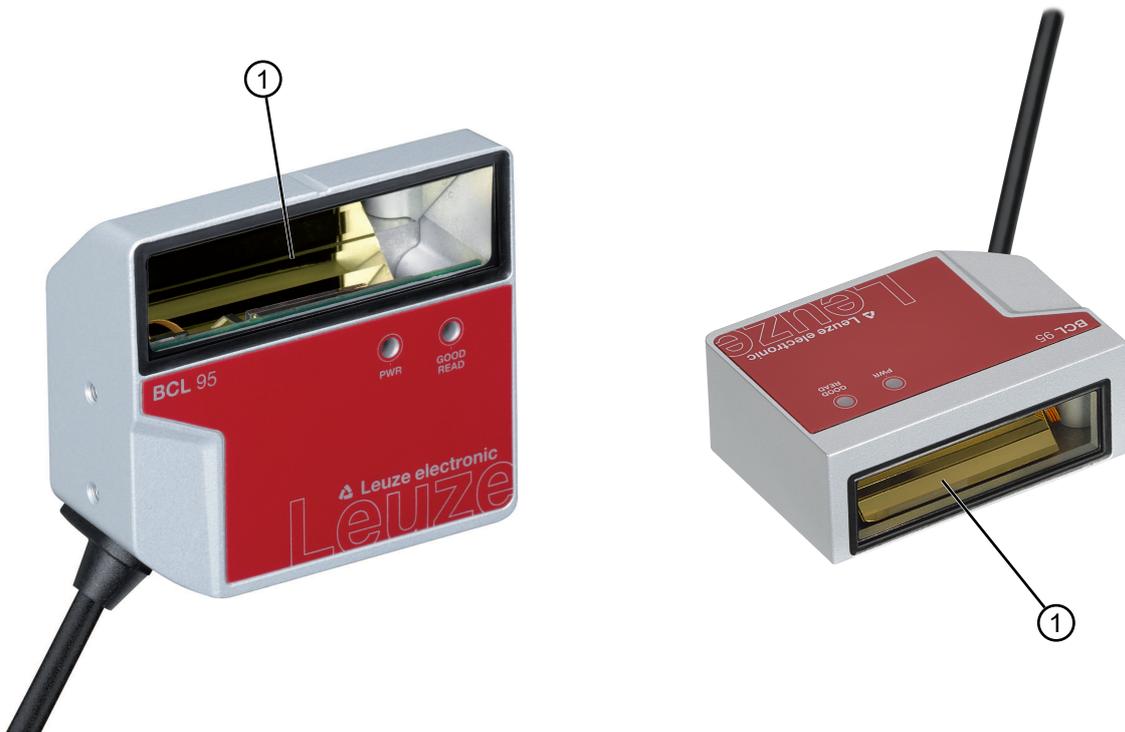
## 2.4 Disclaimer

Leuze electronic GmbH + Co. KG is not liable in the following cases:

- The device is not being used properly.
- Reasonably foreseeable misuse is not taken into account.
- Mounting and electrical connection are not properly performed.
- Changes (e.g., constructional) are made to the device.

2.5 Laser safety notices

|  |   |
|--|---|
|  <b>ATTENTION</b> |   |
|                   | <p><b>LASER RADIATION – CLASS 1 LASER PRODUCT</b></p> <p>The device satisfies the requirements of IEC/EN 60825-1:2014 safety regulations for a product of <b>laser class 1</b> and complies with 21 CFR 1040.10 except for conformance with IEC 60825-1 Ed. 3., as described in Laser Notice No. 56, dated May 8, 2019.</p> <ul style="list-style-type: none"> <li>↳ Observe the applicable statutory and local laser protection regulations.</li> <li>↳ The device must not be tampered with and must not be changed in any way. There are no user-serviceable parts inside the device. Repairs must only be performed by Leuze electronic GmbH + Co. KG.</li> </ul> |
| <b>NOTICE</b>  |   |
|                   | <p><b>Laser aperture!</b></p> <p>The glass optics cover is the only aperture through which laser radiation may be observed on this product.</p>   |



1 Laser aperture

Fig. 2.1: Laser aperture

### 3 Device description

#### 3.1 Device overview

##### 3.1.1 The BCL 95 bar code reader

The bar code reader is a laser scanner with integrated decoder for all commonly used bar codes, e.g. 2/5 Interleaved, Code 39, Code 128, EAN etc.

- The reading field is optimized for the reading of sample tubes, reagent containers, etc., in lab automation.
- Reliable reading of 80 mm high code labels at a short distance.
- Due to the small dimensions of the unit and the variants with frontal or lateral beam exit, the bar code reader can also be used in highly constrained spaces.
- The many possible configurations of the device allow it to be adapted to a multitude of reading tasks.
- Information on technical data and characteristics: see chapter 12 "Technical data".

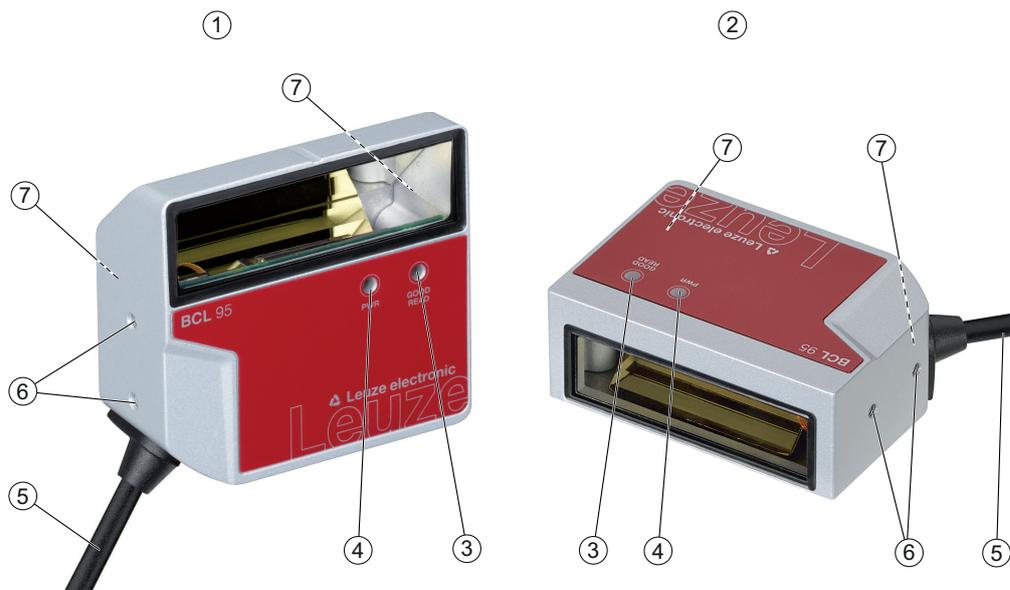
##### 3.1.2 Stand-alone operation

The bar code reader is operated as a "stand-alone" single device. The electrical connection of the operating voltage, the interface and the switching input is made via a 6-wire cable with open cable ends or via an 8-pin M12 connector.

#### 3.2 Performance characteristics

- Laser scanner with integrated decoder; lateral or frontal beam exit
- High-resolution optics
- Resolution 0.15 mm ... 0.5 mm  
Reading of all common codes of module size 165 ... 500 µm (6 ... 20 mil) at a reading field height of ≥ 80 mm, even with a reading distance of 25 mm for devices with lateral beam exit
- Reading distance 25 mm ... 170 mm
- Scanning rate of 600 scans/s facilitates reliable reading, even while in motion
- Compact design for simple integration, even in constrained spaces
- Sturdy diecast zinc housing
  - Connection cable 2 m with open cable end
  - Pigtail with M12 connector, 8-pin
- Process and service interface RS 232

### 3.3 Device construction



- 1 BCL 95 M0/R2 ...; lateral beam exit
- 2 BCL 95 M2/R2 ...; frontal beam exit
- 3 Indicator diode – decode LED
- 4 Indicator diode – status LED
- 5 Connection cable, 6-wire with open cable end  
Pigtail with M12 connector, 8-pin
- 6 M2.5 mounting threads on the device side
- 7 M3 mounting threads on the rear of the device

Fig. 3.1: Device construction of the BCL 95

### 3.4 Connection technology

6-wire connection cable with open cable end or pigtail with 8-pin M12 connection plug:

- Voltage supply
- 1 switching input
- 1 switching output
- Process and service interface RS 232

### 3.5 Display elements

Located on the front of the device are two LEDs that indicate the readiness for operation and the read status.

| LED                       | Display                  | Description           |
|---------------------------|--------------------------|-----------------------|
| Status LED<br>(PWR)       | Green, flashing          | Initialization phase  |
|                           | Green, continuous light  | Operational readiness |
|                           | Red, flashing 200 ms     | Warning               |
|                           | Red, continuous light    | Error, no function    |
|                           | Orange, flashing 200 ms  | Service operation     |
| Decode LED<br>(GOOD READ) | Green, 200 ms on         | Reading successful    |
|                           | Red, 200 ms off          | No reading result     |
|                           | Orange, continuous light | Reading gate active   |

## 4 Mounting

- ↪ Observe the mounting instructions (see chapter 4.1 "Selecting a mounting location").
- ↪ Fasten the bar code reader on the mounting threads (see chapter 3.3 "Device construction"):
  - M3 mounting threads on the rear of the device
  - M2.5 mounting threads on the device side

### 4.1 Selecting a mounting location

| <b>NOTICE</b>   |  |
|---|--|
|  | <p>The size of the bar code module influences the maximum reading distance and the width of the reading field.</p> <ul style="list-style-type: none"> <li>↪ When selecting a mounting location and/or the bar code label, take into account the different reading characteristics of the bar code reader with various bar code modules.</li> </ul> |

| <b>NOTICE</b>   |   |
|---|---|
|  | <p><b>Observe when choosing the mounting location!</b></p> <ul style="list-style-type: none"> <li>↪ Maintain the permissible environmental conditions (humidity, temperature).</li> <li>↪ Avoid possible soiling of the reading window due to liquids, abrasion by boxes, or packaging material residues.</li> <li>↪ Ensure that there is the lowest possible chance of damage to the bar code reader by mechanical collision or jammed parts.</li> <li>↪ Avoid possible ambient light influence (no direct sunlight).</li> </ul> |

In order to select the right mounting location, several factors must be considered:

- Size, orientation, and position tolerance of the bar codes on the objects to be scanned.
- The reading field of the bar code reader in relation to the bar code module width.
- The resulting minimum and maximum reading distance from the respective reading field with the respective module width (see chapter 12.2 "Reading fields").
- alignment of the bar code reader for avoiding reflections.
- distance between bar code reader and host system with respect to the interface.

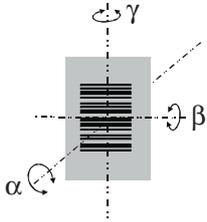
The best read results are obtained if the following prerequisites are fulfilled:

- The reading distance lies in the middle area of the reading field.
- There is no direct sunlight and ambient light influences are avoided
- The bar code labels are of good print quality and have good contrast ratios.
- You are not using glossy labels.
- The bar code is moved past the reading window with an angle of rotation of approx. 15°.

**NOTICE****Avoid direct reflection of the laser beam!**

The beam exits the bar code reader perpendicular to the reading window.

↳ The bar code label must be rotated by  $> 10^\circ$  to avoid a reflection of the laser beam in the case of glossy labels.



$\alpha$  Azimuth angle

$\beta$  Angle of inclination

$\gamma$  Angle of rotation

Recommended angle of rotation:  $\gamma > 10^\circ$

Fig. 4.1: Definition of the reading angles

## 5 Electrical connection

 **CAUTION**



**Safety notices!**

- ↪ The bar code reader is completely sealed and must not be opened.
- ↪ Before connecting the device, be sure that the supply voltage agrees with the value printed on the name plate.
- ↪ Connection of the device and maintenance work while under voltage must only be carried out by a qualified electrician.
- ↪ The power supply unit for the generation of the supply voltage for the bar code reader and the corresponding connection units must have a secure electrical insulation according to IEC 60742 (PELV).
- ↪ If faults cannot be rectified, take the device out of operation and protect it from accidentally being started.

 **CAUTION**



**UL applications!**

For UL applications, use is only permitted in LPS/Class 2 circuits in accordance with the NEC (National Electric Code).

**NOTICE**



**Laying cables!**

- ↪ Lay all connection cables and signal lines within the electrical installation space or permanently in cable ducts.
- ↪ Lay the cables and lines so that they are protected against external damages.
- ↪ For further information: see ISO 13849-2, Table D.4.

The electrical connection is established via the connection cable (see chapter 5.3 "Pin assignment"):

- 6-wire connection cable with open cable end
- Pigtail with M12 connector, 8-pin

The bar code reader is provided with the following interfaces:

- Voltage supply
- 1 switching input
- 1 switching output
- Process and service interface RS 232

You can configure the functions of the switching input and the switching output according to your requirements via the *Sensor Studio* configuration software (see chapter 6 "Configuration and diagnostics software - Sensor Studio").

### 5.1 Operating voltage

The bar code reader is designed for an operating voltage of 5 V. The operating voltage is fed in via the connection cable (see chapter 5.3 "Pin assignment").

- +5 VDC: pin 1 of the 8-pin M12 connector plug or red wire of the connection cable with open cable end
- GND: pin 3 of the 8-pin M12 connector plug or violet wire of the connection cable with open cable end

### 5.2 Housing ground

To avoid electromagnetic interference, a low-impedance connection is necessary from the housing to the machine ground.

**5.3 Pin assignment**

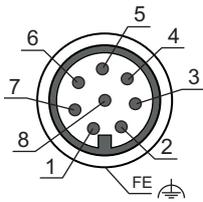


Fig. 5.1: Pin assignment for M12 connector, 8-pin, A-coded

Tab. 5.1: RS 232 – M12 connector

| Pin | Signal     | Description                   | IN / OUT | Core color |
|-----|------------|-------------------------------|----------|------------|
| 1   | +5 VDC     | Voltage supply 5 VDC          | IN       | White      |
| 2   | SW IN      | Switching input               | IN       | Brown      |
| 3   | GND        | Voltage supply 0 VDC / Ground | IN       | Green      |
| 4   | SW OUT     | Switching output              | OUT      | Yellow     |
| 5   | NC         | Not connected                 | ---      | Gray       |
| 6   | RS 232 RxD | Serial interface              | IN       | Pink       |
| 7   | RS 232 TxD | Serial interface              | OUT      | Blue       |
| 8   | FE/Shield  | Functional earth/shield       | ---      | Red        |

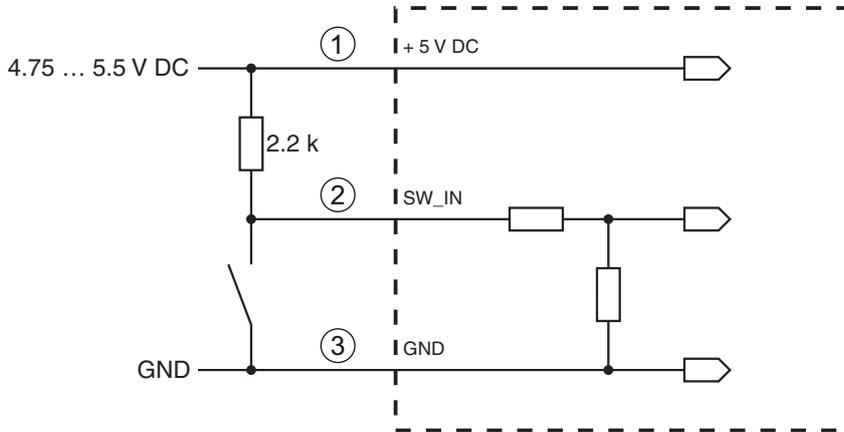
Tab. 5.2: RS 232 – connection cable

| Core color         | Signal     | Description                   | IN / OUT |
|--------------------|------------|-------------------------------|----------|
| Red                | +5 VDC     | Voltage supply 5 VDC          | IN       |
| Orange             | SW IN      | Switching input               | IN       |
| Violet             | GND        | Voltage supply 0 VDC / Ground | IN       |
| Black              | SW OUT     | Switching output              | OUT      |
| White              | RS 232 RxD | Serial interface              | IN       |
| Green              | RS 232 TxD | Serial interface              | OUT      |
| Drain wire, yellow | FE/Shield  | Functional earth/shield       | ---      |

### 5.4 Switching input

By means of the SW IN switching input connection, you can trigger a read process in the standard setting (low = active) with the connection SW IN (pin 2 / orange) and GND (pin 3 / violet). We recommend wiring a 2.2 kΩ pull-up resistor as defined cable termination.

Depending on how the switching input is actuated, you can operate it both as NPN (low = active) as well as PNP (high = active).

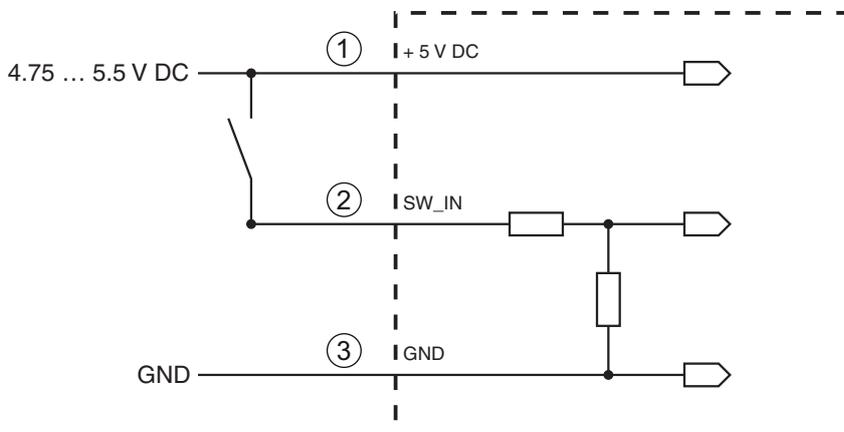


- 1 Pin 1 / red
- 2 Pin 2 / orange
- 3 Pin 3 / violet

Connection version NPN: standard setting (low = active); input resistance: 36 kΩ

Fig. 5.2: Switching input for connection variant NPN (standard setting)

PNP actuation: With the "inverted" setting (high = active), you can trigger a read process by applying a voltage of +5 V DC (pin 1 / red) at SW IN (pin 2 / orange).



- 1 Pin 1 / red
- 2 Pin 2 / orange
- 3 Pin 3 / violet

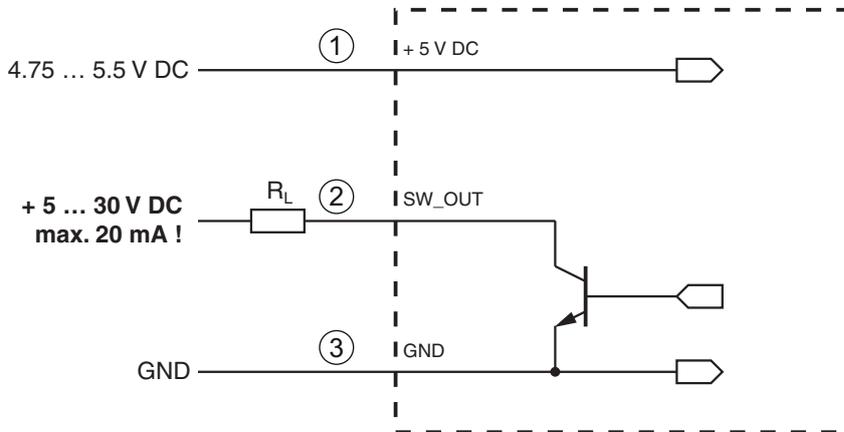
Connection version PNP: inverted setting (high = active); input resistance: 36 kΩ

Fig. 5.3: Switching input for connection variant PNP ("inverted" setting)

### 5.5 Switching output

The NPN switching output connection between SW OUT (pin 4 / black) and GND (pin 3 / violet) can be activated in the scanner setup.

In the basic setting, the SW OUT switching output is switched to GND if a code is detected.



- 1 Pin 1 / red
- 2 Pin 4 / black
- 3 Pin 3 / violet

Fig. 5.4: Switching output

**NOTICE**

 **Maximum loading of the switching output**  
 Do not load the switching output of the code reader with more than 20 mA at +5 ... 30 V DC!

### 5.6 Cable lengths and shielding

Observe the maximum cable lengths:

| Connection       | Interface | Max. cable length | Shielding     |
|------------------|-----------|-------------------|---------------|
| BCL 95           | RS 232    | < 3 m             | Required      |
| Switching input  |           | < 3 m             | Not necessary |
| Switching output |           |                   |               |

**NOTICE**

 Make certain that the cables of the RS 232 interface are shielded should a cable extension be necessary.

### 5.7 PC or terminal connection

Via the RS 232 service interface, you can configure the bar code reader by means of a PC or a terminal program. For this, you need an RS 232 connection that establishes the RxD, TxD and GND connections between PC and bar code reader (see chapter 5.3 "Pin assignment").

## 6 Configuration and diagnostics software - Sensor Studio

The *Sensor Studio* configuration software provides a graphical user interface for the operation, configuration and diagnostics of the device via the RS 232 service interface.

A device that is not connected to the PC can be configured offline.

Configurations can be saved and reopened as projects for transferring back to the device at a later time.

| <b>NOTICE</b>   |   |
|---|---|
|  | <p>Only use the <i>Sensor Studio</i> configuration software for products manufactured by Leuze electronic.</p> <p>The <i>Sensor Studio</i> configuration software is offered in the following languages: German, English, French, Italian and Spanish.</p> <p>The FDT frame application of the <i>Sensor Studio</i> supports all languages; all languages may not be supported in the device DTM (Device Type Manager).</p> |

The *Sensor Studio* configuration software is designed according to the FDT/DTM concept:

- You make the individual configuration settings for the bar code reader in the Device Type Manager (DTM).
- The individual DTM configurations of a project can be called up via the frame application of the Field Device Tool (FDT).
- Communication DTM for bar code readers: *LeCommInterface*
- Device DTM for the BCL 95 bar code reader

Procedure for the installation of the software and hardware:

- ↪ Install the *Sensor Studio* configuration software on the PC.
- ↪ Install the communication and device DTM. Communication and device DTM are included in the *Le-AnalysisCollectionSetup* installation package.
- ↪ Create device DTM for BCL 95 in the project tree of the *Sensor Studio* FDT frame.
- ↪ Connect bar code reader to PC (see chapter 5.7 "PC or terminal connection").
- ↪ Activate service interface on bar code reader (see chapter 7.4.1 "Service mode").

### 6.1 System requirements

To use the *Sensor Studio* configuration software, you need a PC or laptop with the following specifications:

Tab. 6.1: System requirements for *Sensor Studio* installation

|  |  |
|--|--|
| Operating system   | Windows XP or higher (32 bit, 64 bit)<br>Windows Vista<br>Windows 7<br>Windows 8   |
| Computer   | Processor type: 1 GHz or higher<br>Serial COM interface<br>CD-ROM drive<br>Main memory (RAM): at least 64 MB<br>Keyboard and mouse or touchpad |
| Graphics card  | At least 1024 x 768 pixels   |
| Required hard disk capacity for <i>Sensor Studio</i> and communication DTM | 35 MB  |

**NOTICE**

Administrator privileges on the PC are necessary for installing *Sensor Studio*.

## 6.2 Installing Sensor Studio

**NOTICE**

The installation files of the *Sensor Studio* configuration software must be downloaded from the Internet at **www.leuze.com**. For subsequent updates, you can find the most recent version of the *Sensor Studio* installation software on the Internet at **www.leuze.com**.

### 6.2.1 Downloading configuration software

- ↪ Call up the Leuze home page: **www.leuze.com**
- ↪ Enter the type designation or part number of the device as the search term.
- ↪ The configuration software can be found on the product page for the device under the *Downloads* tab.

### 6.2.2 Installing the Sensor Studio FDT frame

**NOTICE****First install the software!**

- ↪ Do not yet connect the device to the PC.
- ↪ First install the software.

**NOTICE**

If FDT frame software is already installed on your PC, you do not need the *Sensor Studio* installation.

You can install the communication DTM and the device DTM in the existing FDT frame. Communication DTM and device DTM are included in the *LeAnalysisCollectionSetup* installation package.

- ↪ Start the PC.
- ↪ Download the configuration software from the Internet to the PC (see chapter 6.2.1 "Downloading configuration software"). Unpack the installation package.
- ↪ Start the *SensorStudioSetup.exe* file.
- ↪ Follow the instructions on the screen.

### 6.2.3 Install the communication DTM and device DTM

Prerequisites:

- ✓ An FDT frame is installed on the PC.
- ↪ Start the *LeAnalysisCollection.exe* file from the installation package and follow the instructions on the screen.

### 6.2.4 Connecting device to PC

The device is connected to the PC via the RS 232 interface.

You need an RS 232 connection that establishes the RxD, TxD and GND connections between PC and device (see chapter 5.7 "PC or terminal connection").

The +5 V DC voltage supply is to be fed in externally (see chapter 5.1 "Operating voltage").

### 6.3 Starting Sensor Studio

Prerequisites:

- ✓ The device has been mounted (see chapter 4 "Mounting") and connected (see chapter 5 "Electrical connection") correctly.
- ✓ The device is connected to the PC via the RS 232 interface (see chapter 6.2.4 "Connecting device to PC").
- ✓ The Sensor Studio configuration software is installed on the PC (see chapter 6.2 "Installing Sensor Studio").
- ⇨ Start the *Sensor Studio* configuration software by double-clicking the [*Sensor Studio*] icon ().
- ⇨ The **mode selection** of the Project Wizard is displayed.
- ⇨ Select the **Device selection without communication connection (offline)** configuration mode and click on [Next].
- ⇨ The Project Wizard displays the device selection list of the configurable devices.

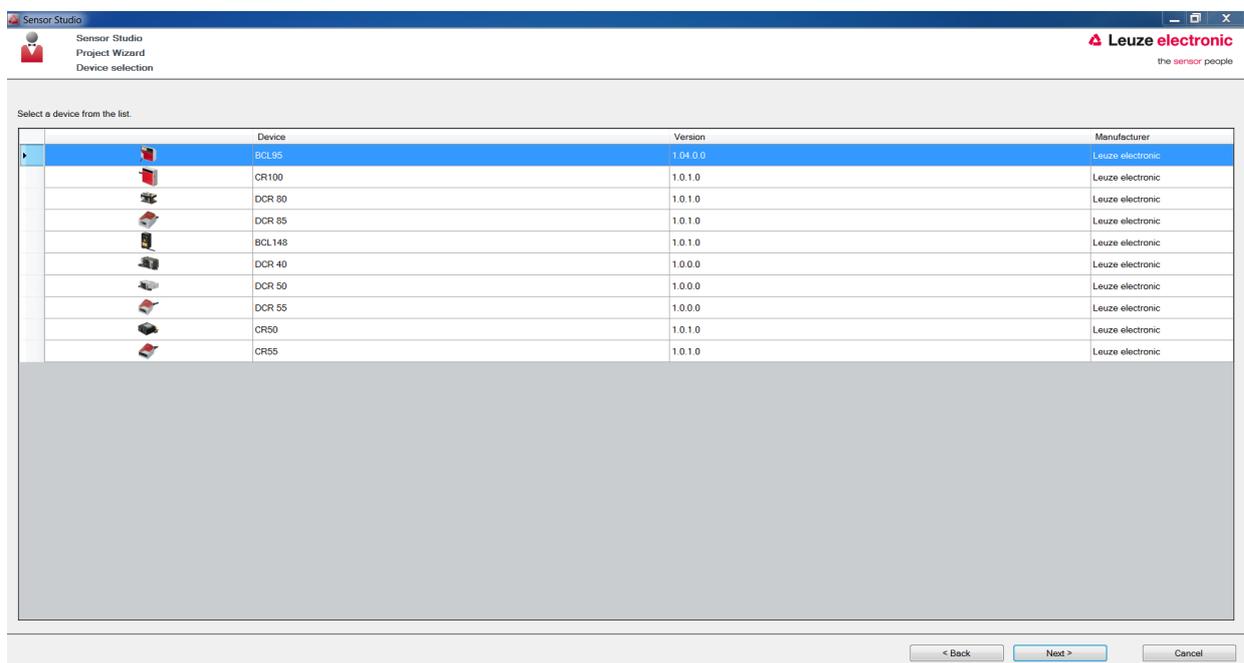


Fig. 6.1: Device selection for the BCL 95

- ⇨ Select **BCL 95** in the **device selection** and click on [Next].
- ⇨ The device manager (DTM) of the connected bar code reader starts with the offline view for the *Sensor Studio* configuration project.
- ⇨ Establish the online connection to the connected bar code reader.
  - ⇨ In the *Sensor Studio* FDT frame, click on the [Establish connection with device] button ().
  - ⇨ In the *Sensor Studio* FDT frame, click on the [Upload parameters to device] button ().
- ⇨ The current configuration data is displayed in the device manager (DTM).

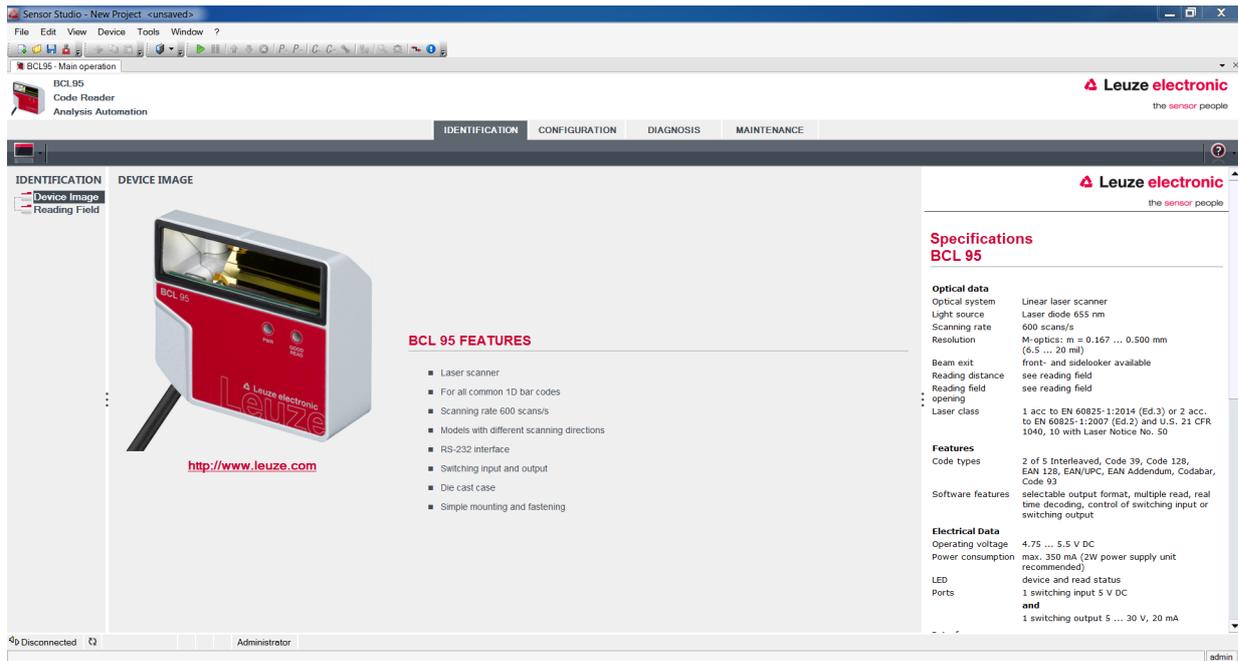


Fig. 6.2: Configuration project: device manager for BCL 95

- ↳ The menu of the *Sensor Studio* device manager (DTM) can be used to change or read out the configuration of the connected device.
  - ⇒ The user interface of the *Sensor Studio* device manager (DTM) is largely self-explanatory.
  - ⇒ The online help system provides information on the menu items and adjustment parameters. Select the **Help** menu item in the menu [?].
- ↳ Transfer the modified configuration parameters to the device.
  - ⇒ If a connection exists, click on the [Download parameters to device] (↓) button on the task bar.

## 6.4 Exiting Sensor Studio

After completing the configuration settings, close the *Sensor Studio* configuration software.

- ↳ Exit the program via **File > Exit**.
- ↳ Save the configuration settings as a configuration project on the PC.

## 6.5 Configuration parameters

In this chapter, you will find information and explanations on the configuration parameters of the device manager (DTM) for the bar code reader.

### NOTICE



This chapter does not include a complete description of the *Sensor Studio* configuration software. Complete information on the FDT frame menu and on the functions in the device manager (DTM) can be found in the online help system.

The device manager (DTM) for BCL 95 bar code readers of the *Sensor Studio* configuration software offers the following configuration functions:

- Decode (see chapter 6.5.1 "Decode tab")
- Output (see chapter 6.5.2 "Output tab")
- Control (see chapter 6.5.3 "Control tab")
- Host Interface (see chapter 6.5.4 "Host interface tab")
- Reference Code (see chapter 6.5.5 "Reference code tab")
- Switching input (sensor) (see chapter 6.5.6 "Switching input tab")
- Switching output (switch) (see chapter 6.5.7 "Switching output tab")

### NOTICE



The online help system displays information on the menu items and configuration parameters for each function. Select the **Help** menu item in the menu [?]

The *Sensor Studio* configuration software offers the following buttons in the **CONFIGURATION** menu:

- : [Reset all parameters in the GUI to their factory default settings]  
Resets all parameters in the graphical user interface to the factory settings.

6.5.1 Decode tab

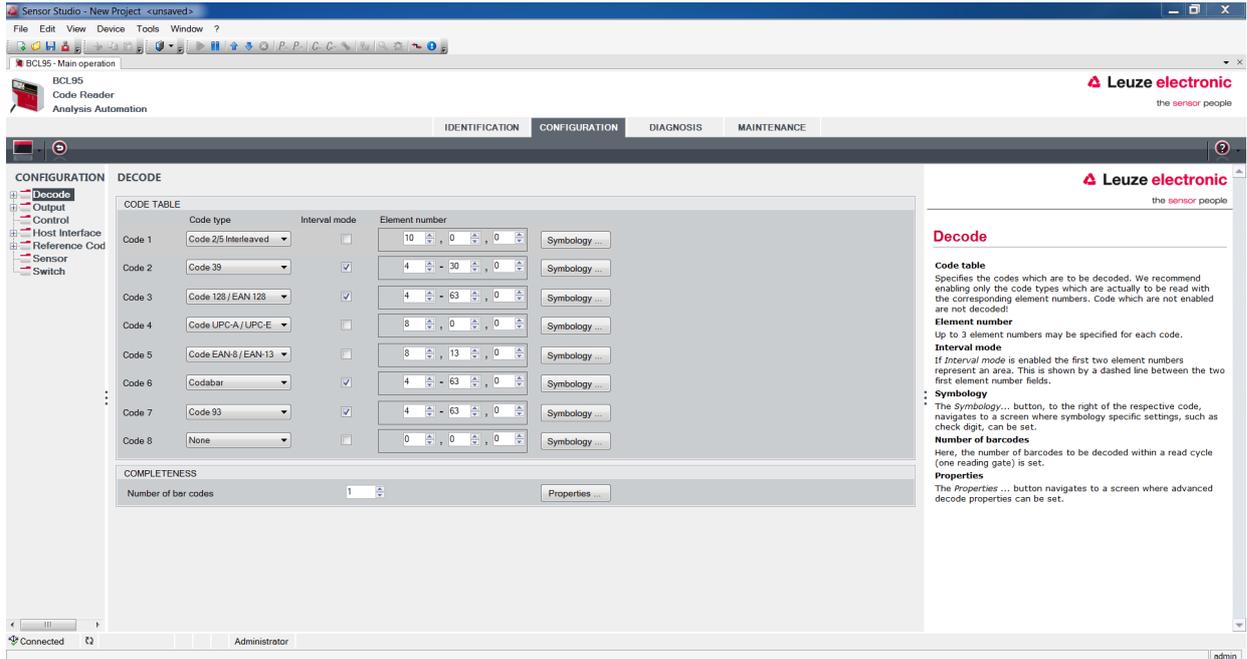


Fig. 6.3: Decode tab

|  |   |
|--|---|
| Code table<br>(CODE TABLE)                                   | Here, the codes which are to be decoded are set.<br>Codes which are not enabled are not decoded!<br><b>Note:</b><br>We recommend enabling <b>only</b> the code types which are to actually be read with the corresponding element numbers.  |
| Element number   | In the field Element number, up to three element entries may be entered.<br>A range of permissible elements is indicated by a dash:<br>e.g., 4-40 elements.<br>To select a range, set the check mark beneath <b>Interval mode</b> . Up to three fixed element numbers with comma:<br>e.g.: 8,13 elements<br>Both are also possible, but the range must be specified first (select <b>Interval mode</b> ):<br>e.g.: 4-10,20 elements |
| Labels to be decoded<br>(COMPLETENESS / Number of bar codes) | Here, the number of the bar codes to be decoded within a read cycle (one reading gate) is set.  |

**NOTICE**

 If the code EAN128 is to be read, 3 additional characters are to be set for the code identifier.

|  |   |
|--|---|
| <p>Properties<br/>(Symbology Properties)</p> | <p>In the Symbology <b>Properties</b> window to the right of the respective code, after <b>Element number</b>, the code-specific settings such as the check digit can be selected.</p> <p>Alternatively, you can select the property settings directly via the navigation tree with the [Symbologies] button.</p> <p>The properties can be individually set for each code type.</p> |
|--|---|

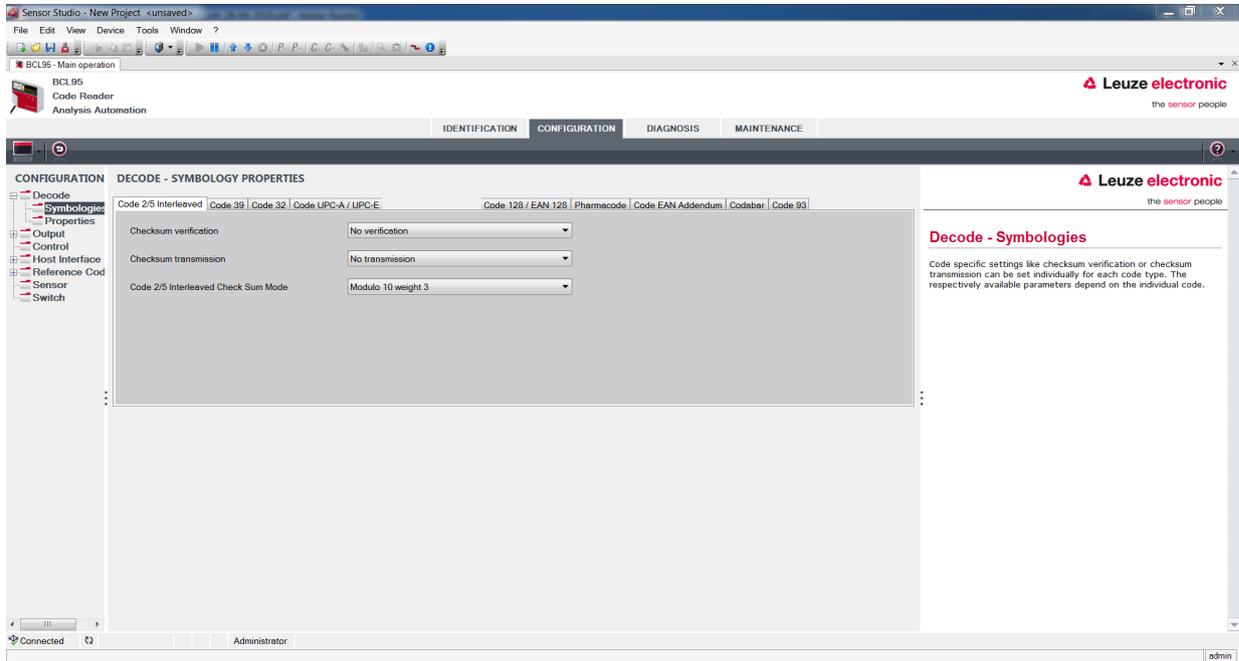


Fig. 6.4: Standard settings of the **Properties** dialog box (SYMBOLGY PROPERTIES)

Properties dialog box (Common Properties)

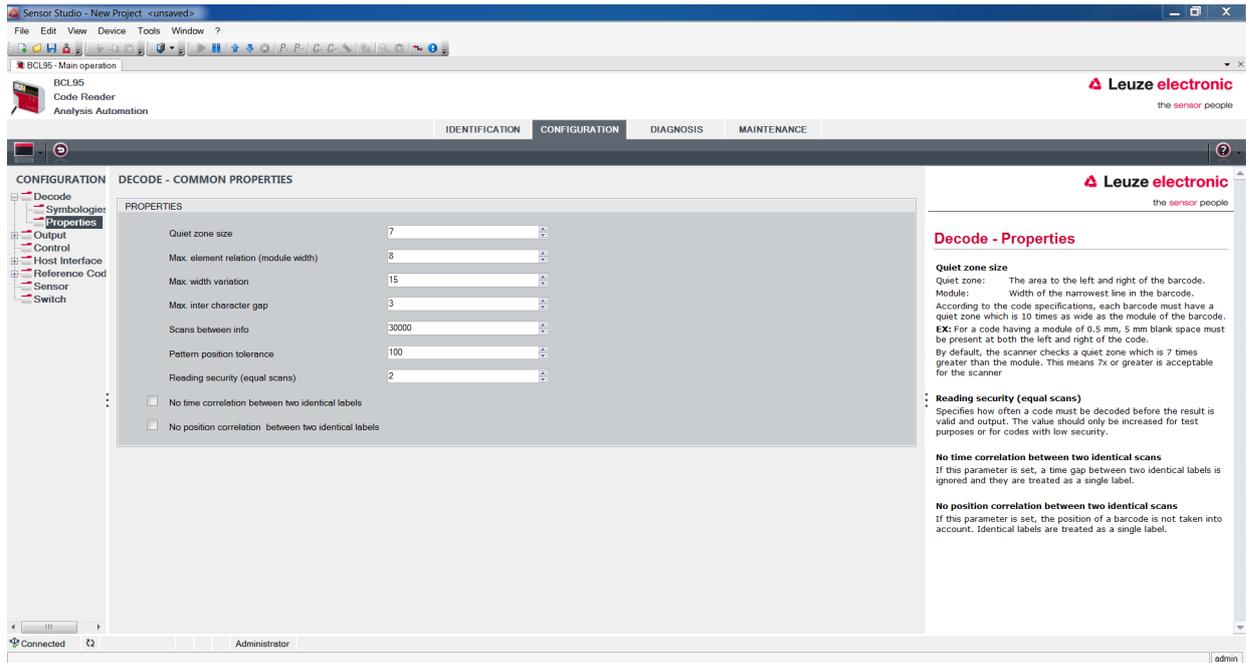


Fig. 6.5: Standard settings of the **Properties** dialog box (COMMON PROPERTIES)

|   |  |
|---|--|
| <p>Quiet zone minimum size (in module widths)<br/>Quiet zone size</p> | <p>Quiet zone: the area to the left and right of the bar code<br/>Module: width of the narrowest bar in the bar code<br/>According to code specifications, each bar code must have a quiet zone that is 10x as wide as the module of the bar code.<br/>Example: For a code with a module of 0.5 mm, there must be 5 mm of empty space to the left and right.<br/>By default, the scanner checks a quiet zone that is 7x greater than the module.</p> |
| <p>Reading reliability<br/>(Reading reliability (equal scans))</p>    | <p>Under <b>reading reliability</b> (equal scans), it is possible to select how often a code must be decoded before the result is valid and output</p>   |
| <p>No time correlation between two identical scans</p>                | <p>If this parameter is set, a gap between two identical labels is ignored and they are treated as a single label.</p>   |
| <p>No position correlation between two identical scans</p>            | <p>If this parameter is set, then the position of a bar code label in the reading beam is not taken into account. Identical labels are treated as a single label.</p>  |

**NOTICE**

 In general, the remaining parameters must not be changed. In the worst case, this could corrupt the read result!

6.5.2 Output tab

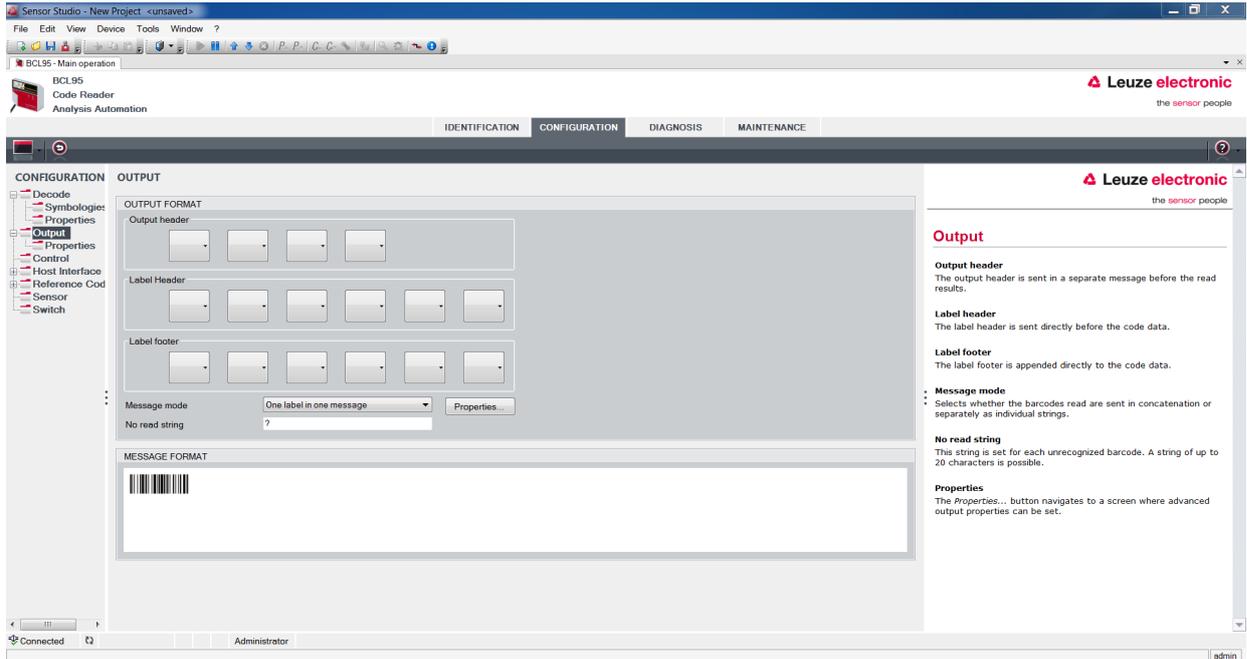


Fig. 6.6: Output tab (OUTPUT FORMAT)

|               |   |
|---------------|---|
| Output header | Select from the options listed below. The output header is sent in a separate message before the read result. |
| Label header  | The label header is set directly before the code data.  |
| Label footer  | The label footer is appended directly to the code data.   |
| Message mode  | Selects whether the bar codes read are sent in concatenation or separately as individual strings.             |

**NOTICE**

 The structure of this message string is depicted symbolically in the preview window.

|   |  |
|---|--|
| Text in the case of misreading (No read string) | This character is set for each unrecognized bar code. Multiple characters (=string) may be entered here. Up to 20 characters are possible. |
|---|--|

**Properties dialog box (Common Properties)**

Set the desired formatting modes and formatting characters as necessary.

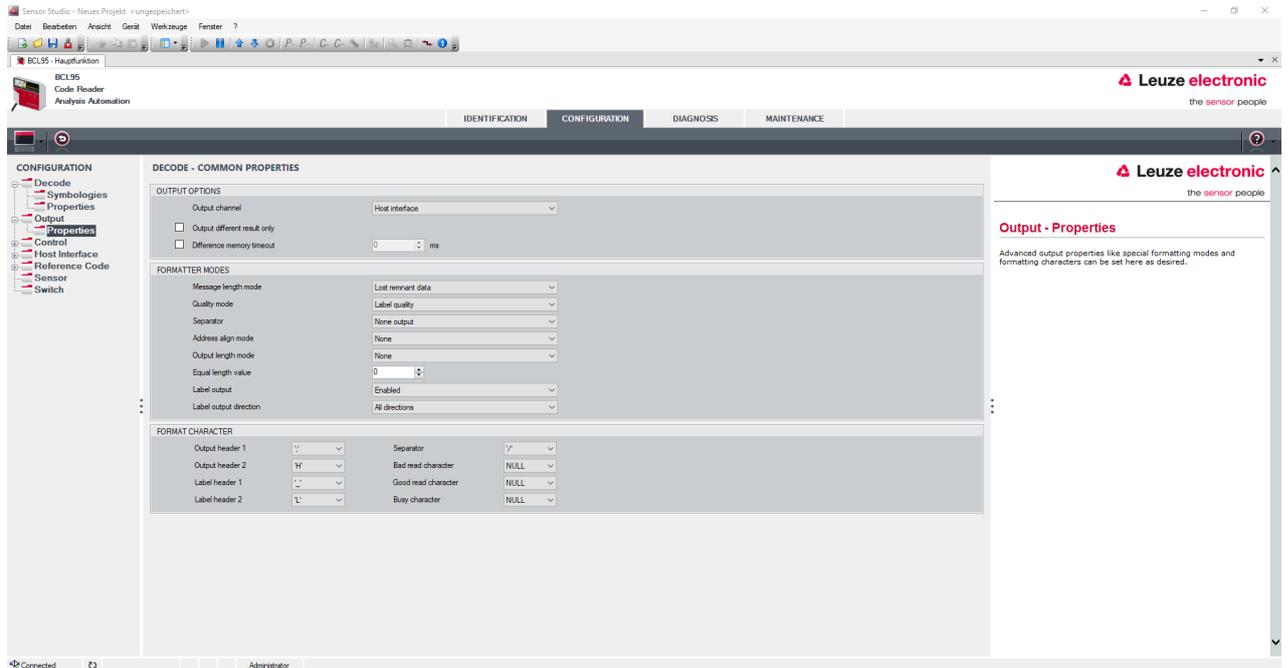


Fig. 6.14: **Properties** dialog box (COMMON PROPERTIES)

|  |   |
|--|---|
| <p>Communication settings<br/>(Output channel)</p>   | <p>Select from one of the options listed.<br/>Standard setting: <i>Host Interface</i></p>   |
| <p>Code output only if the codes/labels are different<br/>(Output different result only)</p> | <p>If you select this setting, a read result is only output within a reading gate opening if it is different than the previous read result.<br/>When rack reading, for example, this is used to set that the codes within adjacent samples are only output once.</p>  |
| <p>Deletion of code output memory<br/>(Difference memory timeout)</p>                        | <p>Selecting this setting deletes the difference memory after the timeout time that can be set to the right of the checkbox has elapsed.<br/>After the timeout time has elapsed, a detected label is output a second time even if it was already directly detected once and the <i>Output different result only</i> checkbox is selected.<br/><br/>The timeout time between the last reading and deletion of the difference memory can be set from 100 ms to 5000 ms.</p> |

6.5.3 Control tab

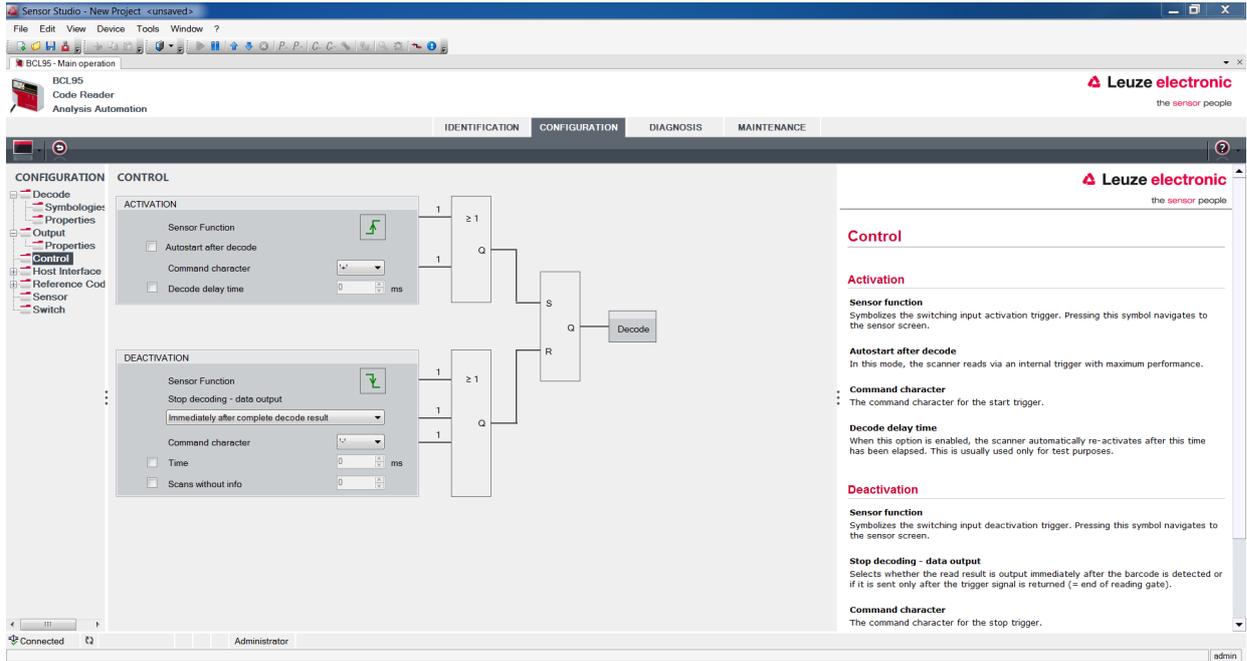


Fig. 6.7: Control tab

Activation

|   |  |
|---|--|
| Switching input 1 Function                          | See menu <b>switching input</b>  |
| Auto-start after decoding<br>Autostart after decode | In this mode, the scanner reads via an internal trigger signal with maximum performance.<br><b>Note:</b> Up to 100 codes per second can be transmitted.  |
| Command character                                   | The standard online character for the trigger start is the '+' character. The character cannot be changed.   |
| Decode delay time                                   | After the time set here has passed, the scanner automatically reactivates itself following a reading gate end (e.g. in combination with Autostart after decode). Is normally used for test purposes. |

Deactivation

|   |  |
|---|--|
| Switching input 1 Function                                  | See menu <b>switching input</b>  |
| Immediately after the complete decoding result is available | If the setting is activated, the read result is output immediately after the bar code is decoded.<br>If the setting is deactivated, the read result is sent only after the trigger signal is returned (= end of reading gate). |
| Command character   | The standard online character for the trigger end is the '-' character. The character cannot be changed.   |
| Time  | If the code reader is activated, the reading gate is automatically closed by the code reader after this preset time has elapsed (e.g. for test purposes).  |
| Scans without info  | Following a successful read, the code reader waits for this number of scans (sequential scans with no read result) before it automatically deactivates itself.   |

6.5.4 Host interface tab

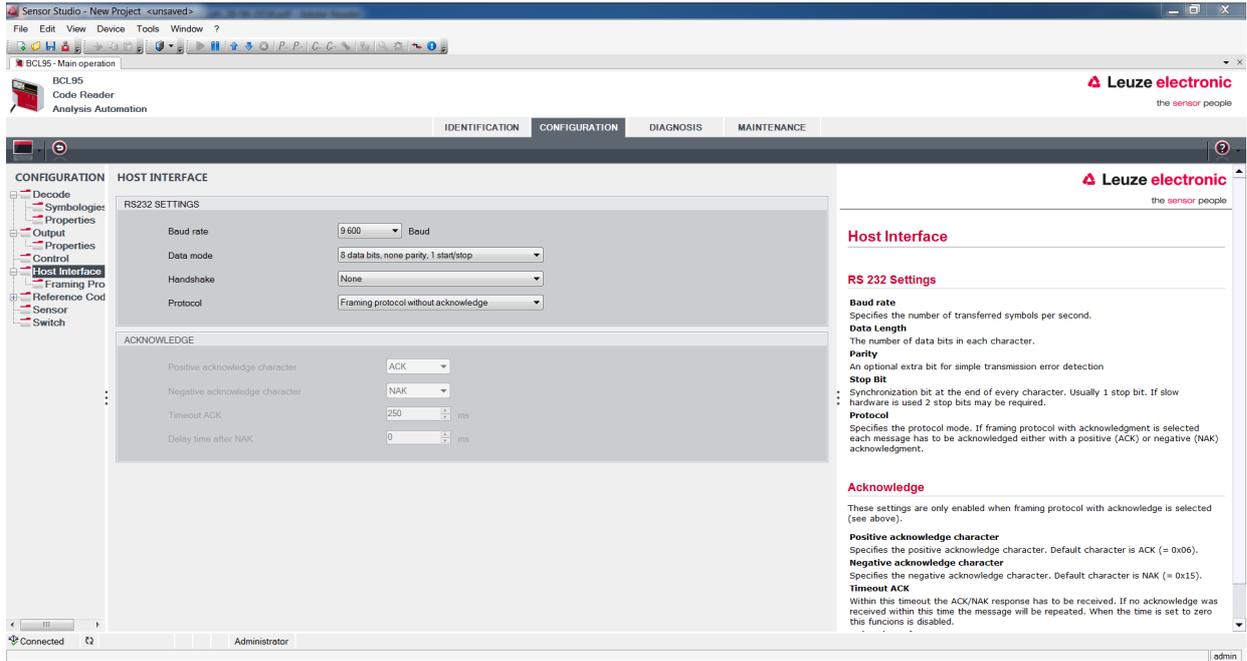


Fig. 6.8: Host Interface tab

Select the desired baud rate, the stop bits, the data bits, the parity and various transmission modes here. The parameters are not active until these settings have been transferred to the code reader (standard procedure).

The desired acknowledgment settings are also to be set in this selection window.

Properties dialog box (Framing Protocol)

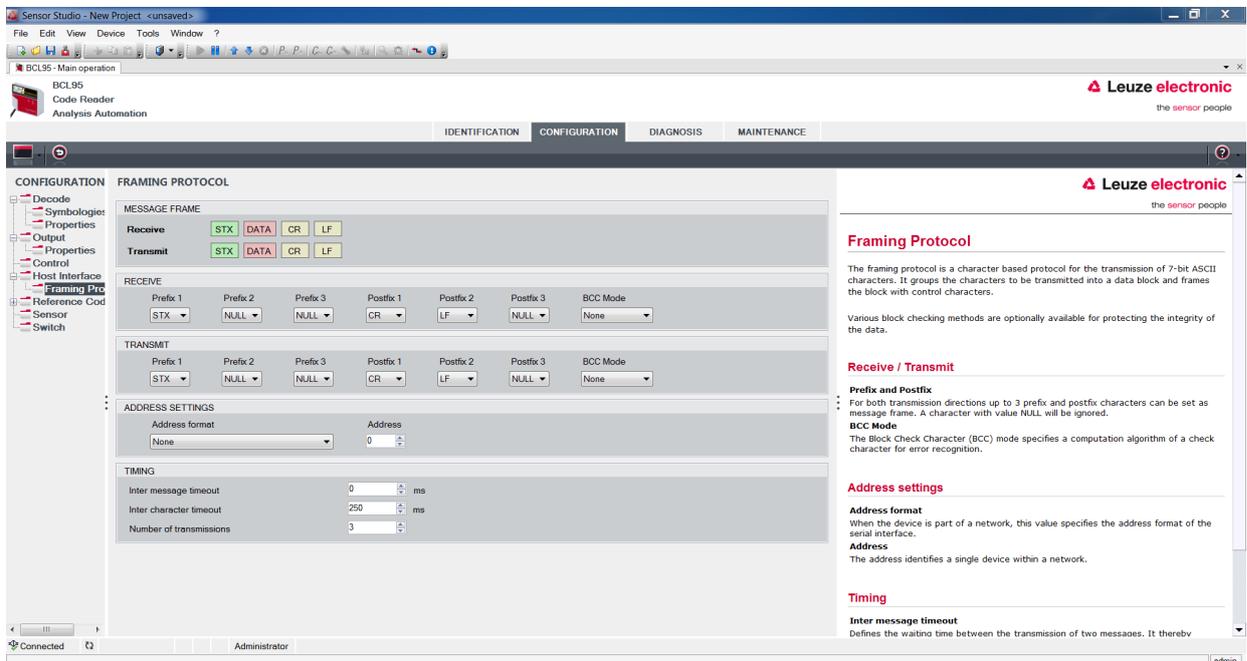


Fig. 6.9: Standard settings of the Properties dialog box (FRAMING PROTOCOL)

Here, you can change the address settings and the protocol for sending and receiving.

**NOTICE**

i

To be able to continue to communicate with a device following a parameter transfer, you may need to make appropriate adjustments to the communication properties of the device in the *Sensor Studio* configuration software.

6.5.5 Reference code tab

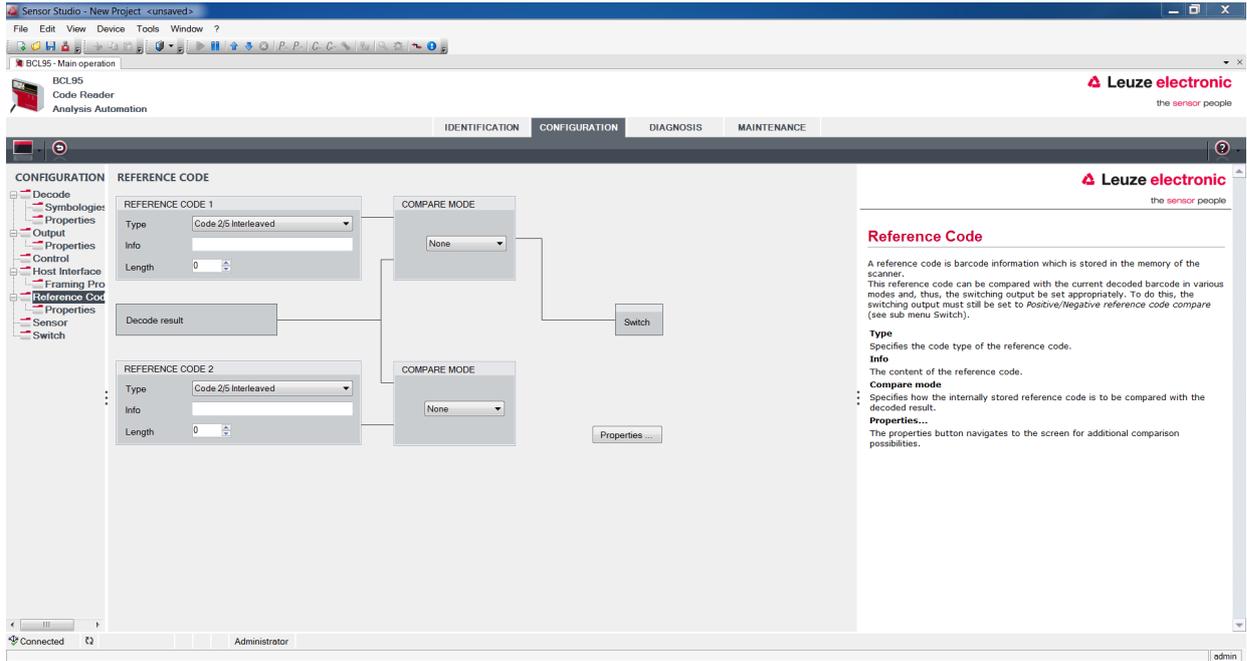


Fig. 6.10: Reference Code tab

A reference code is bar code information which is stored in the memory of the scanner.

The reference code can be compared with the current decoded bar code in various modes and, thus, the switching output be set appropriately. For this purpose, the switching output must be set to **Reference Code Compare (Positive Reference Code Compare or Negative Reference Code Compare)** in the **switching output (switch)** menu.

One possibility to save the reference code is to manually enter the value in this menu. For other possibilities offered by the reference code teach-in, see chapter 8 "Online commands".

|                 |  |
|-----------------|--|
| Type            | Selection of code type.  |
| Contents (Info) | Contents of the reference code.  |
| Comparison mode | Select here how the internally stored reference code is to be compared with the decoded result.<br>For additional comparison possibilities, select the <b>Properties</b> dialog box. |

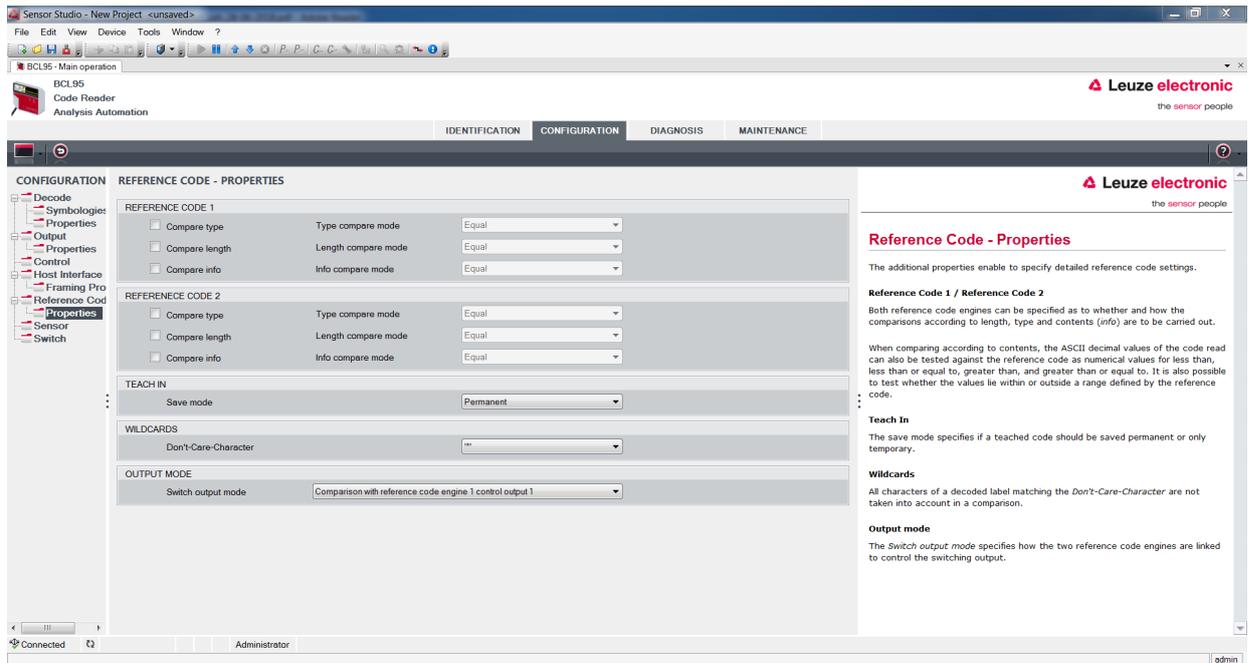


Fig. 6.11: Standard settings of the **Properties** dialog box (PROPERTIES)

6.5.6 Switching input tab

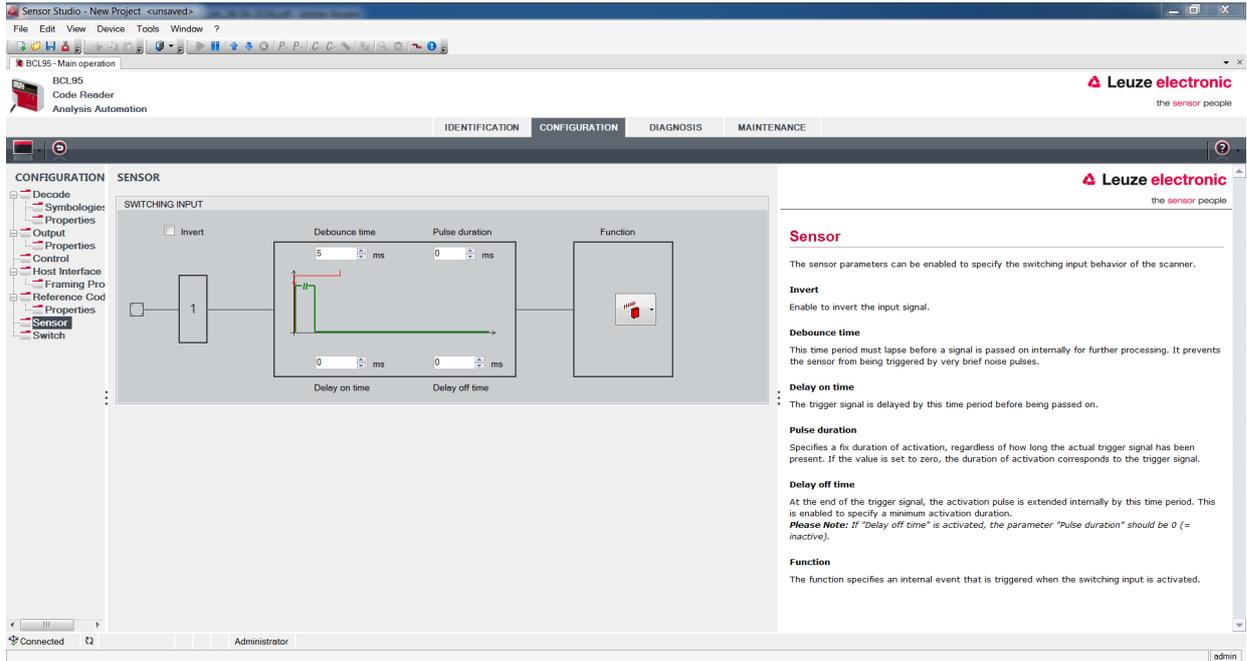


Fig. 6.12: Switching input tab

|   |  |
|---|--|
| Inverted                                | Here, the input level can be inverted  |
| Debounce time                           | This time period must lapse until the trigger signal is regarded as valid.   |
| Start-up delay<br>(Start-up delay time) | The trigger signal is passed on delayed by the specified time period.  |
| Pulse duration                          | If the value is higher than "0": duration of the activation, regardless of how long the trigger signal has been applied. |
| Switch-off delay<br>(Delay off time)    | After the end of the trigger signal, the pulse is extended internally by this time period.                               |
| Function<br>(Control)                   | Event that is started when the switching input is activated.   |

| <b>NOTICE</b>   |  |
|---|--|
|  | If switch-off delay is activated, the <i>pulse duration</i> parameter should be "0". |

6.5.7 Switching output tab

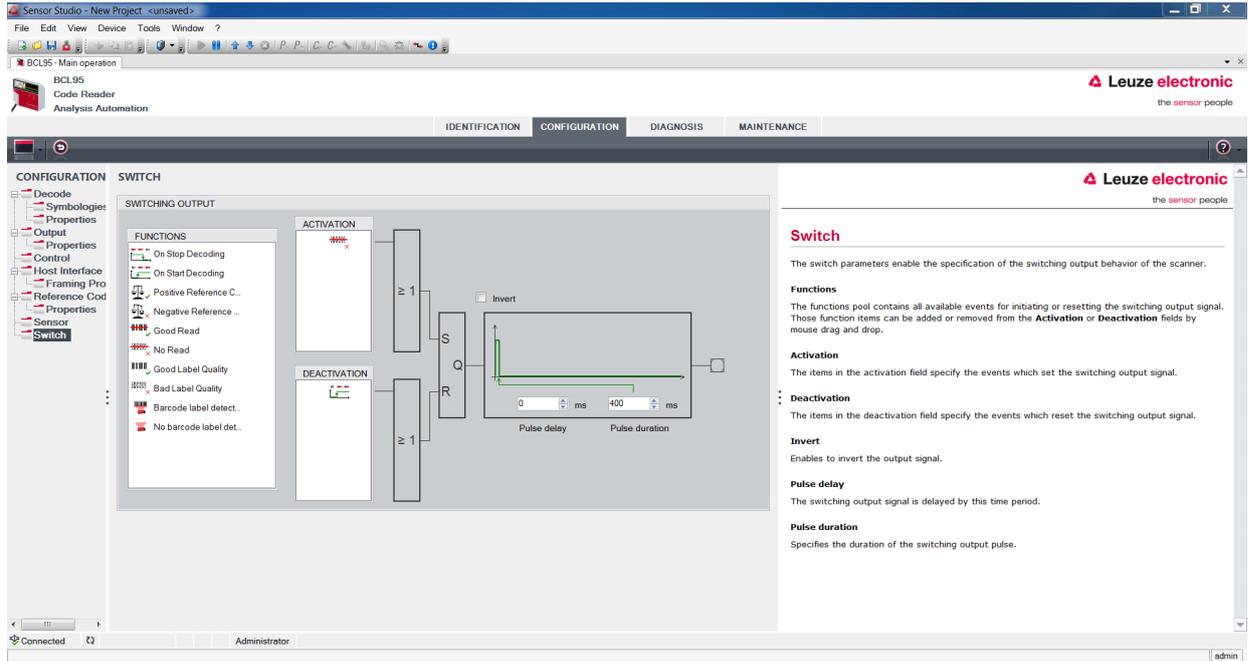


Fig. 6.13: Switching output tab

|                                   |   |
|-----------------------------------|---|
| Activation                        | Select the desired event which is to initiate the switching of the switching output here.<br>Multiple events can also be simultaneously activated.                                |
| Deactivation                      | Shown here is the event which results in the switching output being reset if the set pulse duration has not yet expired.<br>Multiple events can also be simultaneously activated. |
| Inverted                          | Here, the input level can be inverted   |
| Pulse duration                    | Duration of the switching output pulse.   |
| Pulse delay<br>(Pulse delay time) | Length of time before the switching output is activated.  |

## 6.6 Diagnosis

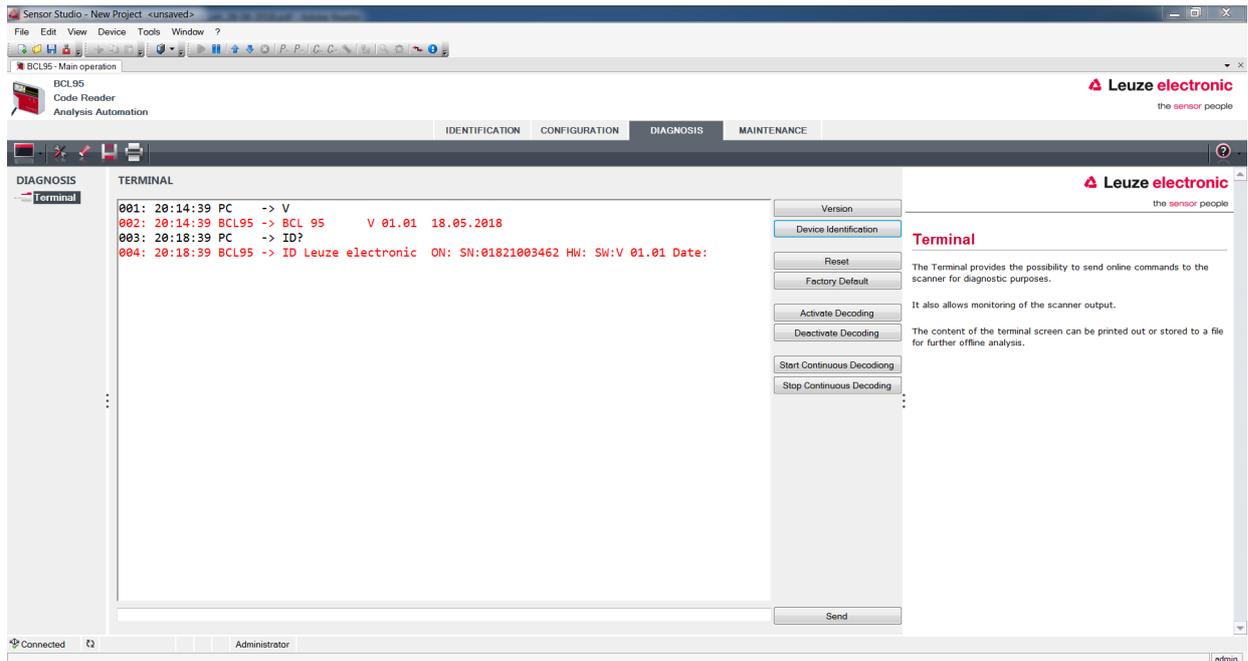


Fig. 6.14: *Diagnosis* tab

On the *Diagnosis* tab, you can send online commands to the device see chapter 8 "Online commands" as well as display the read results and the device status.

Furthermore, buttons are available for the following functions:

- Layout of the screen display
- Deleting and printing the screen content
- General terminal settings

|   |   |
|---|---|
| Version   | Requests device version information (see chapter 8.2 "General online commands", command "V").<br>You can use this command to check whether the communication between PC and scanner is functional. If you do not receive an acknowledgment, please check the interface connections or the protocol. |
| Device Identification                                 | Query of the serial number as well as the hardware and software versions.   |
| Reset   | Carries out a software reset. The device is restarted and reinitialized, leaving it in the same state as when the operating voltage is switched on.   |
| Factory Default                                       | Activates the device with the factory settings.   |
| Activate Decoding<br>Deactivate Decoding              | Activates/deactivates decoding.   |
| Start Continuous Decoding<br>Stop Continuous Decoding | Starts/stops continuous decoding.   |

## 6.7 Firmware Reload

With the *Firmware Reload* tool (*MAINTENANCE* tab), you can load a different firmware into the device.

**NOTICE**



You can find detailed information on the *Firmware Reload* tool in the information area of the **FIRMWARE RELOAD** dialog box and in the *Sensor Studio* online help.

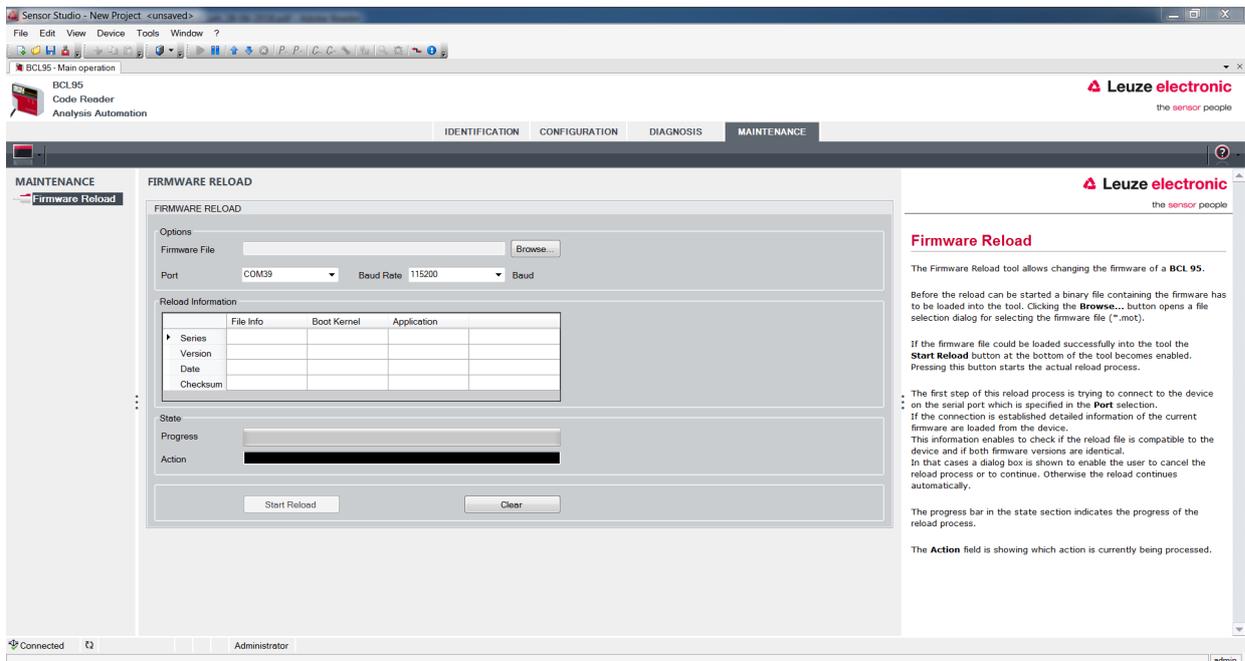


Fig. 6.15: Firmware Reload

- ↳ Load the file with the new firmware (\*.mot) in the *Firmware Reload* tool. Click the [Browse] button. A dialog box for selecting the firmware file (\*.mot) opens.
- ↳ Once the firmware file is loaded in the *Firmware Reload* tool, click on the [Start Reload] button to load the new firmware into the device.
  - The device is connected via the serial interface specified under **Port**.
  - The *Firmware Reload* tool checks whether the new firmware is compatible with the device.
    - If the new firmware is compatible, the firmware is automatically installed in the device.
    - If the new firmware is not compatible with the device or is identical with the current firmware version, a dialog box for canceling or continuing the installation is displayed.

## 7 Starting up the device - Configuration

### 7.1 Measures to be performed prior to the initial commissioning

| <b>NOTICE</b>   |  |
|---|--|
|  | <ul style="list-style-type: none"> <li>↳ Observe the notices for device arrangement (see chapter 4.1 "Selecting a mounting location").</li> <li>↳ If possible, always trigger the bar code reader with the aid of commands or an external transducer (photoelectric sensor).                             <ul style="list-style-type: none"> <li>⇒ Only then can you be certain whether a code has been read (code contents are transmitted) or not (the <b>NoRead</b> character is transmitted at the end of the reading gate).</li> </ul> </li> <li>↳ Before commissioning, familiarize yourself with the operation and configuration of the device.</li> <li>↳ Before connecting the operating voltage, recheck all connections and ensure that they have been properly made.</li> </ul> |

### 7.2 Starting the device

#### 7.2.1 Power-on test

After connecting the operating voltage, the bar code reader performs an automatic "Power On" function test.

- During the start-up phase, the status LED flashes green.
- If the status LED is permanently lit green, the bar code reader is ready for operation. Any stored customer-specific settings are active.

#### 7.2.2 Interface

Proper function of the interface can most easily be tested in service operation using the RS 232 interface with the *Sensor Studio* configuration software.

#### 7.2.3 Online commands

Using the online commands, important device functions can be checked, e.g. reading activation (see chapter 8 "Online commands").

You can use online commands to directly send control and configuration commands to the device.

You can send online commands with a terminal program or with the *Sensor Studio* configuration software (see chapter 6 "Configuration and diagnostics software - Sensor Studio").

#### 7.2.4 Problems

For information on how to proceed in the event of problems during commissioning of the devices, see chapter 10 "Diagnostics and troubleshooting".

If a problem occurs that cannot be rectified even after checking all electrical connections and settings on the devices and on the host, contact your responsible Leuze electronic subsidiary or Leuze electronic customer service (see chapter 11 "Service and support").

### 7.3 Starting up with factory settings

- ↪ Connect the 5 V DC operating voltage.
- ↪ If applicable, connect the switching input and the RS 232 interface.
- ↪ Switch on the operating voltage. The status LED must illuminate green.
- ↪ Activate the bar code reader via the switching input or with the '+' online command. The laser switches itself on.
- ↪ Hold the following sample bar code up to the bar code reader at a distance >25 mm ... <150 mm.



- ↪ If reading is successful, the laser switches off. The read result is displayed on the monitor of the connected device.
- ↪ Deactivate the reading gate by removing the switching input signal or with the '-' online command.

### 7.4 Setting the configuration parameters

You commissioned the device. Usually, you will have to configure it before you can use it. With the configuration possibilities offered by the *Sensor Studio* configuration software or the device DTM, you can individually adapt the device to your specific application. For instructions regarding the various setting options, refer to the online help or to the see chapter 6.5 "Configuration parameters".

- To operate the bar code reader, it is normally sufficient to set code type and code length in accordance with the bar codes that are to be read.
- Depending on the application, you can configure the switching input according to your requirements.

#### Configuration settings

The configuration settings are stored in the memory of the bar code reader in parameter sets. The various parameter sets are explained to understand what is happening during configuration parameter setting (see chapter 7.4.2 "Parameter sets").

- The setting of code type and code length is usually accomplished by using the *Sensor Studio* configuration software (see chapter 6 "Configuration and diagnostics software - Sensor Studio").
- You can set other configuration parameters as follows:
  - Via the *Sensor Studio* configuration software with the buttons located under **CONFIGURATION**.
  - Via the internal setup of the bar code reader (start with the online command **CS**; see chapter 7.4.2 "Parameter sets")
  - Via online commands (see chapter 8.4 "Online commands for the parameter set operations").

#### 7.4.1 Service mode

You can connect a PC or a terminal to the device via the RS 232 interface and configure the device through this connection (see chapter 5.7 "PC or terminal connection").

Setting the required parameters is carried out easiest in the 'Service' operating mode.

The Service mode provides the following defined operating parameters on the RS 232 interface, no matter how the device is configured for process mode:

- Transmission rate: 9600 baud
- No parity
- 8 data bits
- 1 stop bit
- Prefix: STX
- Postfix: CR, LF

**Activate service interface**

The service interface can be activated by holding a defined bar code label in front of the reading window during power-up (initialization phase).



Fig. 7.1: Bar code label "Service"

- ☞ While the laser switches on for approx. 1 s after power-up, the "Service" label is to be held up in front of the bar code reader at a suitable read distance. When the device is in "Service" mode, the status LED flashes orange.

**7.4.2 Parameter sets**

The configuration settings are stored in the memory of the bar code reader in parameter sets.

- Factory default parameter set
- Current parameter set

**Factory default parameter set**

This parameter set contains the factory-set default settings for all parameters of the bar code reader. It is permanently stored in the FLASH ROM of the bar code reader.

The parameter set with the default settings is loaded into the memory of the bar code reader:

- The first time the device is commissioned after delivery
- With the *Sensor Studio* configuration software via the [Factory Default] button in the **DIAGNOSIS** menu.
- After the online command **PC20** (see chapter 8.4 "Online commands for the parameter set operations")
- If the checksums of the current parameter set are invalid

**Current parameter set**

In this parameter set, the current settings for all device parameters are stored. When the bar code reader is in operation, the current parameter set is stored in the EEPROM of the bar code reader.

The current parameter set is loaded into the main memory of the bar code reader with the **Copy parameter set** parameter set command (see chapter 8.4 "Online commands for the parameter set operations").

You can save the current parameter set as follows:

- Copying a valid parameter set from the host computer into the bar code reader
- Off-line configuration using the *Sensor Studio* configuration software and then subsequently loading to the bar code reader

|               |   |
|---------------|---|
| <b>NOTICE</b> |   |
|               | To load the configuration into the bar code reader, select online mode. |

## 8 Online commands

You can use online commands to directly send control and configuration commands to the device. To do this, connect the bar code reader to a computer (host) (see chapter 5.7 "PC or terminal connection").

| <b>NOTICE</b>   |  |
|---|--|
|  | You can send online commands with a terminal program or with the <i>Sensor Studio</i> configuration software (see chapter 6 "Configuration and diagnostics software - Sensor Studio"). |

Information about the transmission protocol: see chapter 6.5.4 "Host interface tab".

Using the online commands you can:

- Control/decode the reading gate.
- read/write/copy parameters.
- carry out an automatic configuration.
- Teach-in/set a reference code.
- call up error messages.
- call up statistical device information.
- carry out a software reset in order to reinitialize the device.

| <b>NOTICE</b>  |   |
|--|---|
|  | For diagnostics, you can send online commands to the device via the <i>Sensor Studio</i> configuration software ( <b>DIAGNOSIS &gt; Terminal</b> ). |

### 8.1 Overview of commands and parameters

| <b>NOTICE</b>   |  |
|---|--|
|  | The following chapters describe the input of online commands via a terminal program. To input online commands via the <i>Sensor Studio</i> configuration software see chapter 6 "Configuration and diagnostics software - Sensor Studio" |

#### Syntax

Online commands consist of one or two ASCII characters followed by command parameters.

No separation characters may be entered between the command and the command parameter(s). Both small and capitalized letters can be used.

Tab. 8.1: Syntax example

|                 |                     |
|-----------------|---------------------|
| Command 'CA':   | autoConfig function |
| Parameter '+':  | Activation          |
| Transmitted is: | 'CA+'               |

#### Notation

Commands, parameters and returned data are enclosed between single quotation marks ' ' in the text of this manual.

| <b>NOTICE</b>   |   |
|---|---|
|  | Most online commands are acknowledged by the device and any requested data returned. For commands that are not acknowledged, command execution can be observed or monitored directly on the device. |

## 8.2 General online commands

### Software version number

|                |   |
|----------------|---|
| Command        | 'V'   |
| Description    | Requests device version information   |
| Parameter      | None  |
| Acknowledgment | Example: 'BCL 95 V 01.15 17.05.2018'<br>The first line contains the device type of the bar code reader, followed by the device version number and version date. The data which is actually displayed may vary from the values given here. |

#### **NOTICE**



You can use this command to check whether the communication between PC and scanner is functional. If you do not receive an acknowledgment, please check the interface connections or the protocol.

### Software reset

|                |   |
|----------------|---|
| Command        | 'H'   |
| Description    | Carries out a software reset. The device is restarted and reinitialized, leaving it in the same state as when the operating voltage is switched on. |
| Parameter      | None  |
| Acknowledgment | 'S' (start signal)  |

autoConfig

|                |   |   |                                       |
|----------------|---|---|---------------------------------------|
| Command        | 'CA'  |   |                                       |
| Description    | Activates or deactivates the <i>autoConfig</i> function. Certain bar code recognition parameters are programmed automatically in the setup by the bar code labels which the device reads while the 'autoConfig' function is active. |   |                                       |
| Parameter      | '+'   | Activates 'autoConfig'  |                                       |
|                | '/'   | Rejects the last code read  |                                       |
|                | '-'   | Deactivates 'autoConfig' and stores the decoded data in the current parameter set |                                       |
| Acknowledgment | 'CSx'   |   |                                       |
|                | x   | Status  |                                       |
|                |   | '0'   | valid 'CA' command                    |
|                |   | '1'   | Invalid command                       |
|                |   | '2'   | 'autoConfig' could not be activated   |
|                |   | '3'   | 'autoConfig' could not be deactivated |
|                |   | '4'   | Result could not be deleted           |
| Description    | 'xx yy zzzzzz'  |   |                                       |
|                | xx  | Code type of the read code  |                                       |
|                |   | '01'  | 2/5 Interleaved                       |
|                |   | '02'  | Code 39                               |
|                |   | '03'  | Code 32                               |
|                |   | '06'  | UPC-A / UPC-E                         |
|                |   | '07'  | EAN-8 / EAN-13                        |
|                |   | '08'  | Code 128, EAN 128                     |
|                |   | '09'  | Pharmacode                            |
|                |   | '10'  | EAN Addendum                          |
|                |   | '11'  | Codabar                               |
|                |   | '12'  | Code 93                               |
|                | yy  | Number of digits of the read code   |                                       |
|                | zzzzzz  | Contents of the decoded label. A ↑ appears if the label was not correctly read.   |                                       |

**Manual definition of the reference code**

|                |   |                                      |  |
|----------------|---|--------------------------------------|--|
| Command        | 'RS'  |                                      |  |
| Description    | This command can be used to define a new reference code in the device by means of direct input via the serial interface. The data is saved in the parameter set according to your input under reference code 1 or 2 and stored in the working buffer for direct further processing. |                                      |  |
| Parameter      | 'RSyvxxzzzzzzzz'  |                                      |  |
|                | y, v, x and z are placeholders (variables) for the actual input.  |                                      |  |
|                | y   | Def. reference code no.              |  |
|                |   | '1'                                  | (code 1)                               |
|                |   | '2'                                  | (code 2)                               |
|                | v   | Storage location for reference code: |  |
|                |   | '0'                                  | RAM+EEPROM                             |
|                |   | '3'                                  | RAM only                               |
|                | xx  | Def. code type (see command 'CA')    |  |
| z              | Def. code information (1 ... 30 characters)   |                                      |  |
| Acknowledgment | 'RSx'   |                                      |  |
|                | x   | Status                               |  |
|                |   | '0'                                  | Invalid Rx command                     |
|                |   | '1'                                  | Invalid command                        |
|                |   | '2'                                  | Insufficient memory for reference code |
|                |   | '3'                                  | Reference code has not been saved      |
|                |   | '4'                                  | Reference code invalid                 |
| Example        | Entry = 'RS130678654331'<br>• Code 1 (1)<br>• RAM only (3)<br>• UPC (06)<br>• Code information  |                                      |  |

Teach-in

|                |  |                                      |   |
|----------------|--|--------------------------------------|---|
| Command        | 'RT'   |                                      |   |
| Description    | This command enables a reference code to be defined quickly by reading an example label.   |                                      |   |
| Parameter      | 'RTy'  |                                      |   |
|                | y  | Function                             |   |
|                |  | '1'                                  | Defines reference code 1                          |
|                |  | '2'                                  | Defines reference code 2                          |
|                |  | '+'                                  | Activates the definition of reference code 1 or 2 |
|                |  | '.'                                  | Ends the teach event                              |
| Acknowledgment | The device first responds with the command 'RS' and corresponding status (see command 'RS'). After a bar code has been read, it sends the result in the following format:<br>'RCyvxxzzzzz' |                                      |   |
|                | y, v, x and z are placeholders (variables) for the actual input.   |                                      |   |
|                | y  | Def. reference code no.              |   |
|                |  | '1'                                  | (code 1)  |
|                |  | '2'                                  | (code 2)  |
|                | v  | Storage location for reference code: |   |
|                |  | '0'                                  | RAM+EEPROM  |
|                |  | '3'                                  | RAM only  |
| xx             | Def. code type (see command 'CA')  |                                      |   |
| z              | Def. code information (1 ... 30 characters)  |                                      |   |

**NOTICE**



With this function, only code types are recognized that are identified using the 'autoConfig' function or which were set in the set-up.

⚠ After each reading via an 'RTy' command, explicitly switch off the function again since failure to do so will interfere with other commands as well as prevent execution of a new 'RTy' command.

**Reading a reference code**

|                |  |                                      |
|----------------|--|--------------------------------------|
| Command        | 'RR'   |                                      |
| Description    | The command reads out the reference code defined in the device. If no parameters are specified, all defined codes are output.  |                                      |
| Parameter      | <reference code number>  |                                      |
|                | '1'  | Reference code 1                     |
|                | '2'  | Reference code 2                     |
| Acknowledgment | If no reference codes are defined, the device responds with the 'RS' command and corresponding status (see command 'RS').<br>With valid codes, output is in the following format:<br>'RCyvxxzzzzz' |                                      |
|                | y, v, x and z are placeholders (variables) for the actual input.   |                                      |
|                | y  | Def. reference code no.              |
|                |  | '1' (code 1)                         |
|                |  | '2' (code 2)                         |
|                | v  | Storage location for reference code: |
|                |  | '0' RAM+EEPROM                       |
|                |  | '3' RAM only                         |
|                | xx   | Def. code type (see command 'CA')    |
| z              | Def. code information (1 ... 30 characters)  |                                      |

**Alignment mode**

|                |   |  |
|----------------|---|--|
| Command        | 'JP'  |  |
| Description    | This command is used for simplified mounting and alignment of the device in static installation situations. After activating the function with 'JP+', the scanner continuously supplies status information to the serial interfaces. With this on-line command, the scanner is set to terminate the decoding after 100 successfully decoded labels and output the status information. Subsequently, the read process is reactivated automatically.<br>As status, the output returns the following values: <ul style="list-style-type: none"> <li>• Scans which contain the valid label information on the basis of 100 scans</li> <li>• Decoding result</li> </ul> These values can be used to determine the decoding quality: <ul style="list-style-type: none"> <li>• If the reading quality is high, the laser beam flashes in brief, regular intervals.</li> <li>• The worse the decoder decodes, the longer the pauses become during which the laser light is switched off.</li> </ul> |  |
| Parameter      | '+'   | Starts the adjustment mode.  |
|                | '-'   | Ends the adjustment mode.  |
| Acknowledgment | 'xxxxx_yyyyy'   |  |
|                | xxxxx   | "Scans since reading gate release" (Scans_with info):<br>Number of scans that contain valid label information. The maximum value is 100. |
|                | yyyyy   | Bar code information.  |

### 8.3 Online commands for system control

#### Activate sensor input

|                |                                 |
|----------------|---------------------------------|
| Command        | '+'                             |
| Description    | The command activates decoding. |
| Parameter      | No                              |
| Acknowledgment | None                            |

#### Deactivate sensor input

|                |                                 |
|----------------|---------------------------------|
| Command        | '-'                             |
| Description    | The command activates decoding. |
| Parameter      | No                              |
| Acknowledgment | None                            |

#### Activate continuous decoding

|                |   |
|----------------|---|
| Command        | 'C+'  |
| Description    | The command activates continuous decoding (continuous reading). |
| Parameter      | No  |
| Acknowledgment | None  |

#### Deactivate continuous decoding

|                |   |
|----------------|---|
| Command        | 'C-'  |
| Description    | The command deactivates continuous decoding (end continuous reading). |
| Parameter      | No  |
| Acknowledgment | None  |

#### Activate switching output

|                |   |                      |            |
|----------------|---|----------------------|------------|
| Command        | 'OA'  |                      |            |
| Description    | The command activates the switching output. |                      |            |
| Parameter      | 'OAx': Activate switching output            |                      |            |
|                | x   | Switching output no. |            |
|                |   | '1'                  | (Output 1) |
| Acknowledgment | None  |                      |            |

#### Deactivate switching output

|                |   |                      |            |
|----------------|---|----------------------|------------|
| Command        | 'OD'  |                      |            |
| Description    | The command deactivates the switching output. |                      |            |
| Parameter      | 'ODx': Deactivate switching output            |                      |            |
|                | x   | Switching output no. |            |
|                |   | '1'                  | (Output 1) |
| Acknowledgment | None  |                      |            |

## 8.4 Online commands for the parameter set operations

### Definitions

- **<BCC type>** Type of checksum calculation.
  - '0': No checksum
  - '3': XOR checksum (mode 3)
- **<PS type>** Parameter set type
  - '0': Current parameter set (data stored in the EEPROM (non-volatile))
  - '1': Reserved
  - '2': Standard parameter set (not changeable)
  - '3': Operating values (data in the RAM, will be lost after reset)
- **<Status>** Mode of parameter processing
  - '0': Does not perform a reset following the write operation; no other parameters follow.
  - '1': Does not perform a reset following the write operation; other parameters follow.
  - '2': Subsequently performs a reset, no additional parameters follow.
- **<Start address>** Relative address of the parameter within the parameter set
- **<Para0L> <Para0H>... <Para122L> <Para122H>**:  
 Parameter set data of the message. The sequence of the data is arranged identically to the device, i.e. when a word is transmitted, first the low byte is sent then the high byte. The parameter set data is converted for transmission from HEX format to a 2-byte-ASCII format. During the conversion, two ASCII characters – representing the *lower nibble* and the *higher nibble* – are created for each HEX value.

Example:

| Decimal | Hex    | Transmission                      |
|---------|--------|-----------------------------------|
| 4660    | 0x1234 | '1' '2' '3' '4' = 31h 32h 33h 34h |

- Para0H = 31h, Para0L = 32h, Para1H = 33h, Para1L = 34h  
 Taking into consideration the maximum message length and the remaining command parameters, a maximum of 123 bytes on parameter data (246 bytes on message data) can be transmitted in a single operation.  
 Valid values: '0' ... '9', 'A' ... 'F'
- **<Acknowledgment>**:  
 Acknowledgment of the transmitted message
  - '0': Valid transfer
  - '1': Invalid message
  - '2': Invalid message length
  - '3': Invalid block check type
  - '4': Invalid bloc checksum
  - '5': Invalid data length
  - '6': Invalid message data
  - '7': Invalid start address
  - '8': Invalid parameter set
  - '9': Invalid parameter set type

**Copying parameter set**

|                |  |   |                              |
|----------------|--|---|------------------------------|
| Command        | 'PC'   |   |                              |
| Description    | The command copies complete parameter sets.              |   |                              |
| Parameter      | '03'   | Copy parameters from the EEPROM into the RAM and initialize all associated functions                  |                              |
|                | '20'   | Copy standard parameters from the FLASH into the EEPROM and RAM and initialize all relevant functions |                              |
|                | '30'   | Copy parameters from the RAM into the EEPROM  |                              |
| Acknowledgment | 'PSx'  |   |                              |
|                | x  | Status  |                              |
|                |  | '0'   | Valid transfer               |
|                |  | '1'   | Invalid message              |
|                |  | '2'   | Invalid message length       |
|                |  | '3'   | Invalid block check type     |
|                |  | '4'   | Invalid block check checksum |
|                |  | '5'   | Invalid data length          |
|                |  | '6'   | Invalid message data         |
|                |  | '7'   | Invalid start address        |
|                |  | '8'   | Invalid parameter set        |
|                | '9'  | Invalid parameter type  |                              |
| Example        | 'PC20' loads the default parameter set (factory setting) |   |                              |

**Requesting parameter set from device**

|                |   |                        |                              |
|----------------|---|------------------------|------------------------------|
| Command        | 'PR'  |                        |                              |
| Description    | The command requests the parameter data from the device. The <PS type> parameter indicates from which parameter set the data are to be transferred. |                        |                              |
| Parameter      | <BCC type> <PS type> <Start address> <Data length>  |                        |                              |
| Acknowledgment | 'PSx'   |                        |                              |
|                | x   | Status                 |                              |
|                |   | '0'                    | Valid transfer               |
|                |   | '1'                    | Invalid message              |
|                |   | '2'                    | Invalid message length       |
|                |   | '3'                    | Invalid block check type     |
|                |   | '4'                    | Invalid block check checksum |
|                |   | '5'                    | Invalid data length          |
|                |   | '6'                    | Invalid message data         |
|                |   | '7'                    | Invalid start address        |
|                |   | '8'                    | Invalid parameter set        |
|                | '9'   | Invalid parameter type |                              |
| Example        | 'PR00102004'<br>Beginning with address 102, four (004) bytes are read out and transferred.  |                        |                              |

**Acknowledge parameter message**

|             |   |                        |                              |
|-------------|---|------------------------|------------------------------|
| Command     | 'PS'  |                        |                              |
| Description | The command acknowledges the received message and delivers an acknowledgment status which indicates whether the message was valid or invalid. |                        |                              |
| Parameter   | 'PSx'   |                        |                              |
|             | x   | Status                 |                              |
|             |   | '0'                    | Valid transfer               |
|             |   | '1'                    | Invalid message              |
|             |   | '2'                    | Invalid message length       |
|             |   | '3'                    | Invalid block check type     |
|             |   | '4'                    | Invalid block check checksum |
|             |   | '5'                    | Invalid data length          |
|             |   | '6'                    | Invalid message data         |
|             |   | '7'                    | Invalid start address        |
|             |   | '8'                    | Invalid parameter set        |
|             | '9'   | Invalid parameter type |                              |

**Transfer parameters**

|                |  |                        |                              |
|----------------|--|------------------------|------------------------------|
| Command        | 'PT'   |                        |                              |
| Description    | <p>The command transmits parameter data starting from the defined address and stores them in an intermediate buffer.</p> <p>If the status indicates that further messages follow, these are also stored in the intermediate buffer before they are then stored under the corresponding parameter set type in the EEPROM.</p> <p>The transmission can optionally occur with a block check test of the message data.</p> |                        |                              |
| Parameter      | <p>&lt;BCC type&gt; &lt;PS type&gt; &lt;Status&gt; &lt;Start address&gt; &lt;Para0L&gt; &lt;Para0H&gt; [... &lt;Para122L&gt;][&lt;BCC&gt;]</p>   |                        |                              |
| Acknowledgment | 'PSx'  |                        |                              |
|                | x  | Status                 |                              |
|                |  | '0'                    | Valid transfer               |
|                |  | '1'                    | Invalid message              |
|                |  | '2'                    | Invalid message length       |
|                |  | '3'                    | Invalid block check type     |
|                |  | '4'                    | Invalid block check checksum |
|                |  | '5'                    | Invalid data length          |
|                |  | '6'                    | Invalid message data         |
|                |  | '7'                    | Invalid start address        |
|                |  | '8'                    | Invalid parameter set        |
|                | '9'  | Invalid parameter type |                              |
| Example        | <p>'PT03203305'</p> <p>Address 33 (equal scans) is set to 5. Save in RAM with reset (immediate acceptance of the change and temporary storage)</p>   |                        |                              |

## 9 Care, maintenance and disposal

### Cleaning

Clean the glass window of the bar code reader with a soft, lint-free cloth before mounting if necessary.

#### NOTICE



#### Do not use aggressive cleaning agents!

↪ Do not use aggressive cleaning agents such as thinner or acetone for cleaning the device.

#### NOTICE



↪ To clean the optics cover, use only a lint-free cloth.  
Tips and hard objects damage the lens.

### Maintenance

Usually, the bar code reader does not require any maintenance by the operator.

Repairs to the device must only be carried out by the manufacturer.

↪ For repairs, contact your responsible Leuze electronic subsidiary or Leuze electronic customer service (see chapter 11 "Service and support").

### Firmware Reload

You can load a different firmware into the device using the *Sensor Studio* configuration software (see chapter 6.7 "Firmware Reload").

### Disposing

↪ For disposal observe the applicable national regulations regarding electronic components.

## 10 Diagnostics and troubleshooting

The LED displays provide information about possible warnings or errors (see chapter 3.5 "Display elements"). Using the LED displays, you can determine the causes and initiate trouble shooting measures.

| <b>NOTICE</b>   |  |
|---|--|
|  | <p><b>Contact Leuze electronic subsidiary/customer service</b></p> <p>↳ Please contact your responsible Leuze electronic subsidiary or Leuze electronic customer service if you cannot rectify faults and errors with the configuration software (see chapter 11 "Service and support").</p> |

Tab. 10.1: Status LED

| Error                     | Possible error cause                       | Measures  |
|---------------------------|--|---|
| Off                       | No supply voltage connected to the device. | Check supply voltage.   |
| Red, flashing             | There is a device warning.                 | Query diagnostic data in the device and carry out the resulting measures or reset.  |
| Red, continuous light     | Serious error<br>No function possible.     | Internal device error.<br>Contact Leuze electronic customer service (see chapter 11 "Service and support").   |
| Orange, flashing          | Service operation is active.               | Reset service operation, e.g. by resetting or interrupting the supply voltage.  |
| Error                     | Possible error cause                       | Measures  |
| No communication possible | Incorrect wiring.                          | Check wiring. RxD and TxD cables may be swapped.  |
|                           | Different protocol settings.               | Check protocol settings in the device and in the <i>Sensor Studio</i> configuration software or switch device to the <i>Service</i> operating mode. |
| No code reading possible  | Code reading not possible (quality).       | Improve code quality! Entire code in laser line?  |
|                           | Code is not enabled.                       | Check entries in the code table (code type and length).   |
|                           | Excessive reflections.                     | Increase angle of rotation of the laser beam to > 10° with respect to vertical.   |

## 11 Service and support

**24-hour on-call service at:**

+49 7021 573-0

**Service hotline:**

+49 7021 573-123

Monday to Friday 8.00 a.m. to 5.00 p.m. (UTC+1)

**E-mail:**

service.identify@leuze.de

**Repair service and returns:**

Procedure and Internet form can be found at

[www.leuze.com/repair](http://www.leuze.com/repair)

**Return address for repairs:**

Service center

Leuze electronic GmbH + Co. KG

In der Braike 1

D-73277 Owen / Germany

### 11.1 What to do should servicing be required?

| <b>NOTICE</b>   |   |
|---|---|
|  | <p><b>Please use this chapter as a master copy should servicing be required!</b></p> <p>↪ Enter the contact information and fax this form together with your service order to the fax number given below.</p> |

**Customer data (please complete)**

|                            |  |
|----------------------------|--|
| Device type:               |  |
| Serial number:             |  |
| Firmware:                  |  |
| Status of LEDs:            |  |
| Error description:         |  |
| Company:                   |  |
| Contact person/department: |  |
| Phone (direct dial):       |  |
| Fax:                       |  |
| Street/No:                 |  |
| ZIP code/City:             |  |
| Country:                   |  |

**Leuze Service fax number:**

+49 7021 573 - 199

## 12 Technical data

### 12.1 General specifications

Tab. 12.1: Optics

|   |   |
|---|---|
| Light source  | Laser diode                               |
| Wavelength  | 655 nm (visible red light)                |
| Beam exit   | Frontal or lateral                        |
| Impulse duration<br>(acc. to the measurement conditions in accordance with IEC 60825-1) | <120 $\mu$ s                              |
| Max. output power (peak)  | 2.1 mW                                    |
| Laser class   | 1 acc. to IEC 60825-1:2014                |
| Scanning rate   | 600 scans/s                               |
| Reading distance / reading field width  | see chapter 12.2 "Reading fields"         |
| Resolution  | m = 0.15 mm ... 0.5 mm (6 mil ... 20 mil) |

Tab. 12.2: Code specifications

|                                      |   |
|--------------------------------------|---|
| Code types                           | 2/5 Interleaved, Code 39, Code 128, EAN 128, Pharmacode, Code 93, Codabar, EAN Addendum, Code 32, EAN-8 / EAN-13, UPC-A / UPC-E |
| Module width<br>(distance dependent) | 0.15 mm ... 0.5 mm (6 mil ... 20 mil)   |
| Print quality                        | Grade A, B acc. to ISO/IEC 15416  |
| Angle of rotation                    | > 10°   |

Tab. 12.3: Interfaces

|                        |   |
|------------------------|---|
| Process interface      | RS 232  |
| Baud rate              | 4800 ... 57600 baud   |
| Data formats           | Data bits: 7, 8<br>Parity: none, even, odd<br>Stop bit: 1, 2  |
| Service interface      | RS 232 with fixed data format<br>9600 Bd, 8 data bits, no parity, 1 stop bit<br><STX> <data> <CR><LF> |
| Protocols              | Framing protocol with/without acknowledgment<br>Software handshake X ON / X OFF                       |
| Switching input/output | 1 switching input 5 V DC<br>1 switching output 5 V ... 30 V, 20 mA                                    |

Tab. 12.4: Electrical equipment

|  |   |
|--|---|
| Operating voltage                                      | 4.75 ... 5.5 V DC SELV (Safe Extra Low Voltage) |
| Power consumption                                      | 1.75 W  |
| Current consumption<br>(recommended power supply unit) | Max. 450 mA (peak)<br>Nominal 350 mA at 5 V DC  |
| Switching input  | 5 V DC  |
| Switching output                                       | 5 V ... 30 V, 20 mA                             |

|  |  |
|--|--|
|  <b>CAUTION</b> |  |
|                 | <p><b>UL applications!</b><br/>For UL applications, use is only permitted in LPS/Class 2 circuits in accordance with the NEC (National Electric Code).</p> |

Tab. 12.5: Mechanical data

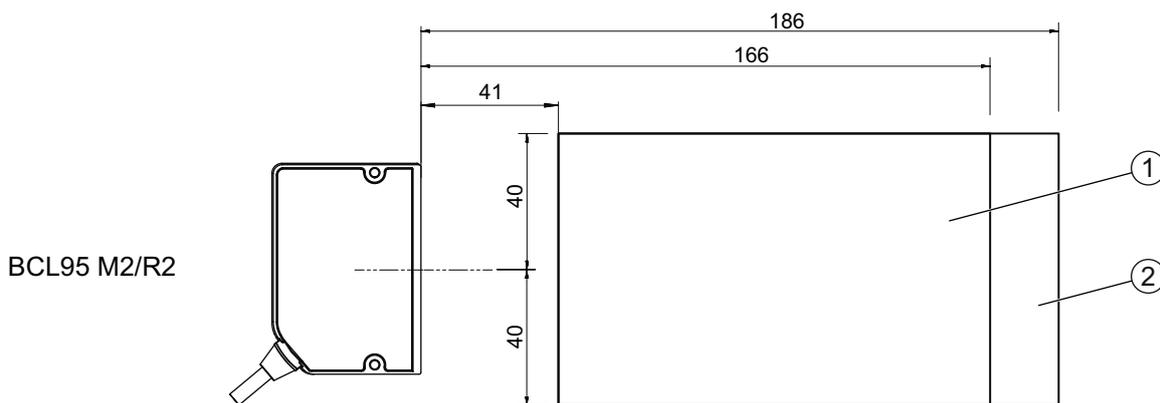
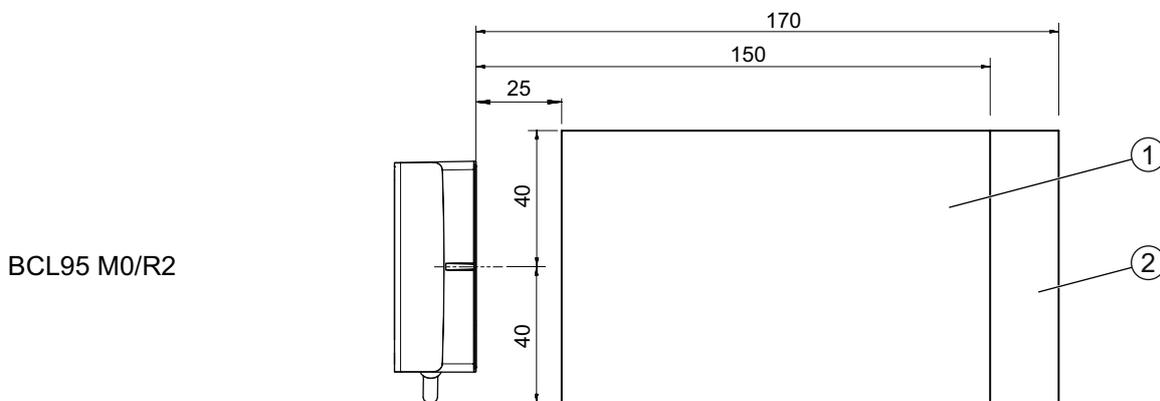
|                      |  |
|----------------------|--|
| Degree of protection | IP 54  |
| Connection type      | Connection cable, 2 m long, 6-wire with open cable end<br>Pigtail with M12 connector, 8-pin                                  |
| Weight               | Approx. 210 g  |
| Dimensions           | see chapter 12.3 "Dimensioned drawings"  |
| Fastening            | 2 M2.5 mounting threads, 4 mm deep, on the side of the device<br>2 M3 mounting threads, 6 mm deep, on the rear of the device |
| Housing              | Diecast zinc   |
| Optics cover         | Glass  |

Tab. 12.6: Environmental data

|                                  |  |
|----------------------------------|--|
| Ambient temperature<br>Operation | +5 °C ... +40 °C   |
| Storage                          | -20 °C ... +60 °C  |
| Air humidity                     | Max. 90% rel. humidity, non-condensing                                   |
| Electromagnetic compatibility    | EN 61326-1:2013-01,<br>FCC 15-CFR 47 Part 15 (09-07-2015) Limits Class B |
| Vibration                        | IEC 60068-2-6, test Fc   |
| Shock                            | IEC 60068-2-27, test Ea  |
| Certifications                   | UL 60950-1, CAN/CSA C22.2 No. 60950-1-07                                 |
| Conformity                       | CE, CDRH, UL   |

12.2 Reading fields

| <b>NOTICE</b>   |   |
|---|---|
|  | <p>Please note that the actual reading fields are also influenced by factors such as labeling material, printing quality, scanning angle, printing contrast etc., and may thus deviate from the reading fields specified here. The origin of the read distance always refers to the front edge of the housing of the beam exit.</p> |



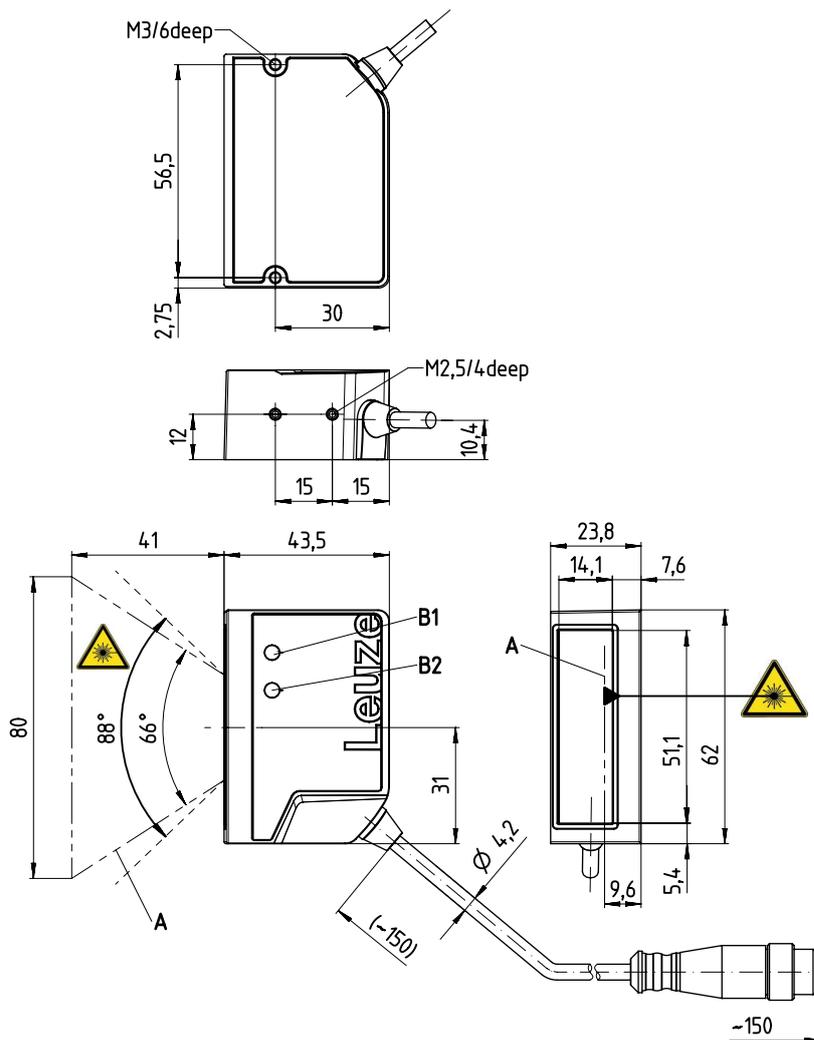
all dimensions in mm

The reading fields are specified for Code128 (four-width code).

- 1 M = 0.165 mm ... 0.2 mm (6,5 mil ... 8 mil)
- 2 M = 0.2 mm ... 0.5 mm (8 mil ... 20 mil)

Fig. 12.1: BCL 95 reading field

12.3 Dimensioned drawings



all dimensions in mm

- A Laser beam
- B1 Indicator diode – decode LED
- B2 Indicator diode – status LED

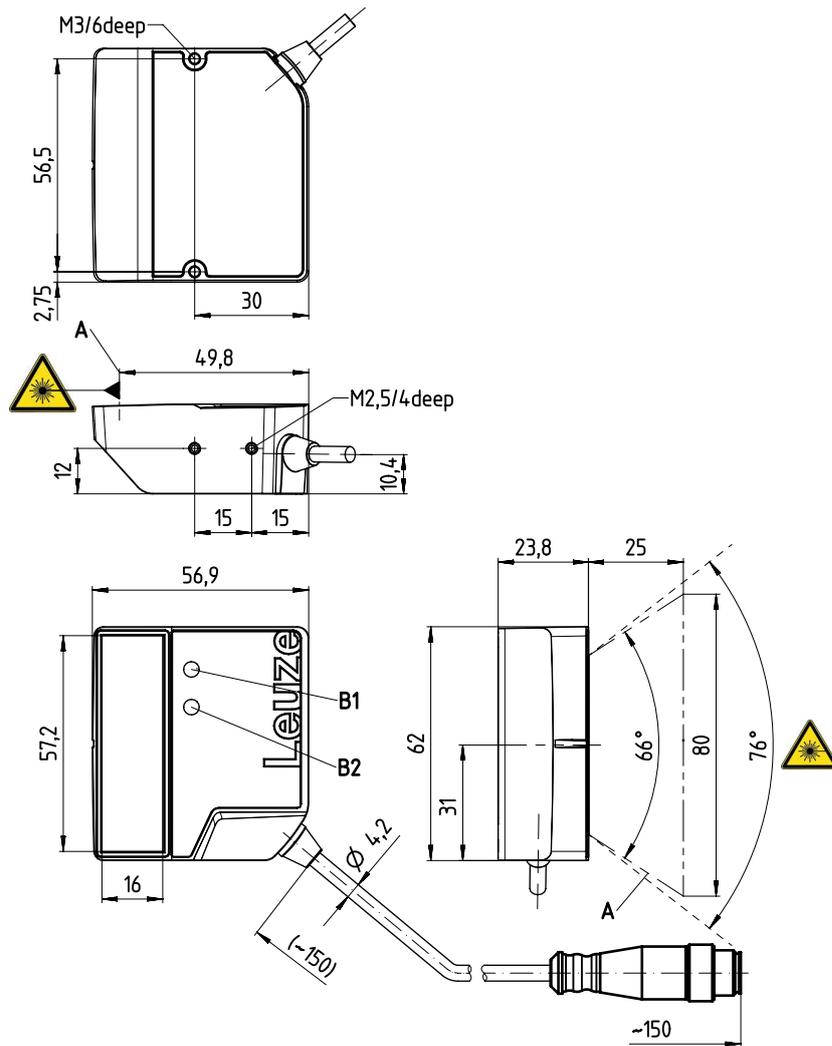
Fig. 12.2: BCL 95 M2/R2 – frontal beam exit

**NOTICE**



**Align device!**

For exact positioning of the laser beam in the application, the device must be aligned.



all dimensions in mm

- A Laser beam
- B1 Indicator diode – decode LED
- B2 Indicator diode – status LED

Fig. 12.3: BCL 95 M0/R2 – lateral beam exit

**NOTICE**



**Align device!**

For exact positioning of the laser beam in the application, the device must be aligned.

## 13 Order guide and accessories

### 13.1 Type overview

Tab. 13.1: Part numbers

| Part no. | Part designation      | Description  |
|----------|-----------------------|--|
| 50138197 | BCL 95 M0R2-150-M12.8 | Single line scanner, RS 232 interface<br>Beam exit: lateral<br>Connection: pigtail with M12 connector, 8-pin |
| 50138198 | BCL 95 M2R2-150-M12.8 | Single line scanner, RS 232 interface<br>Beam exit: frontal<br>Connection: pigtail with M12 connector, 8-pin |
| 50138195 | BCL 95 M0R2           | Single line scanner, RS 232 interface<br>Beam exit: lateral<br>Connection cable, 6 wire, 2 m                 |
| 50138196 | BCL 95 M2R2           | Single line scanner, RS 232 interface<br>Beam exit: frontal<br>Connection cable, 6 wire, 2 m                 |

### 13.2 Accessories

Tab. 13.2: Accessories – connection cables

| Part no. | Part designation   | Description   |
|----------|--------------------|---|
| 50135121 | KD U-M12-8A-P1-020 | Connection 1: connector, M12, axial, female, A-coded, 8-pin<br>Connection 2: open cable end<br>Shielded: no<br>Cable length: 2000 mm<br>Material sheathing: PUR |
| 50135122 | KD U-M12-8A-P1-050 | Connection 1: connector, M12, axial, female, A-coded, 8-pin<br>Connection 2: open cable end<br>Shielded: no<br>Cable length: 5000 mm<br>Material sheathing: PUR |

Tab. 13.3: Accessories - software

|  |   |
|--|---|
| <p><i>Sensor Studio</i> configuration software<br/>Download at <a href="http://www.leuze.com">www.leuze.com</a><br/>(see chapter 6.2.1 "Downloading configuration software")</p> | <p><i>Sensor Studio</i> designed according to the FDT/DTM concept. Contains: communication DTM and device DTM</p> |
|--|---|

#### NOTICE



On request, Leuze electronic can make available the *BCL Configuration Tool* editor program.

**14 EC Declaration of Conformity**

The bar code readers of the BCL 95 series have been developed and manufactured in accordance with the applicable European standards and directives.



## 15 Appendix

### 15.1 Bar code samples



Module 0.3

Fig. 15.1: Code type 01: Interleaved 2 of 5



Module 0.3

Fig. 15.2: Code type 02: Code 39



Module 0.3

Fig. 15.3: Code type 11: Codabar



Module 0.3

Fig. 15.4: Code 128



Module 0.3

Fig. 15.5: Code type 08: EAN 128



SC 2

Fig. 15.6: Code type 06: UPC-A



SC 3

Fig. 15.7: Code type 07: EAN 8